# A particle-in-Burgers model: theory and numerics

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joint work with

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Hyperbolic Conservation Laws and Related Analysis with Applications

#### Plan of the talk

- Model and motivation
- 2 Auxiliary steps
- 3 Main Results
- 4 The frozen particle case: coupling
- The frozen particle case: definition, uniqueness
- **6** The frozen particle case: numerics and existence
- The coupled problem

# MODEL AND MOTIVATION

D'Alembert paradox : a solid immersed in an inviscid fluid is not submitted to any resultant force ; in other words, birds (and planes...) could not fly with a model where viscosity is neglected ! Yet, inviscid (hyperbolic !) models are ok for some fluids...

Answer 1 to the d'Alembert paradox: use viscous models of fluid-solid interaction (see e.g. M. Hillairet , for a recent review).

Answer 2 (when the Reynolds number is large): it is reasonable to neglect the viscous effects in the model that governs the fluid ; but we have to conserve information from the vanishing viscosity in a DRAG FORCE.

The drag force takes the form of a source term which takes into account the difference between the velocity of the fluid and the velocity of the solid.

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The 1D case : the Lagoutière-Seguin-Takahashi model for the interaction, via a drag force, of a point particle with a Burgers fluid writes

 $\partial_t u + \partial_x (u^2/2) = \lambda D(h'(t) - u) \delta_0(x - h(t)),$  $mh''(t) = \lambda D(u(t, h(t)) - h'(t)).$ 

here

- u, the velocity of the fluid, is unknown
- *h*, the position of the solid particle, is unknown (then *h*' and *h*'' respectively denote its velocity and acceleration);

• the parameters are  $\lambda$  (the drag coefficient) and *m* (the mass of the solid particle); both are positive.

• the function *D* which intervenes in the drag force is an increasing odd function.

Actually, we will suppose that

either D(v) = vor D(v) = v|v| (the linear case) (the quadratic case).

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### AUXILIARY STEPS

Our study of the above coupled problem includes two auxiliary steps, that are of interest on their own. The first step is

 $\begin{cases} \partial_t u(t, \mathbf{x}) + \partial_x (u^2/2)(t, \mathbf{x}) = -\lambda \ u(t, \mathbf{x}) \ \delta_0(\mathbf{x}), & t > 0, \ \mathbf{x} \in \mathbb{R}, \\ u(0, \mathbf{x}) = u_0(\mathbf{x}), & \mathbf{x} \in \mathbb{R}, \end{cases}$ 

i.e., the particle is decoupled from the fluid and fixed at zero. Difficulty 1 : the source term has to be carefully defined. Indeed, *u* can be discontinuous (and in fact, typically *u* IS DISCONTINUOUS at the particle location ).

To give an interpretation of the source term, the LeRoux approximation was studied in detail by Lagoutière, Seguin, Takahashi:  $\delta_0 = \partial_x H$  (*H*: the Heavyside function) is replaced by  $\partial_x H_{\varepsilon}$ , a smoothed version. This permits to understand what goes on at the interface.

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Other way around, we should understand how to evolve the particle location given the fluid state at time *t*. Recall the equation (ODE) for the particle:  $mh''(t) = \lambda (u(t, h(t)) - h'(t)).$ 

Recall that  $u(t, \cdot)$  has a jump at x = h(t)...

**Difficulty 2** : understand the equation in the Carathéodory sense ? In the Filippov sense ?? We will see that a nice mathematical and physical interpretation is possible:

• the particle is driven by the lack of mass conservation in the equation for u; or, equivalently, the total quantity of movement  $\int_{\mathbb{R}} u(t, \cdot) + mh'(t)$  is conserved.

• the ODE for *h* can be written in a weak form that involves the values of  $u(t, \cdot)$  on  $\mathbb{R}$  (which is more "robust")

- think of the appropriate definition of solution
- use fixed-point arguments to guarantee existence
- use time splitting algorithms (evolve the PDE and the ODE alternatively) for existence (constructive) and efficient numerics.

