

Notions of solution for conservation laws with fractional diffusion

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Séminaire du Laboratoire Jacques-Louis Lions
June 27, 2014

Plan of the talk

- 1 Fractional convection-diffusion equations**
- 2 Classical, weak and entropy solutions**
 - Definitions of weak and entropy solutions
 - Some well-posedness and regularity results
 - Ill-posedness: construction of a non-entropy weak solution
- 3 Kinetic formulation for fractional conservation laws**
 - Kinetic formulation, the local case
 - Kinetic formulation, adaptation to the fractional case
 - A glimpse into the proof
- 4 Renormalized formulation for fractional diffusion**
 - Renormalized solutions, the local case
 - Renormalized solutions, adaptation to the fractional case

PROBLEM CONSIDERED

Problem considered

We look at the “fractal conservation laws”

$$\partial_t u + \operatorname{div}_x f(u) + \mathcal{L}_\lambda[u] = 0, \quad \text{in } (0, \infty) \times \mathbb{R}^N, \quad (1)$$

$$u(0, \cdot) = u_0, \quad \text{on } \mathbb{R}^N, \quad (2)$$

\mathcal{L}_λ denotes the **fractional power** $(-\Delta)^{\lambda/2}$ of $-\Delta$.

This is a non-local, pseudodifferential operator of order λ , $0 < \lambda < 2$.

Motivations :

- Gaz detonation (Clavin-Denet-He'01), phenomenological
- “Anomalous diffusion” phenomena :
Lévi processes as a generalization of \mathcal{L}_λ
- A “scalar quasi-geostrophic equation”: $\lambda = 1$
- ...

The two reference (limit) case, deeply studied :

- $\lambda = 2$: the parabolic case, similar to the heat equation
- $\lambda = 0$: the pure hyperbolic case (scalar conservation law)

The behaviour of generic solutions is very different in the two cases.

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What is the fractional laplacian ?

If φ is regular (e.g., for a function φ from the Schwartz class $\mathcal{S}(\mathbb{R})$), $\mathcal{L}_\lambda[\varphi]$ can be defined through the Fourier transform:

$$\mathcal{F}(\mathcal{L}_\lambda[\varphi])(\xi) := |\xi|^\lambda \mathcal{F}(\varphi)(\xi). \quad (3)$$

In absence of regularity, a more general definition is provided by the *Lévi-Khinchine formula*: (case $0 < \lambda < 1$: the integral is convergent)

$$\text{const } \mathcal{L}_\lambda[\varphi](x) := \text{v.p.} \int_{\mathbb{R}} \frac{\varphi(x+z) - \varphi(x)}{|z|^{N+\lambda}} dz. \quad (4)$$

Hint : The kernel $\frac{1}{|z|^{N+\lambda}}$ being singular at the origin, split (4) into regular (“order zero”) and singular (“order λ ”) parts:

$$\begin{aligned} \mathcal{L}_\lambda[\varphi] &= -G_\lambda \left(\int_{\{|z|>r\}} \frac{\varphi(\cdot+z) - \varphi(\cdot)}{|z|^{N+\lambda}} dz + \text{v.p.} \int_{\{|z|<r\}} \frac{\varphi(\cdot+z) - \varphi(\cdot)}{|z|^{N+\lambda}} dz \right) \\ &=: \mathcal{R}_\lambda^r[\varphi] + \mathcal{S}_\lambda^r[\varphi]. \end{aligned}$$

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Heuristics: competition of regularizing and de-regularizing effects

Heuristically, the knowledge of the purely hyperbolic ($\lambda = 0$) and of the parabolic ($\lambda = 2$) cases permits to set up a few conjectures :

- in the case $1 < \lambda < 2$, the fractional diffusion operator $\mathcal{L}[u]$ is the leading term. In particular:
 - smooth data give rise to globally defined smooth solutions
 - non-smooth data undergo an instantaneous regularizing effect
 - there is well-posedness in the framework of weak solutions.
- in the case $0 < \lambda < 1$, the fractional diffusion term $\mathcal{L}[u]$ is dominated by the term $\operatorname{div}_x f(u)$. In particular:
 - one expects that even for very smooth initial data, there is no globally defined in time classical solution
 - the notion of a weak (distributional) solution permits to get existence for rather general data...
 - ...but it may lead to non-uniqueness
 - a "good" notion of solution should be inspired by the kinetic solutions/entropy solutions coming from conservation laws.
- Case $\lambda = 1$. Hmmmm... no *a priori* conjectures !
 For some applications, one needs techniques that allow for a wide range of values of λ , including $\lambda = 1$...

