

# Formulation and analysis of Discrete Duality Finite Volume schemes. Part I. Co-volume schemes for the $p(x)$ -laplacian.

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based on joint works with

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## Plan of the talk

- 1 Structural stability for a nonlinear diffusion PDE**
  - A model PDE problem
  - Structural stability
- 2 Generalities on FV schemes and Discrete Duality**
  - Principles of construction of Finite Volume schemes
  - Gradient approximation on diamonds
  - Discrete Duality
- 3 The classical co-volume scheme (=lumped P1 FE)**
  - Construction of a 2D co-volume scheme from a triangulation
  - Discrete Duality property and its consequences
  - Convergence of the co-volume scheme for the  $p(x)$ -laplacian
- 4 Co-volume scheme on general Donald (median dual) mesh**
  - A gradient reconstruction formula on general polygons
  - Generalized co-volume scheme, consistency and Discrete Duality

# STRUCTURAL STABILITY FOR A NONLINEAR DIFFUSION PDE

## A nonlinear diffusion PDE

Consider the problem **(Prob)**:

$$\begin{cases} u - \Delta_{p(x)} u = f & \text{in } \Omega \\ u|_{\partial\Omega} = 0 \end{cases}$$

- $\Omega$ : a bounded Lipschitz domain of  $\mathbb{R}^d$ ,  $d = 1, 2, 3$
- $f$ : an  $L^\infty$  (for simplicity) source term
- the  $p(x)$ -laplacian operator  $\Delta_{p(x)} u := \operatorname{div}(\vec{\nabla} u)^{p(x)-1}$ ,  
 where  $(\vec{\xi})^{p(x)-1} := |\vec{\xi}|^{p(x)-2} \vec{\xi}$  is the “french power” of  $\vec{\xi} \in \mathbb{R}^d$ .  
 Notation:  $\vec{\mathcal{F}}[u] := A(x, \vec{\nabla} u)$  is the flux.  
 The equation writes  $u - \operatorname{div} \vec{\mathcal{F}}[u] = f$ .
- $p$ : a regular function on  $\bar{\Omega}$  with values in  $[p_-, p_+] \subset (1, +\infty)$

**Applications:** e.g., in image processing.

Part of Navier-Stokes models for complex fluids.

**Notion of solution:**

$u \in W_0^{1,1}(\Omega)$  with  $|\nabla u(\cdot)|^{p(\cdot)} \in L^1(\Omega)$ .

Weak formulation (multiply by a test function, integrate by parts).

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## Structural stability

**Basic numerical analysis ? Try to mimic structural stability analysis !**

**Structural stability:** consider  $(f_n)_n, (p_n)_n$  converging to  $f, p$  resp.  
Does the associated solutions' sequence  $(u_n)_n$  of  $(Prob_n)$   
converge to a solution  $u$  of the limit problem?

A way to prove structural stability:

1. Prove **uniform estimates** on the sequence of solutions  $(u_n)_n$
2. Create an **accumulation point  $u$**  for the sequence (compactness arguments). Usually, one starts with a **weak convergence**.
3. Prove that the accumulation point is a solution of the equation  
 $\equiv$  **pass to the limit in the formulation, including nonlinearities**.  
 I.e. for all  $v \in C_0^\infty(\Omega)$ , can we let  $n \rightarrow \infty$  in

$$\int_{\Omega} u_n v + (\vec{\nabla} u_n)^{p_n(x)-1} \cdot \vec{\nabla} v = \int_{\Omega} f_n v ?$$

The question boils down to:

Is the weak limit of  $(\vec{\nabla} u_n)^{p_n(\cdot)-1}$  equal to  $(\vec{\nabla} u)^{p(\cdot)-1}$  ?

Answer : exploit weak PDE formulations both for  $u_n$  and for  $u$ ...