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## MAIN RESULTS

For the Burgers-with-Dirac-at-zero model, we apply the machinery developed for conservation laws with discontinuous flux (adapted entropies, Baiti,Jenssen and Audusse,Perthame; revisited and generalized recently by BA., Karlsen, Risebro using the notion of admissibility germ). The outcome is:

definition(s) of entropy solutions

– uniqueness, continuous dependence  $(L^1, L^1_{loc})$  with domain of dependence) exactly as in the Kruzhkov theory

In addition, we find

– a priori  $L^{\infty}$  bounds and (more delicate) variation bounds

a strikingly simple numerical method (monotone consistent finite volume scheme with a trick at the interface)

– convergence of the numerical scheme, existence.

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- convergence of the numerical scheme, existence .

Then for the Burgers-driven-by-particle model (with x = h(t) GIVEN path of the particle) we deduce well-posedness rather easily.

It is observed that the case of straight path, h(t) = Vt with V = const, reduces to the Dirac-at-zero model by the simultaneous change of u - V into u and of x - Vt into x. Thus, nothing new for h(t) = Vt. Then any  $(W^{2,\infty})$  path  $h(\cdot)$  is approximated by piecewise affine paths; existence is established by passage to the limit. Uniqueness is straightforward from the definition of solution.

For the coupled model with data  $u_0$  and h(0) = 0,  $h'(0) = v_0$ , we get

– existence, for  $L^{\infty}$  data  $u_0$ 

- existence, uniqueness, continuous dependence for BV solutions, for BV data  $u_0$ .

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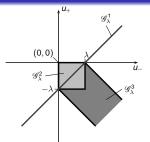
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Model and motivation Auxiliary steps Results h = 0: coupling h = 0: definition, uniqueness h = 0: numerics, existence The coupled problem

## FROZEN PARTICLE (DIRAC-AT-ZERO DRAG TERM): UNDERSTANDING THE COUPLING

#### Frozen particle: understanding the coupling...

The admissibility at the interface  $\{x = 0\}$  of the solution is governed by the germ  $\mathscr{G}_{\lambda}$ (terminology related to the one of BA, Karlsen, Risebro ):



#### Definition

The *admissibility germ*  $\mathscr{G}_{\lambda} \subset \mathbb{R}^2$  (or *germ*, for short) associated with the particle-at-zero problem is the union  $\mathscr{G}_{\lambda} = \mathscr{G}_{\lambda}^1 \cup \mathscr{G}_{\lambda}^2 \cup \mathscr{G}_{\lambda}^3$ , where

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$$\mathscr{G}^1_{\lambda} = \{ (\boldsymbol{a}, \boldsymbol{a} - \lambda), \boldsymbol{a} \in \mathbb{R} \}.$$

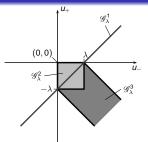
• 
$$\mathscr{G}_{\lambda}^2 = [0, \lambda] \times [-\lambda, 0].$$

• 
$$\mathscr{G}^3_{\lambda} = \{(a, b) \in (\mathbb{R}^+ \times \mathbb{R}^-) \setminus \mathscr{G}^2_{\lambda}, \ -\lambda \leqslant a + b \leqslant \lambda\}.$$

NB: the partition of  $\mathscr{G}_{\lambda}$  into the three parts is dictated by the subsequent analysis, and by profiles study of LST.

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$$\mathscr{G}^{\mathsf{1}}_{\lambda} = \{(a, a - \lambda), a \in \mathbb{R}\}.$$

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NB: the partition of  $\mathscr{G}_{\lambda}$  into the three parts is dictated by the subsequent analysis, and by profiles study of LST.

Explaination : the Burgers equation with Dirac-at-zero drag term is equivalent to  $\partial_t u + \partial_x (u^2/2) = -\lambda u \partial_x H.$ 

We introduce  $H_{\varepsilon} \in C^1(\mathbb{R})$  a non-decreasing function such that  $H_{\varepsilon}(x) = H(x)$ when  $|x| \ge \varepsilon$ . Since we are interested in understanding the behavior of the solution through the stationary interface  $\{x = 0\}$ , we can study only stationary solutions. We then obtain the regularized equation for  $U_{\varepsilon}(x) = u(t, x)$  in the strip  $-\varepsilon < x < \varepsilon$ :

 $(U_{\varepsilon}^{2}/2)'(x) + \lambda U_{\varepsilon}(x)\partial_{x}H_{\varepsilon}(x) = 0.$ 

Proposition (Lagoutière, Seguin, Takahashi '08)

Independently from the choice of  $H_{\varepsilon}$ , there exists a solution to the above ODE with  $U_{\varepsilon}(-\varepsilon) = c_{-}$  and  $U_{\varepsilon}(+\varepsilon) = c_{+}$  if and only if  $(c_{-}, c_{+}) \in \mathscr{G}_{\lambda}$ .

