

# Well-balanced Finite Volume schemes for scalar discontinuous-flux conservation laws

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based upon joint works with

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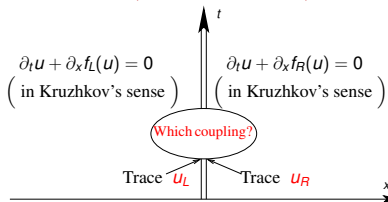
- Example: the particle-in-Burgers problem
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# Discontinuous-flux setting and state-of-the-art

## Prototype discontinuous flux problem

Prototype scalar conservation law with discontinuous flux (DFSCL):

$$\partial_t u + \partial_x (f_L(u) \mathbf{1}_{x < 0} + f_R(u) \mathbf{1}_{x > 0}) = 0$$



- Which notion(s) of solution ?  
Answer: depends on the model !  
[Adimurthi, Mishra, V. Gowda'05]
- Uniqueness ?
- Existence (passage to the limit) ?
- Numerical approximation ?

In many examples, DFSCL can be seen as a *singular limit* problem.

What information is inherited at the limit ?

How can solutions of DFSCL be characterized *intrinsically* ?

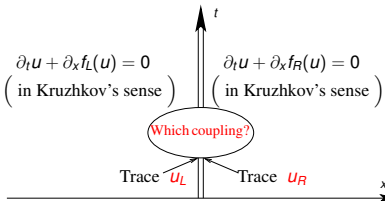
Answer: the essential information is contained in stationary solutions  
 $\Rightarrow$  importance of well-balanced schemes for FV approximation of DFSCL

**NB:** away from the interface, we will always use  
 the Kruzhkov notion of entropy solution  
 + Finite Volume approximations with two-point *monotone fluxes*.

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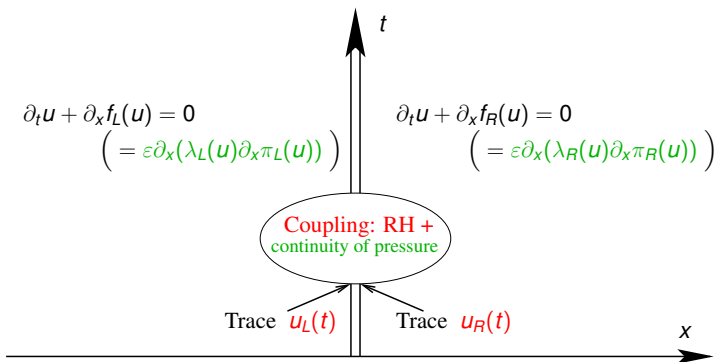
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Example: Buckley-Leverett eqn. as vanishing capillarity limit

## Example: Buckley-Leverett equation as vanishing capillarity limit

Consider Buckley-Leverett equation in 1D medium  
constituted of two rocks with distinct physical properties

$$\partial_t u + \partial_x (f_L(u) \mathbf{I}_{x < 0} + f_R(u) \mathbf{I}_{x > 0}) = 0$$

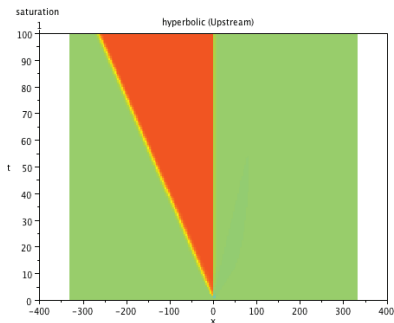


**NB:** the nonlinearities  $\pi_{L,R}$  (capillary pressures) and  $\lambda_{L,R}$  enter the model for  $\varepsilon > 0$  but don't enter the limit model  
 $\Rightarrow$  should Interface Coupling keep memory of  $\pi_{L,R}$  and  $\lambda_{L,R}$  ?