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## Sketch of structural stability proof for (Prob)

Assume  $f_n \rightarrow f$  say, in  $L^2$ . Assume  $p_n \rightarrow p$  a.e. on  $\Omega$ . Follow the steps:

1. Take **test function  $u_n$  in weak formulation of (Prob)** + Young inequality  $\Rightarrow$

$$\|u_n\|_{L^2}^2 + \| |\vec{\nabla} u_n|^{p_n(\cdot)} \|_{L^1} = \int_{\Omega} |u_n|^2 + |\vec{\nabla} u_n|^{p_n(x)} \leq C$$

2. Weak compactness + equi-integrability arguments  $\Rightarrow$

$$u_n \rightharpoonup u \text{ in } L^2, \quad \vec{\nabla} u_n \rightharpoonup \vec{g} \text{ in } L^1, \quad (|\vec{\nabla} u_n|^{p_n(\cdot)-1}) \rightharpoonup \vec{f} \text{ in } L^1.$$

Identification of the weak limit  $\vec{g}$  of  $\vec{\nabla} u_n$  with  $\vec{\nabla} u$ : let  $n \rightarrow \infty$  in

$$\forall \vec{\psi} \in C_0^\infty(\Omega) \quad \int_{\Omega} u_n \operatorname{div} \vec{\psi} = - \int_{\Omega} \vec{\nabla} u_n \cdot \vec{\psi}.$$

3. Identification of the weak limit  $\vec{f}$  of  $(|\vec{\nabla} u_n|^{p_n(\cdot)-1})$  with  $(|\vec{\nabla} u|^{p(\cdot)-1})$ :  
the starting point is the “anti-weak-convergence” inequality

$$\int_{\Omega} \vec{f} \cdot \vec{\nabla} u = \int_{\Omega} (f - u)u \geq \overline{\lim} \int_{\Omega} (f_n - u_n)u_n = \overline{\lim} \int_{\Omega} (|\vec{\nabla} u_n|^{p_n(\cdot)-1}) \cdot \vec{\nabla} u_n.$$

Represent  $\vec{\nabla} u = L^1$  weak-lim  $\vec{\nabla} u_n$  by a Young measure  $(\nu_x(\cdot))_x$

( $\Rightarrow$  this also permits to represent  $\vec{f}$  and  $\vec{f} \cdot \vec{\nabla} u$ ). “Anti-weak” ineq.  $\Rightarrow$

$$\int_{\Omega} \int_{(\mathbb{R}^d)^2} ((\vec{\lambda})^{p_n(\cdot)-1} - (\vec{\mu})^{p_n(\cdot)-1}) \cdot (\vec{\lambda} - \vec{\mu}) d\nu_x(\vec{\lambda}) d\nu_x(\vec{\mu}) \leq 0.$$

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# GENERALITIES ON FINITE VOLUME SCHEMES. DISCRETE DUALITY.

## Generalities on FV schemes

We use Finite Volumes (FV, for short) for space discretization of (*Prob*) .

Generally, let us think of discretizing an elliptic equation of the kind

$$u - \operatorname{div} \vec{\mathcal{F}} = f, \quad \mathcal{F} = A(x, \vec{\nabla} u).$$

The principles for FV approximation of such equations are the following:

- A partition of the space domain  $\Omega$  into “volumes”  $\kappa$  is given; the partition is called “mesh” and denoted by  $\mathfrak{T}$ .
- An unknown  $u_\kappa$  is associated to each volume (usually regarded as the value at a “center” point of the volume, denoted  $x_\kappa$ ); the whole set of the unknowns is called “discrete solution” and denoted by  $u^\mathfrak{T}$ .
- If  $\kappa, \ell$  are “neighbours” (adjacent volumes), the divided differences  $\frac{u_\ell - u_\kappa}{d_{\kappa\ell}}$  are used to “reconstruct” the “discrete gradient”  $\vec{\nabla}^\mathfrak{T} u^\mathfrak{T}$  of  $u^\mathfrak{T}$ .

NB: In the schemes we think of, the reconstruction is done “by hands” .

We do not solve any equations to compute the values of  $\vec{\nabla}^\mathfrak{T} u^\mathfrak{T}$  from those of  $u^\mathfrak{T}$ , but fix *ad hoc* formulas for  $\vec{\nabla}^\mathfrak{T} u^\mathfrak{T}$  in terms of  $u^\mathfrak{T}$ .