The modelling assumption we make is the following :

the traces  $\gamma_{-}u$  and  $\gamma_{+}u$  at  $\{x = 0\}$  of a solution u of the Burgers equation on  $\mathbb{R}^+ \times (\mathbb{R} \setminus \{0\})$  are compatible if and only if there exists a solution to above ODE such that  $U_{\varepsilon}(-\varepsilon) = \gamma_{-}u$ ,  $U_{\varepsilon}(\varepsilon) = \gamma_{+}u$ .

Explaination : the Burgers equation with Dirac-at-zero drag term is equivalent to  $\partial_t u + \partial_x (u^2/2) = -\lambda u \partial_x H.$ 

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Proposition (Lagoutière, Seguin, Takahashi '08)

Independently from the choice of  $H_{\varepsilon}$ , there exists a solution to the above ODE with  $U_{\varepsilon}(-\varepsilon) = c_{-}$  and  $U_{\varepsilon}(+\varepsilon) = c_{+}$  if and only if  $(c_{-}, c_{+}) \in \mathscr{G}_{\lambda}$ .

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Now, the dissipativity properties of the interface coupling are encoded in the germ  $\mathscr{G}_{\lambda}$ . Indeed, define  $\Xi \colon \mathbb{R}^2 \times \mathbb{R}^2 \mapsto \mathbb{R}$  by

$$\Xi^{\pm}((u_{-}, u_{+}), (v_{-}, v_{+})) = \Phi^{\pm}(u_{-}, v_{-}) - \Phi^{\pm}(u_{+}, v_{+})$$

where  $\Phi^{\pm}$  are the so-called semi-Kruzhkov entropy fluxes for Burgers eqn:  $\Phi^{\pm}(u, v) = \operatorname{sgn}^{\pm}(u - v)(u^2 - v^2)/2.$ 

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#### **Proposition (dissipativity and maximality of** $\mathscr{G}_{\lambda}$ )

The following properties hold:

(i) (dissipativity)  $\forall (u_-, u_+), (v_-, v_+) \in \mathscr{G}_{\lambda}$ ,

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# A "better" (indirect) proof comes from the general theory from AKR .

First, property (*i*) is actually equivalent to the "Kato inequality" ( $\Leftrightarrow L^1$ -dissipativity)

$$-\int_{\mathbb{R}^+}\!\!\int_{\mathbb{R}}\!\left((u-v)^+\,\partial_t\varphi+\Phi^+(u,v)\,\partial_x\varphi\right)\leqslant 0\quad\forall\,\varphi\in\mathcal{D}(\mathsf{Q}),\,\varphi\geqslant 0.$$

for the solutions

$$u(t,x) := u_{-} \mathbb{1}_{\{x < 0\}} + u_{+} \mathbb{1}_{\{x > 0\}}, \quad v(t,x) := v_{-} \mathbb{1}_{\{x < 0\}} + v_{+} \mathbb{1}_{\{x > 0\}}$$

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$$\int_{\mathbb{R}^+}\!\!\int_{\mathbb{R}} (\lambda (u^{\varepsilon} - v^{\varepsilon})^+ (\partial_x H_{\varepsilon}) \varphi - (u^{\varepsilon} - v^{\varepsilon})^+ \partial_t \varphi - \Phi^+ (u^{\varepsilon}, v^{\varepsilon}) \partial_x \varphi) \leqslant 0.$$

Further, property (*ii*) means that " $\mathscr{G}^1_{\lambda} \cup \mathscr{G}^2_{\lambda}$  is a definite germ of which  $\mathscr{G}_{\lambda}$  is the unique maximal extension". This follows (with some work) from the fact that  $\mathscr{G}_{\lambda}$  is a complete germ ( $\Leftrightarrow$  the germ allows to solve every Riemann problem).