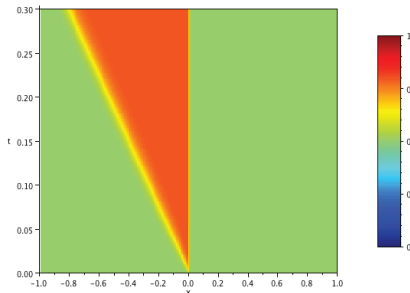
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## Numerical examples: practical interest of the limit model

Constant initial condition, some choice of  $f_{L,R}$  and  $\pi_{L,R}$



(a) Numerical solution  $u_h$   
of the limit (hyperbolic) problem



(b) Numerical solution  $u_h^\varepsilon$   
of the parabolic problem ( $\varepsilon = 10^{-3}$ )

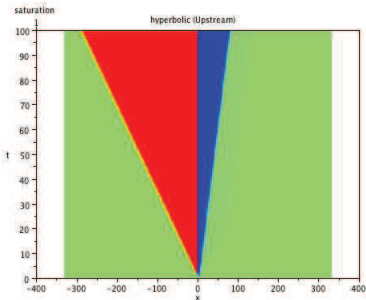
**Speed-up hyperbolic versus parabolic : factor 800.**

The limit problem is approximated according to the recipes of  
[A.,Cancès '12 and '14], [A.,Cancès'15]

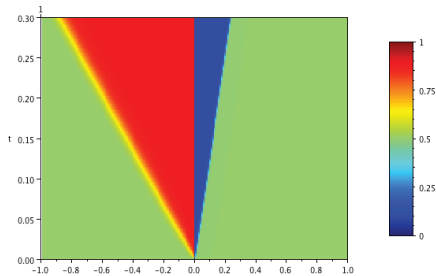
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## Numerical examples: the limit model is under-determined

Same initial condition, same choice of  $f_{L,R}$ , but  $\pi_{L,R}$  are changed



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**Conclusion:** the limit DFSCl model should indeed depend on  $\pi_{L,R}(\cdot)$

**Goal :** understand and formalize this dependence

in terms of ICC (Interface Coupling Conditions)

and find numerical strategies for approximating DFSCl + ICC



## Focus on steady states for DFSCCL.

[A.,Karlsen,Risebro'11] : understanding the model DFSCCL equation

$$\partial_t u + \partial_x (f_L(u) \mathbf{1}_{x < 0} + f_R(u) \mathbf{1}_{x > 0}) = 0$$

One can characterize the Interface Coupling by describing the set  $\mathcal{G}$  of all couples  $(u_L, u_R) \in \mathbb{R}^2$  that can appear as possible traces on the (left,right) at  $x = 0$ .

Scaling invariance  $\Rightarrow$

$(u_L, u_R) \in \mathcal{G}$  iff  $k(x) = u_L \mathbf{1}_{x < 0} + u_R \mathbf{1}_{x > 0}$  is an (admissible) solution

Thus, we are speaking about the piecewise constant steady states !

Algebraic property of  $\mathcal{G}$  (called  $L^1 D$  germ):

- (conservative coupling)  $\forall (u_L, u_R) \in \mathcal{G} \quad f_L(u_L) = f_R(u_R)$
- ( $L^1$ -dissipative coupling)  $\forall (u_L, u_R), (\hat{u}_L, \hat{u}_R) \in \mathcal{G}$

$$\text{sign}(u_L - \hat{u}_L)(f_L(u_L) - f_L(\hat{u}_L)) - \text{sign}(u_R - \hat{u}_R)(f_R(u_R) - f_R(\hat{u}_R)) \geq 0$$

- $\mathcal{G}$  is called maximal if it has no extension satisfying these constraints
- $\mathcal{G}$  is called definite if it has a unique maximal extension, called  $\mathcal{G}^*$

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## Notion of solution and well-posedness.

### Definition

Assume  $\mathcal{G}$  is a definite  $L^1 D$  germ.

An  $L^\infty$  function  $u$  is a  $\mathcal{G}$ -entropy solution

if it is a local Kruzhkov solution away from  $\{x = 0\}$

and moreover, for a.e.  $t > 0$ , the couple  $(u(t, 0^-), u(t, 0^+)) \in \mathcal{G}^*$ .

Equivalently, the trace condition can be replaced by

adapted entropy inequalities:

$\forall (u_L, u_R) \in \mathcal{G}$ , setting  $k(x) = u_L \mathbf{1}_{x < 0} + u_R \mathbf{1}_{x > 0}$ ,

$$\partial_t |u - k(x)| + \partial_x (\text{sign}(u - k(x))(f(x, u) - f(x, k(x)))) \leq 0 \text{ in } \mathcal{D}'.$$

### Theorem

For every definite  $L^1 D$  germ,

Cauchy problem is well posed in the setting of  $\mathcal{G}$ -entropy solutions.