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An overview of the talk

- Highlight the **issues essential for the convection-dominated range $0 < \lambda < 1$** (but that remain relevant for the full range $0 \leq \lambda \leq 2$)
- Discuss **difficulties and advantages of the non-local case**, compared to the local cases ($\lambda = 0$ or $\lambda = 2$):
 - NB** It can be advantageous (technically) to see the classical local case $\lambda = 2$ as $\lambda = 2^-$, i.e., as the limit of the local case (Alibaud, Cifani, Jakobsen'14)
- Point out drawbacks of **classical and weak solutions** ($\lambda < 1$)
- Focus on three relevant notions of solution ($0 < \lambda < 2$):
 - **entropy (Kruzhkov) solutions**, L^∞ setting
 - **kinetic solutions**, L^1 setting
 - **renormalized solutions**, $L^1 + L^\infty$ setting
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CLASSICAL, WEAK AND ENTROPY SOLUTIONS

Notions of solution: weak solutions

Definition (Weak solution)

Let $u_0 \in L^\infty(\mathbb{R}^N)$. A function $u \in L^\infty((0, \infty) \times \mathbb{R}^N)$ is said to be a weak solution to (1),(2) if for all $\varphi \in \mathcal{D}([0, \infty) \times \mathbb{R}^N)$,

$$\int_0^\infty \int_{\mathbb{R}^N} (u \partial_t \varphi + f(u) \cdot \nabla_x \varphi - u \mathcal{L}_\lambda[\varphi]) + \int_{\mathbb{R}^N} u_0 \varphi(0) = 0.$$

Important remark: at least for regular enough u and v there holds the integration-by-parts formula

$$\int \mathcal{L}_\lambda[u]v = \int u \mathcal{L}_\lambda[v] = \text{const} \iint (u(x)-u(y))(v(x)-v(y)) \frac{dx dy}{|x-y|^{N+\lambda}}.$$

Therefore the definition of a weak solution just says

$$\partial_t u + \text{div}_x f(u) + \mathcal{L}_\lambda[u] = 0, \quad u|_{t=0} = u_0 \quad \text{in } \mathcal{D}'.$$

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$$\partial_t \eta(u) + \operatorname{div}_x q(u) + \eta'(u) \mathcal{R}_\lambda^r[u] + \mathcal{S}_\lambda^r[\eta(u)] \leq 0 \quad \text{in } \mathcal{D}'.$$

Here η is an “entropy”, q is the associated “entropy flux”; these notions are **inherited from the Kruzhkov theory of conservation laws**.

The definition of Alibaud is based upon the **fractional Kato inequality**:

$$\forall r > 0 \quad \eta'(u) \mathcal{R}_\lambda^r[u] + \mathcal{S}_\lambda^r[\eta(u)] \leq \eta'(u) \mathcal{L}_\lambda[u].$$

To be compared with the Kato inequality used in the Kruzhkov theory:

$$-\varepsilon \Delta \eta(u) \leq -\varepsilon \Delta \eta(u) + \varepsilon \eta''(u) |\nabla u|^2 = \eta'(u) (-\varepsilon \Delta u).$$

NB smaller is the parameter r , less information is lost.

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WELL-POSEDNESS RESULTS

Well (and ill)-posedness results

- for the case $1/2 < \lambda < 2$, an H^1 solution exists globally and is unique for small H^1 data (Biler-Funaki-Woyczynski'98)
- for $1 < \lambda < 2$, there exists a unique weak solution for L^∞ data, and $u(t, \cdot)$ falls within C^∞ for $t > 0$ (Droniou-Gallouët-Vovelle'02)
- for $0 < \lambda < 2$, there exists a unique entropy solution (Alibaud'07).