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## Generalities on FV schemes (cont<sup>d</sup>)

- Each couple of neighbour volumes possesses a part of the common border, called “interface” and denoted by  $\kappa_L$ . Combining the values  $u_K, u_L$  and the values of the reconstructed discrete gradient  $\vec{\nabla}^\xi u^\xi$  near  $\kappa_L$ , we produce the discretization  $\vec{F}_{\kappa_L}$  of the flux  $\vec{F} = A(x, \vec{\nabla} u)$  on  $\kappa_L$ .
- In two steps, the PDE is replaced by a set of algebraic equations:
  - Firstly, the PDE is “projected on the mesh”. One integrates the continuous equation on  $\kappa$ ; the Green-Gauss formula is used to reduce  $\int_\kappa \operatorname{div} \vec{F}$  to  $\int_{\partial\kappa} \vec{F} \cdot \vec{n}_\kappa$ .  
This yields a discrete system of equalities, one per volume.
  - And secondly, these equalities are approximated by replacing  $u|_\kappa$  with the unknown  $u_\kappa$  and replacing  $\vec{F}|_{\kappa_L}$  with the expression of  $\vec{F}_{\kappa_L} = A(x_{\kappa_L}, \vec{\nabla}_{\kappa_L} u^\xi)$ .

NB: e.g. in TPFA schemes all components of  $\vec{\nabla}_{\kappa_L} u^\xi$  need not be reconstructed, since only the normal fluxes  $\vec{F}_{\kappa_L} \cdot \vec{n}_\kappa$  appear.

However, for (Prob) or for linear anisotropic diffusion  $\mathbb{K} \nabla u$

(cf. R.Eymard’s lectures) : one should(?) define (per interface)  $\vec{\nabla}_{\kappa_L} u^\xi$ .

- As a result, we obtain a closed system of algebraic equations which (hopefully...) can be solved, often in an approximate way.  
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## Volumes and diamonds. Discrete gradient and divergence operators.

For representing discrete gradients, many FV schemes use “diamond mesh”.

A diamond  $\widehat{\kappa}$  is a neighbourhood of interface  $\kappa$ .

Notation ( $\sim$  Gradient Schemes) useful to formulate “Discrete Duality”:

- Consider  $\mathfrak{T} = (\mathcal{D}, \mathcal{M})$  consisting of two partitions of  $\Omega$ :  
volumes  $\kappa$  (mesh  $\mathcal{M}$ ) and diamonds  $D$  (diamond mesh  $\mathcal{D}$ ).
- Consider two kinds of objects:  
discrete functions  $u^{\mathfrak{T}} \in \mathbb{R}^{\#\mathfrak{M}}$  and discrete fields  $\vec{F}^{\mathfrak{T}} \in (\mathbb{R}^{\#\mathfrak{D}})^d$ :

$$u^{\mathfrak{T}} = (u_{\kappa})_{\kappa \in \mathfrak{M}}, \quad \vec{F}^{\mathfrak{T}} = (\vec{F}_D)_{D \in \mathfrak{D}}.$$

They are lifted to  $\Omega$  as piecewise constant (per volume / per diamond) functions  $\Pi u^{\mathfrak{T}}$  and fields  $\vec{\Pi} \vec{F}^{\mathfrak{T}}$  (cf. Gradient Schemes).

- Discrete gradient operator: some “per diamond reconstruction”

$$\vec{\nabla}^{\mathfrak{T}} : \mathbb{R}^{\#\mathfrak{M}} \longrightarrow (\mathbb{R}^{\#\mathfrak{D}})^d, \quad \vec{\nabla}_D u^{\mathfrak{T}} := \text{Formula}(u_{\kappa} \text{ for } \kappa \text{ near } D)$$

- Discrete divergence operator: per volume integration + Green-Gauss:

$$\text{div}^{\mathfrak{T}} : (\mathbb{R}^{\#\mathfrak{D}})^d \longrightarrow \mathbb{R}^{\#\mathfrak{M}}, \quad \text{div}_{\kappa} \vec{F}^{\mathfrak{T}} := \frac{1}{|\kappa|} \sum_D |\partial \kappa \cap D| \vec{F}_D \cdot \vec{n}_{\kappa}.$$

## Scalar products of discrete functions/fields and Discrete Duality

- inner product on the space of discrete functions:

$$\left[ u^\mathfrak{T}, v^\mathfrak{T} \right] := \sum_{K \in \mathfrak{M}} |K| u_K v_K$$