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Model and motivation Auxiliary steps Results h = 0: coupling h = 0: definition, uniqueness h = 0: numerics, existence The coupled problem

# FROZEN PARTICLE (DIRAC-AT-ZERO DRAG TERM): DEFINITION, UNIQUENESS

First, let us describe some elementary solutions of this problem: these are the stationary piecewise constant functions *c*:

$$c(t,x) = c_{-} 1_{\{x < 0\}} + c_{+} 1_{\{x > 0\}} = egin{cases} c_{-} & ext{if } x < 0, \ c_{+} & ext{if } x > 0, \ c_{+} & ext{if } x > 0, \end{cases}$$

They play the role of the constants in the standard Kruzhkov entropy formulation. With the idea of adapted Kruzhkov entropies, we set up

# **Definition (entropy solution)**

Let  $u_0 \in L^{\infty}(\mathbb{R})$ . A function  $u \in L^{\infty}(\mathbb{R}^+ \times \mathbb{R})$  is said to be an entropy solution of the "particle-at-zero" problem if for all function *c* defined above with  $(c_-, c_+) \in \mathscr{G}_{\lambda}$ ,

$$\forall \varphi \in \mathcal{C}^{\infty}_{c}(\mathbb{R}^{+} \times \mathbb{R}), \, \varphi \ge 0 \quad \int_{\mathbb{R}^{+}} \int_{\mathbb{R}} [|u - c(x)| \, \partial_{t} \varphi + \Phi(u, c(x)) \, \partial_{x} \varphi] \, dx \, dt \\ + \int_{\mathbb{R}} |u_{0} - c(x)| \, \varphi(0, x) \, dx \ge 0.$$

Let us provide alternative characterizations of entropy solutions:

# Proposition (equivalent definitions)

A function  $u \in L^{\infty}(\mathbb{R}^+ \times \mathbb{R})$  is an entropy solution if and only if it satisfies any of the following assertions:

- A. The function u verifies the adapted entropy inequalities with  $(c_-, c_+) \in \mathscr{G}^1_{\lambda} \cup \mathscr{G}^2_{\lambda}$ .
- B. The function u verifies the Kruzhkov entropy inequalities for all nonnegative test function  $\varphi \in C_c^{\infty}(\mathbb{R}^+ \times \mathbb{R})$  such that  $\varphi|_{x=0} = 0$ , moreover, for a e t > 0  $(( \sim u)(t), ( \sim u)(t)) \in \mathscr{C}_2$

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# Theorem (L<sup>1</sup> contraction+comparison, analogous to Kruzhkov theory)

Let  $u_0$  and  $v_0$  be two initial data in  $L^{\infty}(\mathbb{R})$  and let u and v be the associated entropy solutions. Then for all R > 0,

for a.e. 
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where  $L = \max\{\|u\|_{\infty}, \|v\|_{\infty}\}$ . Consequently, if  $(u_0 - v_0)^+ \in L^1(\mathbb{R})$ , we have

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Let  $u_0$  and  $v_0$  be two initial data in  $L^{\infty}(\mathbb{R})$  and let u and v be the associated entropy solutions. Then for all R > 0,

for a.e. 
$$t > 0$$
  $\int_{R}^{R} (u - v)^{+}(t, x) dx \leq \int_{-R-Lt}^{R+Lt} (u_0 - v_0)^{+}(x) dx$ 

where  $L = \max\{\|u\|_{\infty}, \|v\|_{\infty}\}$ . Consequently, if  $(u_0 - v_0)^+ \in L^1(\mathbb{R})$ , we have

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In particular, for all  $u_0 \in L^{\infty}(\mathbb{R})$ , there exists at most one solution and the map  $S(t) : u_0 \mapsto u(t, \cdot)$  on its domain is an order-preserving  $L^1$  contraction.

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# FROZEN PARTICLE (DIRAC-AT-ZERO DRAG TERM): NUMERICAL SCHEME AND EXISTENCE

We use a well-balanced finite volume scheme , preserving exactly (some of) the stationary sols  $u(t, x) := u_- \mathfrak{ll}_{\{x < 0\}} + u_+ \mathfrak{ll}_{\{x > 0\}}$ . Usual schemes are determined by a numerical flux  $g(\cdot, \cdot)$ :

- g locally Lipschitz;
- $-g(u,u)=\frac{u^2}{2}$  (consistency );
- $-g(\cdot, b)$  is  $\nearrow$ ,  $g(a, \cdot)$  is  $\searrow$  (monotonicity).