For $0 < \lambda < 1$ and the Burgers flux $f(u) = \frac{u^2}{2}$ in dimension one:

- assume the initial datum u_0 presents an initial discontinuity (say, at zero) with $u_0(0-) > u_0(0+)$ and belongs to some class $\mathfrak{C} \implies$ the discontinuity is persistent, at least for small times
- specially selected smooth initial data in $\mathfrak{C} \implies$ the unique entropy solution, which becomes discontinuous (but not instantly)
- small Lipschitz data in the class $\mathfrak{C} \implies$ global Lipschitz solutions

(Alibaud-Droniou-Vovelle'07; the main tool : characteristics)

For the same fractional Burgers equation in the “hyperbolic regime”,

- Non-entropy weak solutions can be constructed
- Consequently, uniqueness of a weak solution may fail

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CONSTRUCTION OF A “WRONG” WEAK SOLUTION

Ideas of the construction

Goal: **construct u a stationary, discontinuous, weak solution to the fractional Burgers equation that violates the entropy condition (Alibaud, A.'10)**

- We try to mimic the simplest “wrong” weak solution of the Burgers conservation law $\partial_t u + \left(\frac{u^2}{2}\right) = 0$. This is the discontinuous stationary solution
$$u(t, x) := \begin{cases} -1 & x < 0 \\ 1 & x > 0 \end{cases}$$
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- We prove that the Oleřnik inequality still holds for entropy solutions of the fractional Burgers equation
- We work in the space of odd in x functions discontinuous at zero. Ensuring $u(0+) = -u(0-) > 0$, we violate Oleřnik condition.
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$$\eta(x; u, k) = (u - k)^+ \mathbb{1}_{\{x > 0\}} + (u - k)^- \mathbb{1}_{\{x < 0\}}.$$

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Goal: **construct u a stationary, discontinuous, weak solution to the fractional Burgers equation that violates the entropy condition (Alibaud, A.'10)**

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- Work on the **space of odd functions** $H_{odd}^1(\mathbb{R}_*)$ with jump at $x = 0$.
- Construct solutions in the space H_{odd}^1 of the regularized stationary problem

$$\varepsilon(u - \Delta u) + \left(\frac{u^2}{2}\right)_x + \mathcal{L}[u] = 0, \quad u(0\pm) = \pm 1.$$

(they are $\mathcal{D}'(\mathbb{R}_*)$ solutions; in $\mathcal{D}'(\mathbb{R})$, singular term $-2\varepsilon(\delta_0)_x$ appears!)
 Technique : mainly the Schauder fixed-point theorem.

- Pass to the limit, as $\varepsilon \downarrow 0$. The things to be cared of:
 - Compactness (in $H^{\lambda/2}(\mathbb{R}^\pm)$ -weak and for the a.e. convergence): this comes from the uniform in ε estimate for $H^{\lambda/2}(\mathbb{R}^\pm)$ energy
 - Passage to the limit in the weak formulation: straightforward
 - **Guarantee that the discontinuity of u^ε at $x = 0$ persists at the limit**

The last item is challenging. We have **two proofs** .

- a **first one** , with an explicit construction of barriers and **adapted entropies** are used to get “odd-functions” comparison principle.
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KINETIC SOLUTIONS

The pure hyperbolic case

Given a function $u(t, x)$, one introduces the auxiliary quantity

$$\chi(t, x; \xi) = \chi(\xi, u(t, x)) = \begin{cases} 1, & 0 < \xi < u \\ -1, & u < \xi < 0 \\ 0, & \text{otherwise} \end{cases}$$

NB for all Lipschitz $S(\cdot)$ there holds $S(u) = \int_{\mathbb{R}} S'(\xi) \chi(\xi, u) d\xi$.

Represent the nonlinearities from entropy inequalities in this way ;

cancel $S'(u) \Rightarrow$ kinetic formulation for scalar conservation law

$u_t + \operatorname{div} f(u) = 0$:

$$\partial_t \chi(\xi, u) + f'(\xi) \cdot \nabla_x \chi(\xi, u) = \partial_\xi m$$

where $m = m(t, x; \xi)$ is some finite nonnegative measure

responsible for the dissipation of entropy.

Outcome: Full well-posedness theory for $u_t + \operatorname{div} f(u) = 0$, L^1 data.

In $L^1 \cap L^\infty$: kinetic solutions equivalent to Kruzhkov entropy solutions

Proofs: arguments different from Kruzhkov (no variables' doubling).

Lions, Perthame, Tadmor'94; book Perthame'02.

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The degenerate parabolic case

Extension to **local degenerate convection-diffusion equation** :

$$u_t + \operatorname{div} f(u) - \Delta A(u) = 0$$

(and even to anisotropic diffusion case: **Chen, Perthame'03**).