The Godunov scheme (including the  $\mathcal{G}$ -Godunov solver at  $\{x = 0\}$ ) converges to this solution.

## Convergence of approximations.

Numerical (Godunov) or suitable viscosity approximations are proved to converge using the following arguments:

- The approximation method fulfills the (approximate) localized contraction inequality:

$$\partial_t |u^h - \hat{u}^h| + \partial_x (\text{sign}(u - \hat{u})(f(x, u^h) - f(x, \hat{u}^h))) \leq \text{Rem}^h \text{ in } \mathcal{D}'$$

- the steady states  $k(x) = u_L \mathbf{1}_{x < 0} + u_R \mathbf{1}_{x > 0}$ ,  $(u_L, u_R) \in \mathcal{G}$  are limits of the approximation method
- the inequality is used for  $\hat{u}(t, x) = k(x)$ ;  
at the limit  $h \rightarrow 0$ , one gets adapted entropy inequalities for  $u$ .

Thus, crucial features for a numerical method are:

- Discrete contraction
- Preservation (exact, or at the limit  $h \rightarrow 0$ ) of the steady states  $k(x)$  defined from  $\mathcal{G}$ .

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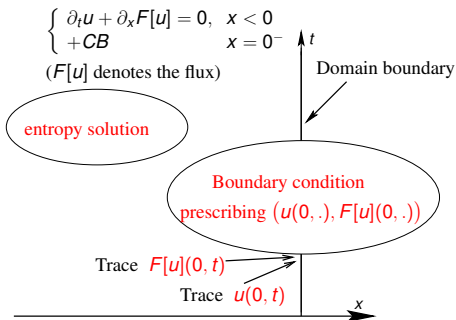
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# Boundary Conditions and Interface Coupling Conditions

## General dissipative boundary conditions



Local “Kato inequality” obtained from the local entropy formulation:

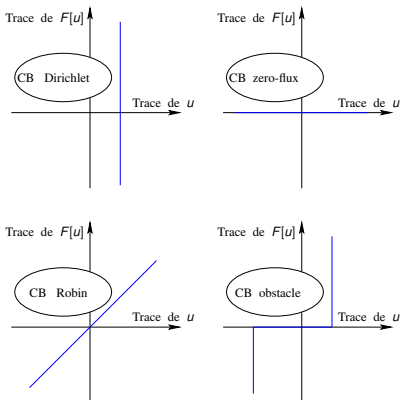
$$\int_{\Omega} |u - \hat{u}|(T, x) - \int_{\Omega} |u_0 - \hat{u}_0| + \int_0^T \int_{\Omega} \text{sign}(u - \hat{u})(F[u] - F[\hat{u}]) \cdot \nabla \xi \leq 0 \quad \forall \xi \in \mathcal{D}(\Omega)^+$$

Exploit KI near the boundary: test fct.  $\xi_n \rightarrow \mathbf{1}_{\Omega}$  with  $\nabla \xi_n \rightarrow -\delta|_{\partial\Omega} \mathbf{n} \Rightarrow$

$$\int_{\Omega} |u - \hat{u}|(T, x) - \int_{\Omega} |u_0 - \hat{u}_0| \leq - \int_0^T \gamma_{ad hoc} \left\{ \text{sign}(u - \hat{u})(F[u] - F[\hat{u}]) \cdot \mathbf{n} \right\}(t) dt$$



## Classical boundary conditions



In these cases,  $(u, F[u]) \in \beta$  for some maximal monotone graph  $\beta$ .

**General framework:** BC set up in terms of a maximal monotone dependence between the solution  $u$  and flux  $F[u]$  at the boundary

Boundary dissipation:

$$\text{sign}(u - \hat{u})(F[u] - F[\hat{u}]) = \text{sign}(u - \hat{u})(\beta(u) - \beta(\hat{u})) \geq 0 !$$

## Dissipative BC for hyperbolic conservation law. Projection.

**Hyperbolic** equation  $u_t + f(u)_x = 0$  + **formal BC**  $(u, F[u]) \in \beta$  :

- **Uniqueness is obvious** for the formal problem
- Formal problem ill-posed (**in general, existence fails**)
- Problem with  $\dots = \varepsilon \partial_{xx}^2 u$  is well posed.  
The limit is a local entropy solution verifying **effective BC**  
 $(u, F[u]) \in \tilde{\beta}$  where  $\tilde{\beta}$  is a **projection of  $\beta$** .  
Problem with effective BC (i.e.,  $\tilde{\beta}$  in BC) is well posed
- One can easily grasp the projection procedure by picturing  $\tilde{\beta}$ .  
One observes :  $\tilde{\beta}$  is the **maximal monotone subgraph of  $f$**   
**which is the closest to  $\beta$  !**