We only modify  $g(\cdot, \cdot)$  at the interface x = 0 (between  $x_0$  and  $x_1$ ):

 $g_{\lambda}^{-}(a,b)=g(a,\,b+\lambda) \quad ext{and} \quad g_{\lambda}^{+}(a,b)=g(\,a-\lambda\,,b).$ 

Idea :  $g_{\lambda}^{\pm}$  "only see" the  $\mathscr{G}_{\lambda}^{1}$  part of the germ !

Then the scheme writes

$$\begin{aligned} \forall i \neq 0, 1 & u_i^{n+1} = u_i^n - \frac{\Delta t}{\Delta x} (g(u_i^n, u_{i+1}^n) - g(u_{i-1}^n, u_i^n)); \\ i = 0: & u_0^{n+1} = u_0^n - \frac{\Delta t}{\Delta x} (\boldsymbol{g}_{\lambda}^-(\boldsymbol{u}_0^n, \boldsymbol{u}_1^n) - g(\boldsymbol{u}_{-1}^n, \boldsymbol{u}_0^n)); \\ i = 1: & u_1^{n+1} = u_1^n - \frac{\Delta t}{\Delta x} (g(u_1^n, \boldsymbol{u}_2^n) - \boldsymbol{g}_{\lambda}^+(\boldsymbol{u}_0^n, \boldsymbol{u}_1^n)). \end{aligned}$$

$$u_{\Delta}(t,x) = \sum_{n \in \mathbb{N}} \sum_{i \in \mathbb{Z}} u_i^n \, \mathbb{1}_{(n \Delta t, (n+1)\Delta t)}(t) \, \mathbb{1}_{(x_{i-1/2}, x_{i+1/2})}(x).$$

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Numerical solution:

 $u_{\Delta}(t,x) = \sum_{n \in \mathbb{N}} \sum_{i \in \mathbb{Z}} u_i^n \, \mathbb{1}_{(n \Delta t, (n+1)\Delta t)}(t) \, \mathbb{1}_{(x_{i-1/2}, x_{i+1/2})}(x).$ 

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Under the CFL condition:  $2M\Delta t \leq \Delta x$ , (*M* being the Lipschitz constant of the numerical flux *g* on the *ad hoc* interval of values of  $(u_i^n)_{n,i}$ , the scheme writes

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#### Lemma (L<sup> $\infty$ </sup> bound — choice of *M* in the CFL condition)

Under the CFL condition, the scheme satisfies for all  $n \in \mathbb{N}$ ,  $i \in \mathbb{Z}$  $\min\{ \underset{\mathbb{R}^{-}}{\operatorname{ess inf}} u_0 - \lambda, \operatorname{ess inf}_{\mathbb{R}^+} u_0 \} \leqslant u_i^n \leqslant \max\{ \operatorname{ess sup}_{\mathbb{R}^-} u_0, \operatorname{ess sup}_{\mathbb{R}^+} u_0 + \lambda \}.$ 

#### Proposition (the scheme is (partially) well-balanced)

(i) The initial datum  $v_0(\cdot) = c(\cdot) = c_- \mathbb{1}_{\{x < 0\}} + c_+ \mathbb{1}_{\{x > 0\}},$   $(c_-, c_+) \in \mathscr{G}_{\lambda}^{\uparrow}$ , is exactly preserved in the evolution by the scheme . (ii) Let  $v_{\Delta}$  be the solution of the numerical scheme with the initial datum  $v_0(\cdot) = c(\cdot) = c_- \mathbb{1}_{\{x < 0\}} + c_+ \mathbb{1}_{\{x > 0\}},$  $(c_-, c_+) \in \mathscr{G}_{\lambda}^2$ . Then  $v_{\Delta}$  converge to c in  $L^{\uparrow}_{loc}(\mathbb{R}^+ \times \mathbb{R})$  as  $\Delta x \to 0$ .