- inner product on the space of discrete fields:

$$\left\{ \vec{\mathcal{F}}^\mathfrak{T}, \vec{\mathcal{G}}^\mathfrak{T} \right\} := \sum_{D \in \mathfrak{D}} |D| \vec{\mathcal{F}}_D \cdot \vec{\mathcal{G}}_D$$

- Discrete Duality (DD) property holds if  $\operatorname{div}^\mathfrak{T}$  and  $-\vec{\nabla}^\mathfrak{T}$  fulfill :**

$$\forall u^\mathfrak{T} \in \mathbb{R}^{\#\mathfrak{M}} \quad \forall \vec{\mathcal{F}}^\mathfrak{T} \in \mathbb{R}^{\#\mathfrak{D}}$$

$$\left[ u^\mathfrak{T}, \operatorname{div}^\mathfrak{T} \vec{\mathcal{F}}^\mathfrak{T} \right] + \left\{ \vec{\nabla}^\mathfrak{T} u^\mathfrak{T}, \vec{\mathcal{F}}^\mathfrak{T} \right\} = 0 \quad (\text{or} = \left\langle \dots, \dots \right\rangle_{\partial\Omega}).$$

**Use of DD property:** it permits to mimic the structural stability arguments for proving convergence of the scheme

**Additional ingredient:** (natural) consistency properties

- for the discrete gradient applied to projections of test functions
- for the discrete divergence applied to projection of test fields.

CLASSICAL CO-VOLUME SCHEME

AKA

LUMPED P1 FINITE ELEMENT SCHEME

## The co-volume scheme in 2D

- Consider a Delaunay triangulation  $\mathcal{D}$  (“diamonds”) of  $\Omega$
- Attach the DOF to the nodes of the diamond mesh  $\mathcal{D}$ .  
Interpret the DOF as values of the **const/volume discrete solution**  $u^\mp = (u_k)_k$  on the dual (Voronoi) mesh  $\mathcal{M}$
- Given  $u^\mp$ , the const/diamond discrete gradient  $\vec{\nabla}^\mp u^\mp :=$  the gradient of the P1 EF reconstruction from node DOFs .

### Lemma (explicit representation of $\vec{\nabla}_D u^\mp$ )

This “co-volume discrete gradient” is exact on affine functions and is given by

$$\vec{\nabla}_D u^\mp = \frac{|K_L \cap D|(u_L - u_K)\vec{n}_{K,L} + |M \cap D|(u_M - u_L)\vec{n}_{L,M} + |M_K \cap D|(u_K - u_M)\vec{n}_{M,K}}{|D|}$$

The co-volume scheme for (*Prob*) is formulated “pointwise” as :

$$\forall k \in \mathcal{M} \quad u_k - \frac{1}{|K|} \sum_D |\partial K \cap D| (\vec{\nabla}_D u^\mp)^{p_D-1} \cdot \vec{n}_k = f_k$$

with  $(p_D)_D, (f_k)_k$  piecewise constant discretizations of  $p(\cdot)$  and  $f(\cdot)$ .  
Dirichlet BC: attach the values 0 to the nodes  $x_k \in \partial\Omega$ .

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## 2D co-volume scheme is a Discrete Duality scheme

### Lemma (the DD property)

*The 2D co-volume scheme has the Discrete Duality property.*

**Proof:**

$$\begin{aligned}
 \sum_{K \in \mathfrak{T}} |K| \left( \frac{1}{|K|} \sum_D |\partial K \cap D| \vec{\mathcal{F}}_D \cdot \vec{n}_K \right) v_K &= \\
 &\left( \text{gather by } D; \text{ notice } \vec{\mathcal{F}}_D \cdot \vec{n}_K \equiv -\vec{\mathcal{F}}_D \cdot \vec{n}_L \right) \\
 = \sum_{D \in \mathfrak{D}} |D| \vec{\mathcal{F}}_D \cdot \frac{|\mathcal{K}_L \cap D| (v_L - v_K) \vec{n}_{K,L} + \dots + |\mathcal{M}_K \cap D| (v_K - v_M) \vec{n}_{M,K}}{|D|} &= \sum_{D \in \mathfrak{D}} |D| \vec{\mathcal{F}}_D \cdot \vec{\nabla}_D v^\sharp.
 \end{aligned}$$

NB: this is a “**miracle property**” (unlike in mimetic schemes) !

