Analysis and approximation of particle-in-Burgers model

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joint work with

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February, 2015 — Institut Henri Poincaré, Paris 27th CEA-GAMNI seminar

Plan of the talk



- 2 Fixed particle case
- Resolving the coupling
- Interface coupling conditions and equilibria



MODEL AND MOTIVATION

Model and motivation

D'Alembert paradox : a solid immersed in an inviscid fluid is not submitted to any resultant force; in other words, birds (and planes...) could not fly with a model where viscosity is neglected ! Yet, inviscid (hyperbolic !) models are desirable for some fluids.

1D case, scalar (playground?) : the Lagoutière-Seguin-Takahashi 'JDE07 model for interaction, via a drag force, of a massive point particle with a Burgers fluid:

$$\left(\begin{array}{c} \partial_t u + \partial_x (u^2/2) = -D(u - h'(t)) \ \delta_0(x - h(t)), \\ mh''(t) = D(u|_{(t,h(t))} - h'(t)). \end{array} \right)$$

Call it B+P model. Here

• *u*, the velocity of the fluid, is unknown

• *h*, the position of the solid particle, is unknown.

Main focus: $D(v) = \lambda v$ A variant: $D(v) = \lambda v |v|$ (the linear case) (the quadratic case)

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Main focus: $D(v) = \lambda v$ (the linear case)A variant: $D(v) = \lambda v |v|$ (the quadratic case).

- Sense to give the the product of distributions $(u h'(t)) \delta_0(x h(t))$ in the RHS of the PDE ? Describe *u* for a *frozen h*?
- Sense to give to the RHS $u|_{(t,h(t))} h'(t)$ of the ODE ? Describe *h* for a fixed *u*?
- Resolve the coupling: fixed-point or splitting approach. Well-posedness, convergence of approximating schemes.
- Numerical approximation: a cheap scheme ? (good resolution at the particle location is essential, but full Riemann solver is not welcome).
- (is being improved) Particle path approximation: difficulty to keep particle(s!) at mesh interfaces. Re-meshing? Projection?
- (unsolved) uniqueness for L^{∞} (non *BV*) data ???

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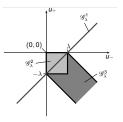
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Giving sense to the PDE: description of interface coupling in Burgers

Interpret the singular source term as the limit of $(u - h'(t))\partial_x H_{\varepsilon}(x)$

⇒ description (LST'07) of the set of all couples $(u_-, u_+) \in \mathbb{R}^2$ that can be connected across the particle:

This is \mathcal{G}_{λ} for particle at rest (h' = 0); one has $\mathcal{G}_{\lambda}(V) = \mathcal{G}_{\lambda} + (V, V)$ for h'(t) = V, due to invariance.



Hence: postulate as modeling assumption: *u* is an admissible solution of the PDE in B+P model if

- it is a Kruzhkov entropy solution away from the path x = h(t);
- and it takes traces such that $(u|_{(t,h(t)^{-})}, u|_{(t,h(t)^{+})}) \in \mathcal{G}_{\lambda}(h'(t))$.

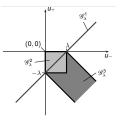
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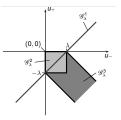
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Giving sense to the ODE: particle moved by conservation of momentum

Following LST'07 , we consider that particle moves according to

$$t\mapsto \int_{\mathbb{R}}u(t,x)\,dx+mh'(t)\ \equiv\ const.$$

Thus, the particle is driven by the "lack of conservativity" of the PDE, i.e., by the jump of the normal to the interface flux component:

$$mh''(t) = \left((u_{-})^{2}/2 - h'(t)u_{-}\right) - \left((u_{+})^{2}/2 - h'(t)u_{+}\right).$$

We prefer to see it as follows (use Green-Gauss): given *u* a Kruzhkov solution to Burgers away from x = h(t),

$$-m\int_0^T h'(t)\xi'(t)dt = mh'(0)\xi(0) + \int_0^T \int_{\mathbb{R}} \left[u\psi\xi_t + \frac{u^2}{2}\xi\psi_x\right] + \int_{\mathbb{R}} u_0\psi\xi(0).$$

 $\forall \xi \in \mathcal{D}([0, T)), \\ \forall \psi \in \mathcal{D}(\mathbb{R}) \text{ such that } \psi \equiv 1 \text{ on the particle path.}$

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Fixed particle $(h \equiv 0; \text{ then } h(\cdot) \text{ frozen})$

The case $h \equiv 0$: the playground ?

Playground: freeze the particle at x = 0, i.e., work with

$$u_t + \left(\frac{u^2}{2}\right)_x = -u\,\delta_0(x).$$

Dissipative structure (source=singular absorption term) \Rightarrow an extension of Kruzhkov theory applies A., Seguin DCDS-A'12 .