The kinetic formulation takes the form

$$\partial_t \chi(\xi, u) + f'(\xi) \cdot \nabla_x \chi(\xi, u) - A'(\xi) \Delta [\chi(\xi, u)] = \partial_\xi (m+n)$$

where m, n are finite nonnegative measures. Moreover,
the dissipation measure n of the local diffusion operator is given by

$$n(t, x; \xi) := \delta_0(u(t, x) - \xi) A'(\xi) |\nabla u(t, x)|^2.$$

NB It is essential that n is prescribed by an explicit formula
 (while m need not be precisely determined)

Outcome: Full well-posedness for $u_t + \operatorname{div} f(u) - \Delta A(u) = 0$, L^1 data.
 Connection to renormalized solutions in isotropic or anisotropic case
 (e.g. **Ouédraogo, Maliki'09**)

Fractional kinetic dissipation measure

The definition is almost contained in **Karlsen, Ulusoy'11**:
 in this paper, the dissipation measure for fractional diffusion was
 written for smooth entropies (and with $\mathcal{R}_\lambda^f + \mathcal{S}_\lambda^f$ splitting...) as

$$\int_{\mathbb{R}^N} S'(u(t, x)) (u(t, x + z) - u(t, x)) \frac{\text{const}}{|z|^{N+2\lambda}} dz.$$

Our observation stems from the elementary Taylor's identity:

$$\forall a, b \quad S'(a)(b - a) = S(b) - S(a) - \int_{\mathbb{R}} S''(\xi) |b - \xi| \mathbb{1}_{\text{conv}\{a, b\}}(\xi) d\xi.$$

Using singular (Kruzhkov) entropies ($S''(\xi) = 2\delta_0(\xi - k)$), we guess
 the dissipation measure suitable for the fractional Laplacian:

$$n_\lambda(t, x, \xi) := \int_{\mathbb{R}^N} |u(t, x + z) - \xi| \mathbb{1}_{\text{conv}\{u(t, x), u(t, x+z)\}}(\xi) \frac{\text{const}}{|z|^{N+2\lambda}} dz. \quad (5)$$

The kinetic formulation with fractional laplacian takes the form

$$\partial_t \chi(\xi, u) + f'(\xi) \cdot \nabla_x \chi(\xi, u) + \mathcal{L}_\lambda[\chi(\xi, u)] = \partial_\xi (m + n_\lambda)$$

where m, n_λ are finite nonnegative measures, with n_λ from (5).

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Proof by following Chen-Perthame '03

NB Dissipation measure n_λ is less singular than in the local case.

Proof: main issue is uniqueness + L^1 contraction.

As usual, the proof is in two “steps”:

formal proof based on the “algebra of $\{-1, 0, 1\}$ -valued functions”:

$$|\chi(\xi, u) - \chi(\xi, v)| = |\chi(\xi, u) - \chi(\xi, v)|^2 = \chi(\xi, u) + \chi(\xi, v) - 2\chi(\xi, u)\chi(\xi, v),$$

rigorous one with convolution regularization of the formal calculation.

The goal is to get to inequality $\partial_t |\chi(\xi, u) - \chi(\xi, v)| \leq 0$ in $\mathcal{D}'_{(t,x;\xi)}$;

integrating in $\xi \in \mathbb{R}$ yields

$$\partial_t \|u - v\|_{L^1(\mathbb{R}^N)} = \int \partial_t |\chi(\xi, u) - \chi(\xi, v)| d\xi \leq 0 \text{ in } \mathcal{D}'_{(t,x)},$$

and L^1 contraction is justified.

Existence: entropy solutions for $L^1 \cap L^\infty$ data are kinetic solutions;
extension to L^1 data by density as soon as L^1 -contraction is justified.

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Use of the representation formula for n_λ

The result follows from the tedious case-by-case observation :

Lemma

There holds

$$\forall a, b, c, d \in \mathbb{R} \quad F(a, b, c, d) \leq G(a, b, c, d), \quad (6)$$

$$F(a, b, c, d) := \text{sign}(a - b) \text{sign}(c - d) \int_{\mathbb{R}} \mathbb{1}_{\text{conv}\{a, b\}}(\xi) \mathbb{1}_{\text{conv}\{c, d\}}(\xi) d\xi$$

$$G(a, b, c, d) := \int_{\mathbb{R}} \left(|b - \xi| \delta(\xi - c) \mathbb{1}_{\text{conv}\{a, b\}}(\xi) \right. \\ \left. + |d - \xi| \delta(\xi - a) \mathbb{1}_{\text{conv}\{c, d\}}(\xi) \right) d\xi.$$

Definition (5) of dissipation measure n_λ + (formal) calculations say:

$$\text{inequality (6)} \Leftrightarrow \partial_t |\chi(\xi, u) - \chi(\xi, v)| \leq 0.$$

With a mollification step, rigorous proof is achieved.