**Example:** BLN condition [Bardos,LeRoux,Nédélec'79]  
can be reformulated this way [Dubois,LeFloch'88]

- One can describe  $\tilde{\beta}$  in terms of the “Godunov numerical flux”:

$$\tilde{\beta} = \left\{ (u, \mathcal{F}) \mid \mathcal{F} = f(u) = \text{God}[u, \tilde{u}] \in \beta(\tilde{u}) \right\}$$

Détails : [Thesis Sbihi'06],[A.,Sbihi'15]

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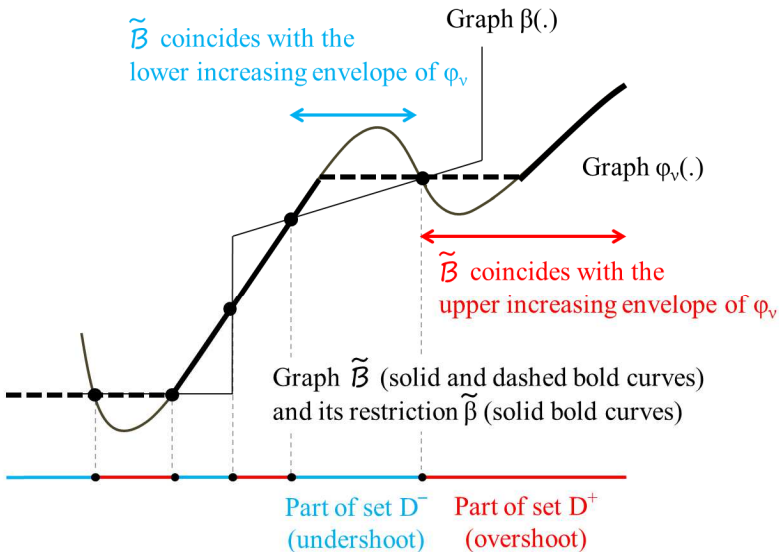
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Dissipative BC in the hyperbolic setting

# Example for a general BC: the projection procedure



## Dissipative Interface Coupling Conditions (ICC)

**Analogy :** One assimilates inner interface to a “double boundary”

Interface Coupling Conditions (ICC) can be expressed, as in the BC case, by

$$\left( (u_L, u_R), (F_L, F_R) \right) \in \mathcal{H} \subset \mathbb{R}^2 \times \mathbb{R}^2$$

where  $u_{L,R}$  are the traces (left and right) of the solution  $u$  and  $F_{L,R}$  are the normal traces (left and right) of the flux  $F[u]$ .

The ICC is conservative if  $\forall ((u_L, u_R), (F_L, F_R)) \in \mathcal{H}, F_L + F_R = 0$ .

The  $L^1$ -dissipativity of the CCI is equivalent to the monotonicity of  $\mathcal{H}$  in the sense:  $\mathcal{H}$  is called 1-monotone if

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**Principle:** The situation of ICC is fully analogous to that of BC!

NB : Idea comes from [Imbert, Monneau'14] (HJeqns on networks).

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## The projection procedure for ICC. The return of the “germs”.

In particular: **a formally prescribed ICC is projected:  $\mathcal{H} \rightarrow \tilde{\mathcal{H}}$ ,**

$$\tilde{\mathcal{H}} := \left\{ (u_L, u_R; F_L, F_R) \in \mathbb{R}^2 \times \mathbb{R}^2 \mid \exists (\bar{u}_L, \bar{u}_R; F_L, F_R) \in \mathcal{H} \right. \\ \left. F_L = f_L(u_L) = \text{God}_L[u_L, \bar{u}_L], -F_R = f_R(u_R) = \text{God}_R[\bar{u}_R, u_R] \right\}$$

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As for the BC case,  **$\tilde{\mathcal{H}}$  should be seen as the effective ICC [A.,'15]**.