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#### Lemma ( $BV_{loc}$ bound,

Let T > 0 and A > 0. Assume that  $u_0 \in BV(\mathbb{R})$  and  $\Delta x$  is small enough. Then, under the CFL condition and assumption (H), we have

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– estimate in  $BV(0, T; L^1(\mathbb{R}))$  (i.e., time *BV* estimate in the mean ) from translation invariance + contraction (use Crandall-Tartar lemma + (H))

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# Proposition (approximate Kato inequality)

Let  $u_{\Delta}, v_{\Delta}$  be solutions of the scheme. Let  $\varphi \in \mathcal{D}([0, T) \times \mathbb{R}), \varphi \ge 0$ . Then  $-\int_{\mathbb{R}^+} \int_{\mathbb{R}} ((u_{\Delta} - v_{\Delta})^+ \partial_t \varphi + \Phi^+(u_{\Delta}, v_{\Delta}) \partial_x \varphi) \leqslant \operatorname{Rem}(\Delta x, \varphi).$ 

Arguments: monotonicity of the scheme, consistency , the  $BV_{loc}$  in space bound

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#### Proposition (approximate Kato inequality)

Let  $u_{\Delta}, v_{\Delta}$  be solutions of the scheme. Let  $\varphi \in \mathcal{D}([0, T) \times \mathbb{R}), \varphi \ge 0$ . Then  $-\int_{\mathbb{R}^+} \int_{\mathbb{R}} ((u_{\Delta} - v_{\Delta})^+ \partial_t \varphi + \Phi^+(u_{\Delta}, v_{\Delta}) \partial_x \varphi) \leqslant \operatorname{Rem}(\Delta x, \varphi).$ 

In what follows, we need a technical hypothesis (dissipativity at x = 0):

(H)  $\partial_a(\partial_a g(a,b) + \partial_b g(a,b)) \ge 0$ ,  $\partial_b(\partial_a g(a,b) + \partial_b g(a,b)) \ge 0$ ;

Lemma ( *BV<sub>loc</sub>* bound, Bürger, García, Karlsen, Towers )

Let T > 0 and A > 0. Assume that  $u_0 \in BV(\mathbb{R})$  and  $\Delta x$  is small enough. Then, under the CFL condition and assumption (H), we have

 $\|u_{\Delta}(\cdot,\cdot)\|_{BV([0,T]\times\mathbb{R}\setminus(-A,A))} \leqslant \frac{1}{A}Const(T,\|u_0\|_{\mathbf{L}^{\infty}},\|u_0\|_{BV(\mathbb{R})},\lambda).$ 

– estimate in  $BV(0, T; L^1(\mathbb{R}))$  (i.e., time *BV* estimate in the mean ) from translation invariance + contraction (use Crandall-Tartar lemma + **(H)**)

- mean-value theorem: for some  $r \in (0, A)$ ,  $||u(\cdot, \pm r)||_{BV(0,T)} \leq const/A$
- look at our solution as solution to a Cauchy-Dirichlet problem with *BV* initial and boundary data.

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Assume  $u_0 \in L^{\infty}(\mathbb{R})$ . Then, under the CFL condition and assumption (H), the numerical scheme converges in  $L^1_{loc}(\mathbb{R}^+ \times \mathbb{R})$  to the unique entropy solution to "Burgers with particle-at-zero" problem when  $\Delta x$  tends to 0.

In particular, the problem is well-posed , for  $L^{\infty}$  data and  $L^{1}_{loc}$  topology.

#### Proof.

• First assume that  $u_0 \in BV(\mathbb{R})$ .

- $BV_{loc}$  bounds yield compactness: we get u an accumulation point of  $(u_{\Delta})_{\Delta}$ ; - well-balance property for  $(c_{-}, c_{+}) \in \mathscr{G}_{1}^{1} \cup \mathscr{G}_{2}^{2}$  yields enough explicit
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# COUPLED PROBLEM

#### Theorem (well-posedness for moving but decoupled particle)

Given  $h(\cdot) a C^1$  path, there exists a unique entropy solution to the Burgers equation with singular drag term  $-\lambda (u - h'(t))\delta_0(x - h(t))$ ; (localized)  $L^1$  contraction property holds.