NB No need to split $\mathcal{L}_\lambda = \mathcal{R}_\lambda^\zeta + \mathcal{S}_\lambda^\zeta$!

Paper in preparation: Alibaud, A., Ouédraogo'14+ ϵ .

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RENORMALIZED SOLUTIONS

Elliptic problems beyond the variational setting. “Closure solutions”.

Consider for instance the elliptic problem

$$u - \Delta u = f \text{ in } \Omega, \quad u = 0 \text{ on } \partial\Omega;$$

the classical setting is the variational one: $u \in H_0^1(\Omega)$, with $f \in H^{-1}(\Omega)$.

But one also has the property $\|u - \hat{u}\|_{L^1(\Omega)} \leq \|f - \hat{f}\|_{L^1(\Omega)}$

for solutions u, \hat{u} corresponding to data $f, \hat{f} \in L^1 \cap H^{-1}$.

Since every function $f \in L^1$ can be approximated in $\|\cdot\|_{L^1}$ by $L^1 \cap H^{-1}$ functions f_n , then solutions u_n exist, and $(u_n)_n$ is a Cauchy sequence.

From the abstract point of view, one has the solution operator

$L^1 \cap H^{-1} \rightarrow L^1 \cap H_0^1$ and its closure: $L^1 \rightarrow L^1$ (we get “closure solutions”).

NB: the nonlinear semigroup theory then yields “mild solutions” of $u_t = \Delta u$.

“Closure” and “mild” solutions may fall out of the energy space !

Then one faces the following question:

in which sense “closure solutions” satisfy the original equation ?

NB: kinetic solutions provide a characterization of “closure solutions”...

renormalized solutions provide another, “more nonlinear” characterization.

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in which sense “closure solutions” satisfy the original equation ?

NB: kinetic solutions provide a characterization of “closure solutions”...

renormalized solutions provide another, “more nonlinear” characterization.

Elliptic problems beyond the variational setting. “Closure solutions”.

Consider for instance the elliptic problem

$$u - \Delta u = f \text{ in } \Omega, \quad u = 0 \text{ on } \partial\Omega;$$

the classical setting is the variational one: $u \in H_0^1(\Omega)$, with $f \in H^{-1}(\Omega)$.

But one also has **the property** $\|u - \hat{u}\|_{L^1(\Omega)} \leq \|f - \hat{f}\|_{L^1(\Omega)}$

for solutions u, \hat{u} corresponding to data $f, \hat{f} \in L^1 \cap H^{-1}$.

Since every function $f \in L^1$ can be approximated in $\|\cdot\|_{L^1}$ by $L^1 \cap H^{-1}$ functions f_n , then solutions u_n exist, and $(u_n)_n$ is a Cauchy sequence.

From the abstract point of view, one has **the solution operator** $L^1 \cap H^{-1} \rightarrow L^1 \cap H_0^1$ and its closure: $L^1 \rightarrow L^1$ (we get “closure solutions”).

NB: the nonlinear semigroup theory then yields “mild solutions” of $u_t = \Delta u$.
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Truncations. Integrability constraints. Renormalized solutions.

Consider the functions $T_k(\cdot)$ and $\varphi_k(\cdot)$ defined, for $k > 0$, by

$$T_k : r \mapsto \text{sign } r \min\{k, |r|\} \quad \text{and} \quad \varphi_k : r \mapsto T_k(r+1) - T_k(r);$$

$T_k(\cdot)$ is the truncation function at level $k > 0$.

- If we formally take $T_k(u)$ and $\varphi_k(u)$ for the test functions in the equation $u - \Delta u = f$, we find estimates “for finite u ”, “for infinite u ”

$$\|T_k(u)\|_{H_0^1}^2 = \int_{\{|u| < k\}} |\nabla u|^2 \leq k \int |f|, \quad \int_{\{k < |u| < k+1\}} |\nabla u|^2 \leq \int_{\{|u| > k\}} |f| \rightarrow_{k \rightarrow \infty} 0.$$

- multiplying by $H(u)\phi$ with compactly supported H we get

$$\int (u - f)H(u)\phi + H(u) \nabla u \cdot \nabla \phi + H'(u)|\nabla u|^2 \phi = 0 \quad \text{for } \phi \in H_0^1 \cap L^\infty.$$

NB $\forall k, T_k(u) \in H_0^1$ & $H(\cdot)$ compactly supported \Rightarrow integrals converge

In general, saying that u satisfies “complementary PDEs” + “finite u and infinite u estimates” yields a weaker notion of solution (without asking $u \in H_0^1$). This is called renormalized solution.