Two “**naturally defined**” operators **turn out to be dual**.

## Consistency and “Gradient scheme” point of view

### Pointwise form of the discrete duality:

Let us write the DD in a formalism reminiscent of **Gradient Schemes**.

Associate to  $u^\varepsilon$ , the function  $(\Pi u^\varepsilon)(x) := \sum_K u_K \mathbb{1}_K(x)$  on  $\Omega$ ;

and to  $\vec{F}^\varepsilon$ , the field  $(\vec{\Pi} \vec{F}^\varepsilon)(x) := \sum_D \vec{F}_D \mathbb{1}_D(x)$ .

Then the DD property writes  $\sim$  to the **limit-conformity property of GS**:

$$\int_{\Omega} (\Pi \operatorname{div}^\varepsilon \vec{F}^\varepsilon)(x) (\Pi v^\varepsilon)(x) + (\vec{\Pi} \vec{F}^\varepsilon)(x) \cdot (\vec{\Pi} \vec{\nabla} v^\varepsilon)(x) = 0.$$

The limit-conformity can be deduced using **consistency lemmas**. E.g.

### Lemma (consistency of discretization of divergence)

Let  $\vec{\psi} \in C_c^\infty(\Omega)^d$ . Given a sequence of meshes  $\varepsilon$  with  $\operatorname{size}(\varepsilon) \rightarrow 0$ , define  $\vec{\psi}^\varepsilon$  by  $\vec{\psi}_D := \frac{1}{|D|} \int_D \vec{\psi}(x) dx$  for each diamond  $D$ . Then

$$\Pi \operatorname{div}^\varepsilon \vec{\psi}^\varepsilon \rightarrow \operatorname{div} \vec{\psi} \text{ in } L^\infty(\Omega).$$

**Proof:** straightforward using smoothness of  $\vec{\psi}$ .

Finer versions support Sobolev regularity of fields/functions.

**NB** Other consistency lemmas: for discrete functions, for gradients.

## Consequences of the discrete duality

### Corollary (the weak formulation of the scheme)

The scheme is equivalent to: find  $u^\mathfrak{T} \in \mathbb{R}_0^{\#\mathfrak{M}}$  such that

$$\forall v^\mathfrak{T} \in \mathbb{R}_0^{\#\mathfrak{M}} \quad \left[ u^\mathfrak{T}, v^\mathfrak{T} \right] + \left\{ (\vec{\nabla}^\mathfrak{T} u^\mathfrak{T})^{\rho^\mathfrak{T}-1}, \nabla^\mathfrak{T} v^\mathfrak{T} \right\} = \left[ f^\mathfrak{T}, v^\mathfrak{T} \right].$$

### Corollary (discrete variational form of the scheme)

The scheme is equivalent to: find  $u^\mathfrak{T} \in \mathbb{R}_0^{\#\mathfrak{M}}$  that minimizes

$$\mathbb{E} : u^\mathfrak{T} \mapsto \sum_{K \in \mathfrak{M}} |K| \frac{|u_K - f_K|^2}{2} + \sum_{D \in \mathfrak{D}} |D| \frac{|\vec{\nabla}_D u^\mathfrak{T}|^{\rho^\mathfrak{T}}}{\rho^\mathfrak{T}}.$$

### Proposition (asymptotic compactness)

Assume that for a sequence of meshes  $\mathfrak{T}_h$  with  $h = \text{size}(\mathfrak{T}_h) \rightarrow 0$ ,  $u^{\mathfrak{T}_h} \in \mathbb{R}_0^{\#\mathfrak{T}_h}$  and  $(\Pi u^{\mathfrak{T}_h})_h, (\vec{\Pi} \vec{\nabla}^{\mathfrak{T}_h} u^{\mathfrak{T}_h})_h$  are bounded in  $L^{1+\text{sthg}}(\Omega)$ .