Our viewpoint: application of the theory of "discontinuous-flux conservation laws" (Risebro, Towers, Karlsen, Seguin-Vovelle, Adimurthi, Audusse-Perthame and many others). Framework of A., Karlsen, Risebro ARMA'11 guarantees well-posedness because of a specific property of \mathcal{G}_{λ} (it is a "maximal L^1 -dissipative germ"). Moreover: convergence of monotone finite volume schemes – with Godunov flux at x = 0 ! - is guaranteed.

CV is based: on well-balance (equilibrium) property of the scheme ; and on compactness due to stability:

- L^{∞} stability (simple, by a kind of maximum principle)
- BV stability (involved: Wave-Front Tracking A.,L.,S.,T. SIMA'14 or fine observation on a special FV scheme Aguillon, L., S.'14)

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- If h'(t) = V = const (straight particle path), change (x − Vt) → x̃, (u − V) → ũ yields ũ_t + (^{ũ²}/₂)_x = −ũδ₀(x).
- Stop-and-restart ⇒ well-posedness for piecewise affine h
- Approximation of given *h* by a sequence of piecewise affine paths *h_n*, compactness of (*u_n*)_{*n*}, passage to the limit ⇒ existence for any *C*¹ path *h*.
- Numerical counterpart: work on $u_t + (\frac{u^2}{2} h'(t)u)_x = -u\delta_0(t)$ or, equivalently, at each time step incline the mesh following the particle Aguillon, L.,S.'14.
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RESOLVING THE COUPLING

Existence for B+P, L^{∞} data

We have just resolved the PDE on u, given h:

 $A: h \mapsto u.$

Conservation of momentum permits to resolve the ODE on *h*, given *u* solution to Burgers:

 $B: u \mapsto h.$

Fixed point strategy (Schauder) applies in appropriate setting:

a ball of C^1 for h,

a ball of L^{∞} considered in a weighted L^1 space, for *u*.

One shows that

• $C = B \circ A$ is continuous (quite delicate point: check the continuity of A !)

• *C* is compact (simple: compactification since $Image(B) \subset W^{2,\infty}$). Thus *C* admits a fixed point. Existence follows. Uniqueness: open ! Details: A.,Lagoutière, Seguin, Takahashi SIMA'14.

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Well-posedness for B+P, BV data

The essential ingredients here are:

- *BV* estimate on *u* (depending only on u_0 and on ||h|| in $W^{2,\infty}$)
- results on Lipschitz dependence of solutions to $u_t + f(t, u)_x = ...$ on the flux *f*, here $f(t, u) = \frac{u^2}{2} - h'(t)u$.

As a result, one easily proves that A is Lipschitz.

Possibility to replace Schauder by Banach-Picard (contractive) fixed-point on short time intervals \Rightarrow well-posedness, for *BV* data.

Another version: Gronwall for uniqueness. Splitting for existence:

- freezing h' on [tⁿ⁻¹, tⁿ], resolve the problem h → u on every time interval; then update h' at t = tⁿ by conservation of momentum.
- get existence from stability (L[∞], BV for u, W^{2,∞} for h) using compactness due to flux nonlinearity, Lions-Perthame-Tadmor'94, Panov'94.

• numerical counterpart for splitting: use a FV scheme (GODUNOV??) to resolve $h \mapsto u$ approximatively

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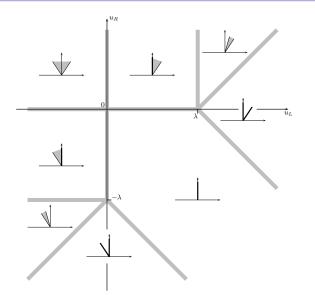
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Case study to describe the Riemann solver, h = 0...Who wants to use Godunov ?



INTERFACE COUPLING CONDITIONS AND ROLE OF EQUILIBRIA

A point of view on the Kruzhkov theory

Consider homogeneous scalar conservation law $u_t + f(u)_x = 0$.

collective ("herd") behaviour: if u, û solutions, ||u − û||_{L¹(ℝ)}(t) ↓ with t. More precisely, Kato inequality holds:

$$|u - \hat{u}|_t + \Phi(u, \hat{u})_x \leqslant 0$$
 in \mathcal{D}'

(|u - k| being Kruzhkov entropy, $\Phi(u, k)$ being the entropy flux).

- Kruzhkov: to describe admissible solutions it's enough to know
 - Kato ineq. holds for any couple of adm. solutions (inherited from approx.! Kruzhkov: from vanishing viscosity)
 - $\hat{u} \equiv k$ are trivially admissible (inherited from approx. as well)
- The basis of convergence proof of well-balanced monotone Finite Volume schemes is :
 - compactness of families of approximate solutions (TVD, or weak BV, or CompComp....)
 - monotonicity of the scheme ⇒ discrete Kato inequality
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• We replicate this idea for $u_t + (\frac{u^2}{2})_x = -u\delta_0$. Seeking equilibria!

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Blackboard talk (15 min?)