One finds:

- $\mathcal{H}$  is conservative  $\Rightarrow \tilde{\mathcal{H}}$  is also conservative
- $\mathcal{H}$  is  $L^1$ -dissipative  $\Rightarrow \tilde{\mathcal{H}}$  is also  $L^1$ -dissipative ;  
moreover, **the domain of  $\tilde{\mathcal{H}}$  is an  $L^1 D$  germ**

Example of ICC: “conservative inflow-outflow Robin conditions”

Given monotone continuous functions  $A_{L,R} : \mathbb{R} \rightarrow \mathbb{R}$  (e.g.,

$$A_{L,R}(u) = \frac{\lambda_{L,R}}{1-\lambda_{L,R}} u \text{ for some parameters } \lambda_{L,R} \in (0, 1)),$$

$$\mathcal{H} := \left\{ (u_L, u_R; F, -F) \in \mathbb{R}^2 \times \mathbb{R}^2 \mid u_{L,R} \in \mathbb{R}, F = A_L(u_L) - A_R(u_R) \right\}.$$



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# Examples of ICC, applications and well-balanced FV schemes

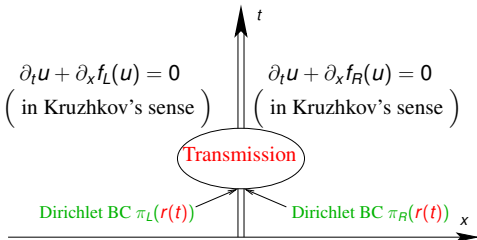
Main Example: transmission maps (the conservative case)

## Conservative ICC defined by transmission maps

The example of vanishing capillarity suggests the following ICC:

$$(u_L, u_R; F_L, F_R) \in \mathcal{H}(\pi_{L,R}) \Leftrightarrow F_L + F_R = 0, \quad \pi_L(u_L) = \pi_R(u_R).$$

The interface coupling by **transmission map**  $r \mapsto (\pi_L(r), \pi_R(r))$  :



Transmission: **two Dirichlet pbs (in the BLN sense) coupled by**

- **the Dirichlet BC**  $\pi_{L,R}(r(t))$  ( $r(t)$  being **additional unknown**)
- **the conservativity relation**

$$\text{God}_L[u(t, 0^-), \pi(r(t))] = \text{God}_R[\pi_R(r(t)), u(t, 0^+)].$$

## Well-balanced FV schemes for transmission-map ICC

[A., Cancès'12,'14,'15] FV schemes for the transmission-map ICC:  
the two-point interface flux  $F_{int}(\cdot, \cdot)$  is defined by

$$F_{int}(u_-, u_+) = \text{God}_L[u_-, \pi_L(r)] = \text{God}_R[\pi_R(r), u_+]$$

where  $r \in \mathbb{R}$  solves  $\text{God}_R[\pi_R(r), u_+] - \text{God}_L[u_-, \pi_L(r)] = 0$ .

Properties of the scheme:

- One implicit unknown per interface point;  
the equation to be solved is a scalar monotone equation  
(e.g.,  $\Rightarrow$  *regula falsi* method)
- The numerical flux  $F_{int}$  is monotone and Lipschitz
- The scheme is well balanced  
(it preserves the “germ” steady states)  $\Rightarrow$  the scheme converges

NB: we use Godunov fluxes of  $f_{L,R}$ ...

but not the Riemann solver at the interface !

- Moreover,  $\text{God}_{L,R}$  can be replaced by any classical num. flux !  
The scheme is “asymptotically well-balanced” and convergent.

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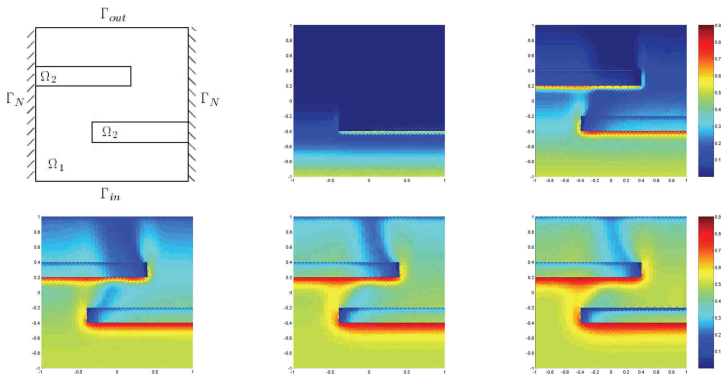
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## Numerical example in 2D (IMPES scheme)

Combination with 2D IMplicit Pressure - Explicit Saturation Scheme:



The two-rock domain is initially saturated in water. Two barriers (rock  $\Omega_2$ ) have a higher entry pressure. The vertical boundaries are impermeable. Bottom+top : a constant rate of a total flux is prescribed. Saturation  $s = 0.5$  imposed on  $\Gamma_{in}$ . Details: [\[Andreianov,Brenner,Cancès'13\]](#) .