Then there exists  $u \in W_0^{1,1}(\Omega)$  such that

$$\Pi u^{\mathfrak{T}_h} \rightarrow u \text{ in } L^1(\Omega) \text{ and } \vec{\Pi} \vec{\nabla}^{\mathfrak{T}_h} u^{\mathfrak{T}_h} \rightharpoonup \vec{\nabla} u \text{ weakly in } L^1(\Omega).$$

**Proof:** Use DD + consistency for test fields  $\vec{\psi}$  and  $\text{div} \vec{\psi}$ .

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## Proof of convergence of the co-volume scheme for (Prob):

Follow the lines of the Steps of the structural stability proof.

1. Take **test function  $u^\varepsilon$**  in the discrete weak formulation of (Prob $^\varepsilon$ ).

Young inequality  $\Rightarrow$

$$\begin{aligned} \|\Pi u^\varepsilon\|_{L^2}^2 + \|\Pi \vec{\nabla}^\varepsilon u^\varepsilon\|_{L^1}^{\rho^\varepsilon(\cdot)} & \\ &= \left[ u^\varepsilon, u^\varepsilon \right] + \left\{ (\vec{\nabla}^\varepsilon u^\varepsilon)^{\rho^\varepsilon-1}, \vec{\nabla}^\varepsilon u^\varepsilon \right\} \leq C \end{aligned}$$

2. “Asymptotic compactness” property + equi-integrability  $\Rightarrow$

$$\Pi u^\varepsilon \rightharpoonup u \text{ in } L^2, \quad \Pi \vec{\nabla}^\varepsilon u^\varepsilon \rightharpoonup \vec{\nabla} u \text{ in } L^1, \quad (\Pi \vec{\nabla}^\varepsilon u^\varepsilon)^{\rho_n(\cdot)-1} \rightharpoonup \vec{\mathcal{F}} \text{ in } L^1.$$

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$$\begin{aligned} \int_\Omega \vec{\mathcal{F}} \cdot \vec{\nabla} u &= \int_\Omega (f - u)u \geq \overline{\lim} \left[ f^\varepsilon - u^\varepsilon, u^\varepsilon \right] \\ &= \overline{\lim} \left\{ (\vec{\nabla}^\varepsilon u^\varepsilon)^{\rho^\varepsilon-1}, \vec{\nabla}^\varepsilon u^\varepsilon \right\} \equiv \int_\Omega (\Pi \vec{\nabla}^\varepsilon u^\varepsilon)^{\rho^\varepsilon-1} \cdot \Pi \vec{\nabla}^\varepsilon u^\varepsilon. \end{aligned}$$

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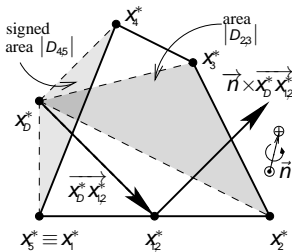
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# GENERALIZED CO-VOLUME SCHEME ON DONALD (MEDIAN DUAL) MESH



## A gradient reconstruction formula

Polygon  $D \subset \Theta$ , oriented by  $\vec{n} \perp \Theta$



Let  $\Theta$  be a plane in  $\mathbb{R}^3$  with a unit normal vector  $\vec{n}$ , and  $D \subset \Theta$  be a polygon.

Introduce the vertices  $x_i^*$ ,  $i = 1, \dots, \ell$  (numbered counter-clockwise w.r.t. the orientation of  $\Theta$  induced by  $\vec{n}$ ).

Denote the area of  $\sigma$  by  $|D|$ , we have  $|D| = \sum_{i=1}^{\ell} |D_{i,i+1}|$  (sub-areas are signed).

Let  $x_b^* \in \Theta$  be a distinguished point .

Take  $x_{i,i+1}^*$  the midpoints of the edges .