#### Definition :

- the germ  $\mathscr{G}_{\lambda}$  changes into  $(h'(t), h'(t)) + \mathscr{G}_{\lambda}$ ;

– versions **B.** ("with traces") and **D.** ("adapted entropy inequalities with remainder term") permit to define entropy solutions.

#### Arguments :

- for uniqueness, comparison, L<sup>1</sup> contraction: same technique;
- for existence: use characterization D. (it is stable by passage to the limit!);
- approximate  $h(\cdot)$  by a family  $(h_n)_n$  of piecewise affine paths
- construction of solutions for "particle at  $h_n$ " is straightforward:  $h'_n$  being piecewise constant, one changes variables to reduce to the "drag force-at-zero" case. Procedure restarted at each time where  $h'_n$  jumps.

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#### Theorem (well-posedness for moving but decoupled particle)

Given  $h(\cdot) = C^1$  path, there exists a unique entropy solution to the Burgers equation with singular drag term  $-\lambda (u - h'(t))\delta_0(x - h(t))$ ; (localized)  $L^1$  contraction property holds.

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Uniqueness proof for the coupled problem relies on a Gronwall inequality, which in turn relies on a Lipschitz dependence estimate for the map  $h(\cdot) \mapsto u(\cdot, \cdot)$ .

#### Theorem (dependence of u on the path $h(\cdot)$ )

Assume  $u, \hat{u}$  are entropy solutions corresponding to the particles located at  $h(\cdot), \hat{h}(\cdot)$ , respectively, with  $h(0) = 0 = \hat{h}(0)$  and same initial datum  $u_0$ . Assume  $\hat{u} \in L^{\infty}(0, T; BV(\mathbb{R}))$ . Then for a.e.  $t \in (0, T)$ ,

$$\|u(t,\cdot)-\hat{u}(t,\cdot)\|_{L^1(\mathbb{R})}\leqslant C(\|u\|_{\infty},\|\hat{u}\|_{\infty},\|\hat{u}\|_{BV},\lambda)\int_{0}^{t}|h'(s)-\hat{h}'(s)|\,ds.$$

Arguments:

- change of variables y = x - h(t), resp. x - h'(t). Two eqns, both with singularity at zero, come out, with different fluxes of the kind  $u \mapsto \frac{u^2}{2} - h'(t)u$ . - use the techniques of dependence of entropy solutions on the flux function (*BV* regularity needed!): Kuznetsov, Bouchut-Perthame, Karlsen-Risebro... : the  $C^1$  norm of the difference of the fluxes pops up, which yields  $|h' - \hat{h}'|$ - use Lipschitz dependence of the germ on h' to describe additional (small) "non-dissipation" term coming from the interface.

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# Case h = h(t): continuous dependence en $h(\cdot)$ , $L^{\infty}$ and BV stability

#### **Proposition (BV estimate)**

The solution constructed for the h = 0 case obeys  $\|u(t, \cdot)\|_{BV(\mathbb{R})} \searrow$  for all t > 0

(at t = 0 the variation may increase by a const. depending on  $||u_0||_{\infty}, \mathscr{G}_{\lambda}$ ).

The solution constructed for the fixed- $h(\cdot)$  case obeys the BV estimate

 $\|u(t,\cdot)\|_{BV(\mathbb{R})} \leq \|u_0\|_{BV(\mathbb{R})} + const(\lambda, \|u_0\|_{\infty}) + 2 \int \|h''(s)\| ds$ 

Argument: (re)-construct solutions by wave-front tracking algorithm (Dafermos, Holden-Risebro, Bressan et al.) (better control of interactions).

#### Lemma (L $^{\infty}$ bounds)

We get a uniform  $L^{\infty}$  bound on ad hoc sequences of  $h'(\cdot)$  and  $u(\cdot, \cdot)$ .

To be precise: if we look at solutions to the coupled problem, we get  $\max\{||u||_{\infty}, ||h'||_{\infty}\} \leq \max\{||u_0||_{\infty}, |h'(0)|\}.$ 

For solutions appearing in the fixed-point or splitting arguments, we get somewhat weaker bounds.