Example: flux limitation in road and pedestrian traffic

## Traffic models with point constraint

[Colombo,Goatin'07] : LWR model  $\partial_t u + \partial_x f(u) = 0$   
with point constraint  $f(u)|_{x=0} \leq q(t)$ .

Models red lights, pay tolls, construction sites,...

The underlying ICC is:

$$\begin{aligned} \mathcal{H}(t) &= \{(k, k, F, -F) \mid k \text{ arbitrary, } F \leq q(t)\} \text{ (the Kruzhkov part)} \\ &\cup \{(k_L, k_R, F, -F) \mid k_L > k_R, F = q(t)\} \text{ (non-Kruzhkov jumps)} \end{aligned}$$

Given any monotone consistent Lipschitz numerical flux  $F(\cdot, \cdot)$ ,  
the interface numerical flux for the constrained model is defined by:

$$F_{int}(t; u_-, u_+) = \min\{F(u_-, u_+), q(t)\}.$$

- the flux  $F_{int}$  is monotone and Lipschitz
- the scheme is asymptotically well balanced  $\Rightarrow$  it converges  
[A.,Goatin,Seguin'10]
- if  $F$  is the Godunov flux of  $f$ , then the resulting scheme is the Godunov scheme also at the interface [Cancès,Seguin'12]

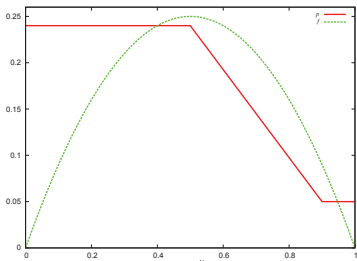
Example: flux limitation in road and pedestrian traffic

## Application to pedestrian traffic modeling

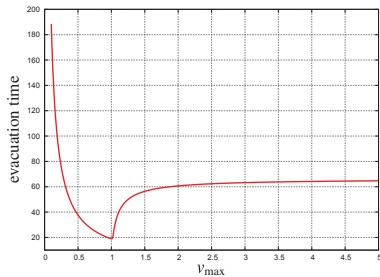
Let us make depend  $q(t)$  on the solution  $u(t, \cdot)$ . We propose new pedestrian (“panic at the exit”) models [A., Donadello, Rosini’14] :

$$f(u)|_{t=0} \leq q(t) = P\left(\int_{\mathbb{R}_-} w(x)u(t, x) dx\right), \quad w \geq 0, \quad \int_{\mathbb{R}_-} w(x) dx = 1.$$

$P(\cdot)$  non-increasing  $\Rightarrow$  “Faster is Slower” and Braess paradoxes!  
Simulations of [A., Donadello, Razafison, Rosini prep.’15] .



(e) Flux  $f(\cdot)$  of the LWR model and the “exit-clugging map”  $P(\cdot)$



(f) Dependence of evacuation time at the exit on the speed  $v_{max}$  at the entrance



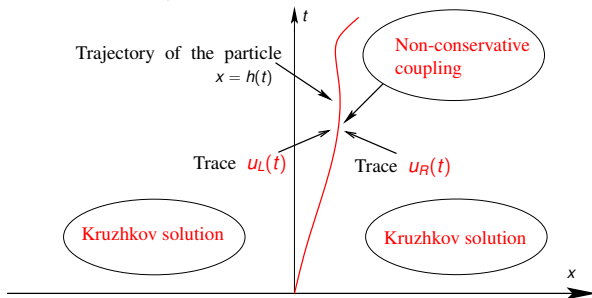
# Conservation Laws with point source

Example: the particle-in-Burgers problem

## Coupling of Burgers fluid and a point Particule via a drag force

Model proposed by [Lagoutière,Seguin,Takahashi'07] :

$$\begin{cases} \partial_t u + \partial_x \frac{u^2}{2} = -(u - h'(t))\delta_0(x - h(t)), \\ h''(t) = u(t, h(t)) - h'(t) \end{cases}$$



- Splitting arguments or fixed point arguments  $\Rightarrow$  decoupling
- Change of variable  $\Rightarrow$  reduction to the case  $h' \equiv 0$ .