- Piecewise constants k(x) = k−11 x<0 + k+11 x>0 are the simplest equilibria. Blow-up argument identifies the set of all admissible k(x) with "(k−, k+) ∈ G_λ".
- The set G_λ has a structure of L¹D germ ((u₋, u₊), (û₋, û₊) ∈ G_λ ⇒ dissipation of the entropy flux: Φ(u₊, û₊) − Φ(u₋, û₋) ≤ 0; the maximality of G_λ). ∃, ! from theory of A.,Karlsen,Risebro'11. Numerics: Godunov at interface converges...
- Forget traces, use adapted entropy ineq. (\equiv Kato ineq. with $\hat{u}(t, x) = k(x)$).
- The line G¹_λ = {(u_−, u₊) | u_− − u₊ = 1} is a "preferential part" of G_λ. Idea: use this graph to "predict" u_± from u_∓. This leads to "prediction" interface numerical fluxes F[±] (non-conservativity ⇒ one-sided fluxes at interface!):

 $F^{-}(u_{-1/2}, u_{1/2}) := F(u_{-1/2}, u_{1/2} - \lambda), \quad F^{+}(u_{-1/2}, u_{1/2}) := F(u_{-1/2} + \lambda, u_{1/2})$

- The resulting "prediction" scheme is well-balanced w.r.t. $\mathcal{G}_{\lambda}^{1}$ but not w.r.t. \mathcal{G}_{λ} . Difficulty: \mathcal{G}_{λ} is a maximal $L^{1}D$ germ; its part $\mathcal{G}_{\lambda}^{1} \cup \mathcal{G}_{\lambda}^{2}$ is a definite $L^{1}D$ germ, but $\mathcal{G}_{\lambda}^{1}$ is not definite. Therefore, convergence of the scheme on some Riemann problems (with endstates in $\mathcal{G}_{\lambda}^{2}$) has to be proved "by hands" (delicate).
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Blackboard talk (15 min?)

- Piecewise constants k(x) = k−11 x<0 + k+11 x>0 are the simplest equilibria. Blow-up argument identifies the set of all admissible k(x) with "(k−, k+) ∈ G_λ".
- The set G_λ has a structure of L¹D germ ((u₋, u₊), (û₋, û₊) ∈ G_λ ⇒ dissipation of the entropy flux: Φ(u₊, û⁺) − Φ(u₋, û₋) ≤ 0; the maximality of G_λ). ∃, ! from theory of A.,Karlsen,Risebro'11. Numerics: Godunov at interface converges...
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FINITE VOLUME SCHEMES FOR B+P

Numerical Finite Volume schemes (first order) = CONCLUSION

Four basic schemes for $h \equiv 0$ (all of them convergent) which only differ by the choice of numerical flux at the particle location:

- "totally well-balanced" : Godunov, with the Riemann solver of L.,S.,T.'07
- "(partially) well-balanced" prediction interface flux of A.,S.'12
- improves on the previous: "very well-balanced" flux of Aguillon, L., S.'14
- "almost well balanced" (totally WB, if based on Godunov for Burgers) hybridized transmission interface flux of A.,Cancès JHDE'15 with one nonlinear equation to solve (scalar, monotone: easy!) per time step.

Adapting these schemes to the coupled problem: main ideas.

- Splitting : update (uⁿ, hⁿ, Vⁿ) to (uⁿ⁺¹, hⁿ, Vⁿ) by one of the above; then update the particle velocity Vⁿ to Vⁿ⁺¹ by conservation of moment, finally update its position hⁿ to hⁿ⁺¹ by integration of the velocity.
- All methods require to localize h^{n+1} at a mesh interface \Rightarrow
 - making the mesh follow the particle ? Aguillon,L.,S.'14, 1 particle only (but the only scheme with convergence proof !)
 ⇒ serious difficulties if more than 1 particle:
 - use projection by random sampling (like Glimm) ? A.,L.,S.,T.'10 trapezoid cells around the particle used for update, then erased
 - or shift the mesh by a multiple of Δx ? Towers'15

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Coupled problem: a well-balanced random-choice numerical scheme

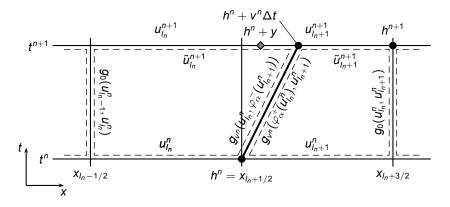


Figure: Representation of the algorithm based on the well-balanced scheme.

Numerics: Glimm scheme versus well-balanced random-choice scheme

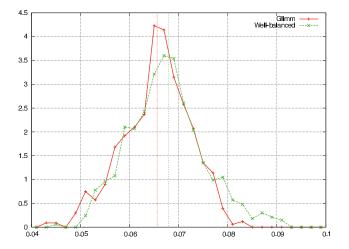


Figure: Probability distributions of velocity of the particle for the two schemes (1000 runs, Van der Corput equidistributed sequences used)

Numerics: drafting-kissing-tumbling

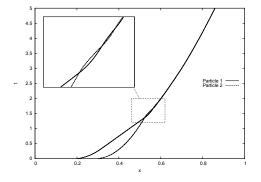


Figure: Trajectories of two particles



MERCI – THANK YOU !