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To be precise: if we look at solutions to the coupled problem, we get  $\max\{||u||_{\infty}, ||h'||_{\infty}\} \leq \max\{||u_0||_{\infty}, |h'(0)|\}.$ 

For solutions appearing in the fixed-point or splitting arguments, we get somewhat weaker bounds.

# Case h = h(t): continuous dependence en $h(\cdot)$ , $L^{\infty}$ and BV stability

#### **Proposition (BV estimate)**

The solution constructed for the h = 0 case obeys

 $\|u(t,\cdot)\|_{BV(\mathbb{R})} \searrow \text{ for all } t > 0$ 

(at t = 0 the variation may increase by a const. depending on  $||u_0||_{\infty}, \mathscr{G}_{\lambda}$ ).

The solution constructed for the fixed-h( $\cdot$ ) case obeys the BV estimate

 $\|u(t,\cdot)\|_{BV(\mathbb{R})} \leqslant \|u_0\|_{BV(\mathbb{R})} + const(\lambda, \|u_0\|_{\infty}) + 2\int_{0}^{t} |h''(s)| \, ds.$ 

Argument: (re)-construct solutions by wave-front tracking algorithm (Dafermos, Holden-Risebro, Bressan et al.) (better control of interactions).

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#### Case of *u* frozen: evolving $h = h(\cdot)$

Proposition (modelling/"traces" interpretation of the ODE on  $h(\cdot)$  )

For every drag force, the ODE in the coupled problem writes

$$mh''(t) = \left( (u_{-})^2/2 - h'(t)u_{-} \right) - \left( (u_{+})^2/2 - h'(t)u_{+} \right)$$

Notice that the right-hand side above is expressed as the difference of the normal components of the 2D-field  $(u, u^2/2)$  on the curve  $\{x = h(t)\}$  from the left and from the right. Combining this observation with the Green-Gauss formula, we get the following weak formulation of the ODE:

#### Lemma (second interpretation of the ODE on $h(\cdot)$ )

Let u be a weak solution of the PDE on  $\{x \neq h(t)\}$ ; let  $h \in W^{2,\infty}(0,T)$ . Then  $h(\cdot)$  verifies the ODE if and only if for all  $\xi \in \mathcal{D}([0,T))$ , for all  $\psi \in \mathcal{D}(\mathbb{R})$  such that  $\psi \equiv 1$  on the set  $\{x \in \mathbb{R} : \exists t \in [0,T] \text{ such that } h(t) = x\}$ , there holds

$$-m\int_0^T h'(t)\xi'(t)dt = mh'(0)\xi(0) + \int_0^T \int_{\mathbb{R}} \left[u\psi\xi_t + \frac{u^2}{2}\xi\psi_x\right] + \int_{\mathbb{R}} u_0\psi\xi(0).$$

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#### The above ingredients can be used in several ways:

- In a fixed-point argument  $h(\cdot) \mapsto u(\cdot, \cdot) \mapsto h(\cdot)$ (compactness: work in  $C^1([0, T])$ , exploit a  $W^{2,\infty}(0, T)$  bound on  $h(\cdot)$ )

– In a time splitting algorithm (alternatively evolving *u* and *h* on small time intervals):

- *u* updated from *h* using the theory of entropy solutions for *h* frozen;
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In a numerical scheme (same time splitting + approximation in space of the conservation law); an interesting possibility is the random-choice algorithm (Glimm), in order not to adapt the space meshing to the particle location.

#### Theorem (Main result)

For all BV datum  $u_0$  and given h(0), h'(0), there exists a unique entropy solution to the coupled problem.

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#### Coupled problem: a well-balanced random-choice numerical scheme

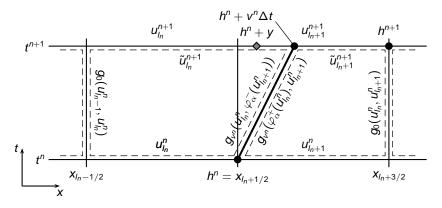


Figure: Representation of the algorithm based on the well-balanced scheme.

# Numerics: drafting-kissing-tumbling

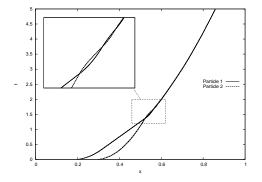


Figure: Trajectories of two particles

### Thx !!!

# THANK YOU !