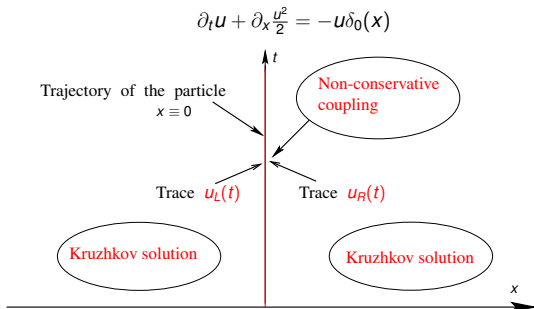
Theory: [A.,Lagoutière,Seguin,Takahashi'14] ;

numerics: [ALST'10],[Aguillon,Lagoutière,Seguin'14],[Towers'15]

Example: the particle-in-Burgers problem

## Burgers equation perturbed by a singular source term

Simplified version of the previous problem:

NB: Formal dissipativity  $\Rightarrow$  the “germ”/ICC formalism can be used.

[Lagoutière, Seguin, Takahashi’07] : the rigorous interpretation of the non-conservative product  $u(t, x)\delta_0(x)$  reduces to finding steady states via  $\delta_\varepsilon, \varepsilon \rightarrow 0$ . **Particular steady states:**

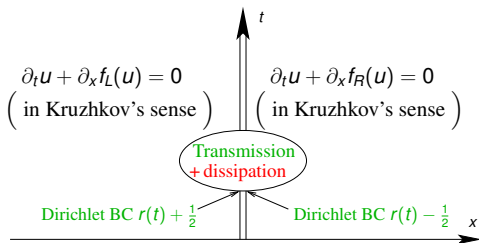
$$k(x) = u_L \mathbf{1}_{x < 0} + u_R \mathbf{1}_{x > 0}, \quad u_L = r + \frac{1}{2}, \quad u_R = r - \frac{1}{2},$$

moreover, **the corresponding defect of conservation equals  $r$**

## Transmission maps for non-conservative coupling

One can attempt to encode the ICC using:

- the transmission map  $r \mapsto (r + \frac{1}{2}, r - \frac{1}{2})$
- and the dissipation map  $r \rightarrow \psi(r) = r$



Transmission: two Dirichlet pbs (in the BLN sense) coupled by

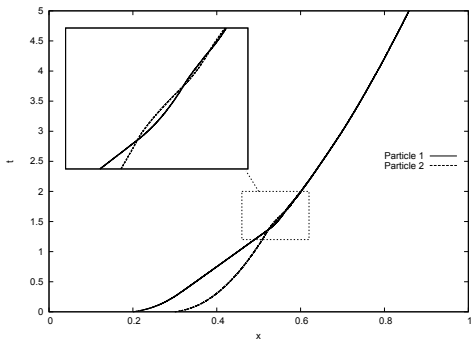
- the Dirichlet BC  $r(t) \pm \frac{1}{2}$  ( $r(t)$ : the additional unknown)
- the dissipativity relation

$$\text{God}_R[r(t) + \frac{1}{2}, u(t, 0^+)] - \text{God}_L[u(t, 0^-), r(t) - \frac{1}{2}] + \psi(r) = 0.$$

Result:  $\psi$  monotone  $\Rightarrow$  same recipes apply for the FV scheme

## Numerics: drafting-kissing-tumbling. Extension to Euler system?

In fact, a simpler (fully explicit) but less robust scheme has already been proposed for Burgers-particle problem. A simulation:



**Figure:** Trajectories of two particles

NB: For Euler-particle pb., extension of this scheme fails [Aguillon'14]  
Preliminary results on the transmission-like scheme are encouraging.

## Conclusions:

- in modeling with DFSCCL, identification of Interface Coupling Conditions is essential
- well-balanced (asymptotically) monotone FV schemes converge
- no general strategy (except for transmission+dissipation ICC)
- successful examples

## Perspectives:

- other examples of ICC that appear in practice ?
- (partial) extension of transmission strategies to some systems ??

GRAZIE !