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How to renormalize the fractional laplacian

Difficulty: non-locality \Rightarrow no chain rule like $\nabla u \mathbb{1}_{|u|<k} = \nabla T_k(u)$

Result: With appropriate notation, definitions and re-interpretation of truncation terms, one finds the same well-posedness results as for the local case: existence, uniqueness, L^1 contraction for renormalized solutions of $u + \mathcal{L}[u] = f$ for all L^1 data (Alibaud, A., Bendahmane'10)

Notation: write $T_k u$ for $T_k(u)$, etc.

- Let $d\mu(z)$ is the measure with the density $g(z) := G_s |z|^{-(N+s)}$, i.e.,

$$\mathcal{L}[\phi] = \int_{\mathbb{R}^N} (\phi(x+z) - \phi(x)) d\mu(z).$$

More general measures μ can be considered (Lévy diffusions).

- Let $d\pi(x, y)$ denote the measure $\frac{1}{2}g(x-y) dx dy$ on \mathbb{R}^{2N} .

Recall the following representation of the quadratic form $(\mathcal{L}u, v)_{L^2(\mathbb{R}^N)}$:

For all $u, v \in \mathcal{D}(\mathbb{R}^N)$ (and more, by density)

$$\int_{\mathbb{R}^N} (\mathcal{L}u) v = \iint_{\mathbb{R}^{2N}} (u(x) - u(y)) (v(x) - v(y)) d\pi(x, y).$$

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Definition of renormalized solutions

Definition

Let $f \in L^1_{loc}(\mathbb{R}^N)$. A measurable function $u : \mathbb{R}^N \rightarrow \mathbb{R}$ is called renormalized solution of the problem $u + \mathcal{L}u = f$ if $u \in L^1_{loc}(\mathbb{R}^N)$ and

(i) for all $k > 0$,
$$\iint_{\mathbb{R}^{2N}} (u(x) - u(y)) (T_k u(x) - T_k u(y)) d\pi(x, y) < +\infty;$$

$$\lim_{k \rightarrow +\infty} \iint_{\mathbb{R}^{2N}} (u(x) - u(y)) (\varphi_k u(x) - \varphi_k u(y)) d\pi(x, y) = 0;$$

(ii) for all compactly supported renormalization function $H \in W^{1,\infty}(\mathbb{R})$, for all test function $\phi \in \mathcal{D}(\mathbb{R}^N)$

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“Phase plane” splitting and rewriting the constraint

Set $H_\mu := \{ v \mid \delta_{x,y} v \in L^2(\mathbb{R}^{2N}, d\pi) \}$; recall that $\delta_{x,y} v = v(x) - v(y)$.

The quotient space $H_\mu / \{ v \equiv \text{const} \}$ is a Hilbert space under the scalar product $(v, w) \mapsto \iint_{\mathbb{R}^{2N}} (\delta_{x,y} v)(\delta_{x,y} w) d\pi(x, y)$.

A close examination shows that the “estimates for finite u ” and “estimates for infinite u ” in the Definition imply the properties

$$\|T_k u\|_{H_\mu} \leq k \|f\|_{L^1} \quad \text{and} \quad \lim_{k \rightarrow +\infty} \iint_{\{(u(x), u(y)) \in A_k\}} |u(x) - u(y)| d\pi(x, y) = 0,$$

where $A_k := \{ (u, v) \in \mathbb{R}^2 \mid k+1 \leq \max\{|u|, |v|\} \text{ and } (\min\{|u|, |v|\} \leq k \text{ or } uv < 0) \}$.

Further, denote the region $\{ (u, v) \in \mathbb{R}^2 \mid |u| \leq k, |v| \leq k \}$ by B_k ; finally, the “remainder region” $C_k = \mathbb{R}^2 \setminus (A_k \cup B_k)$ can be neglected, as $k \rightarrow \infty$.

So: due to the “estimates for finite/infinite u ”, for every truncation level k ,

- we control $\delta_{x,y} u$ in L^1 in the region $\{(x, y) \mid (u(x), u(y)) \in A_k\}$;
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These ideas permit to prove existence and uniqueness as in the local case.

NB Convergence for finite differences easier to prove than for gradients !

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THANK YOU — MERCI !