### Lemma

For all  $\vec{r} \parallel \Theta$ , 
$$\vec{r} = \frac{1}{|D|} \sum_{i=1}^{\ell} (\vec{r} \cdot \overrightarrow{x_i^* x_{i+1}^*}) [\vec{n} \times \overrightarrow{x_b^* x_{i,i+1}^*}] \equiv \frac{2}{|D|} \sum_{i=1}^{\ell} |D_{i,i+1}| (\vec{r} \cdot \vec{e}_{i,i+1}) \vec{e}'_{i,i+1},$$

where  $\vec{e}_{i,i+1} := \overrightarrow{x_i^* x_{i+1}^*} / \|\overrightarrow{x_i^* x_{i+1}^*}\|$  and  $\vec{e}'_{i,i+1} := [\vec{n} \times \overrightarrow{x_b^* x_{i,i+1}^*}] / \|\overrightarrow{x_b^* x_{i,i+1}^*}\|$ .

The formula can be derived from the “magical formula” of [Droniou, Eymard](#) .

NB: if  $\ell > 3$ , this is one of infinitely many affine reconstruction formulas !

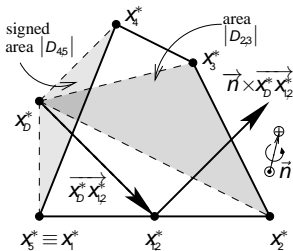
## The formula (cont<sup>d</sup>)

### Corollary (Consistency of the gradient reconstruction)

Take  $(w_i^*)_{i=1}^\ell \subset \mathbb{R}$ ,  $w_{\ell+1}^* := w_1^*$ . If  $w_i^*$  are the values of an affine function  $w$  at the vertices  $x_i^*$  of the polygon  $\sigma$ , then

$$\vec{\nabla} w = \frac{1}{|D|} \sum_{i=1}^{\ell} (w_{i+1}^* - w_i^*) [\vec{n} \times \overrightarrow{x_i^* x_{i+1}^*}] \equiv \frac{2}{|D|} \sum_{i=1}^{\ell} |D_{i,i+1}| \frac{w_{i+1}^* - w_i^*}{d_{i,i+1}} \vec{e}'_{i,i+1},$$

where  $d_{i,i+1} := \|\overrightarrow{x_i^* x_{i+1}^*}\|$  and  $\vec{e}'_{i,i+1} := [\vec{n} \times \overrightarrow{x_i^* x_{i+1}^*}] / \|\vec{n} \times \overrightarrow{x_i^* x_{i+1}^*}\|$



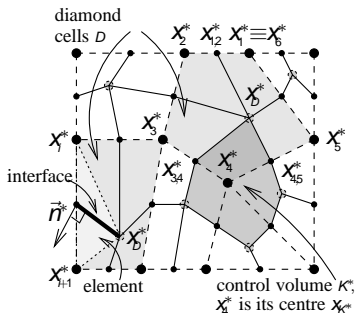
## 2D co-volume scheme: generalization to Donald (median dual) mesh.

The idea of the 2D co-volume scheme on the Voronoï mesh dual to a triangulation was:

reconstruct the discrete gradient on a given triangulation (affine per triangle) and then write the FV scheme on the dual mesh .

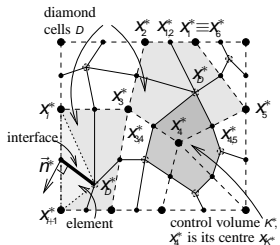
Thus the triangles were “diamonds” of the scheme.

We can replace the triangulation  $\mathcal{D}$  by an arbitrary polygonal partition.



We use the “median dual mesh” ( $\equiv$  “Donald dual mesh”) for  $\mathcal{M}$ .

## Generalized co-volume scheme in 2D (cont<sup>d</sup>)



Here, we do not necessarily need  $\sigma$ 's (the “diamonds”) to be triangles; any polygon would do (in particular, quadrilaterals are welcome).

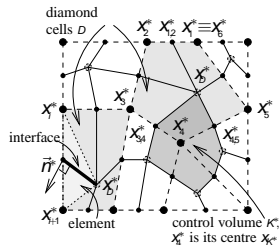
We associate to each “diamond” a value of the discrete gradient (reconstructed from the formula of the Corollary) .

We associate to the mesh the standard FV discrete divergence operator.

**Theorem (DD property for 2D co-volume scheme on Donald mesh)**

*These discrete gradient and divergence operators are linked by the discrete duality (integration-by-parts) formula.*

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## To be continued... towards 2D and 3D DDFV schemes

To be continued...  
**2D and 3D “DDFV schemes”**  
are awaiting us tomorrow !