

Analysis of Discontinuous Galerkin Methods for Fractional Conservation Laws and Related Equations

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Joint work with Simone Cifani (Trondheim) & Espen Jakobsen (Trondheim)

Fractional degen convection-diffusion equations

$$\begin{cases} u_t + f(u)_x = (a(u)u_x)_x + b\mathcal{L}[u], \\ u(x, 0) = u_0(x) \end{cases}$$

$f, a : \mathbb{R} \rightarrow \mathbb{R}$, $a \geq 0$ bounded, Lipschitz continuous

$b \geq 0$ is a constant, and \mathcal{L} is a nonlocal operator

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\mathcal{L} is fractional Laplacian:

$$\mathcal{L}[\widehat{u(\cdot, t)}](\xi) = -|\xi|^\lambda \hat{u}(\xi, t).$$

$$\lambda \in (0, 1)$$

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Another way to represent \mathcal{L} (Landkof [72])

$$\mathcal{L}[u(x, t)] = c_\lambda \int_{|z|>0} \frac{u(x+z, t) - u(x, t)}{|z|^{1+\lambda}} dz.$$

\mathcal{L} is fractional Laplacian:

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$$u_t + f(u)_x = (a(u)u_x)_x + b\mathcal{L}[u],$$

Pseudodifferential operator \mathcal{P} with a symbol $a(\omega) \geq 0$:

$$\widehat{\mathcal{P}v}(\omega) = a(\omega)\widehat{v}(\omega)$$

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Lévy-Khintchine formula

$$a(\omega) = ib \cdot \omega + q(\omega) + \int_{\mathbb{R}^d \setminus \{0\}} \left(1 - e^{-iz \cdot \omega} - iz \cdot \omega \mathbf{1}_{|z| < 1}(z) \right) \pi(dz),$$

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↑
drift

↑
diffusion

↑
jump (Lévy) part

↑
Lévy measure

$$\lambda \in (0, 1)$$

Special cases

Fractional diffusion equation

$$u_t = -(-\Delta)^\gamma, \quad \gamma \in (0, 1). \quad u|_{t=0} = u_0.$$

Solution given by Greens' function! Solution is smooth ...

Conservation laws $u_t + f(u)_x = 0$

Discontinuous solutions, shock waves

Weak solutions, entropy conditions

Conservation laws $u_t + f(u)_x = 0$

Discontinuous solutions, shock waves

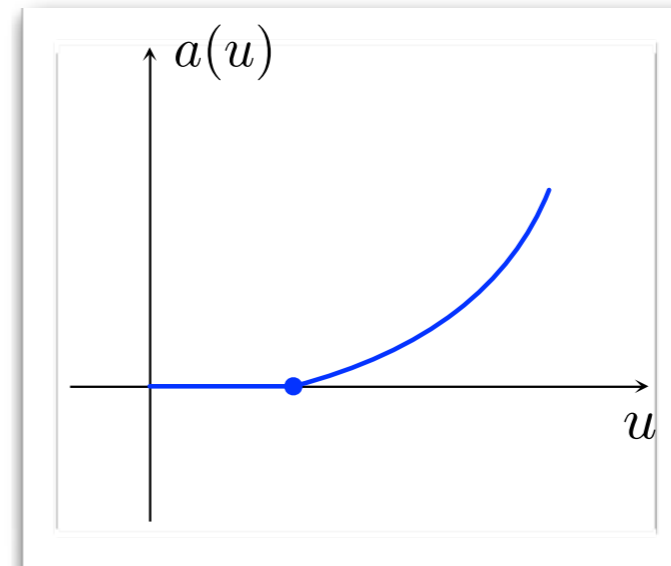
Weak solutions, entropy conditions

For all convex η with $q' = \eta' f'$

$$\partial_t \eta(u) + \partial_x q(u) \leq 0 \quad \text{weakly}$$

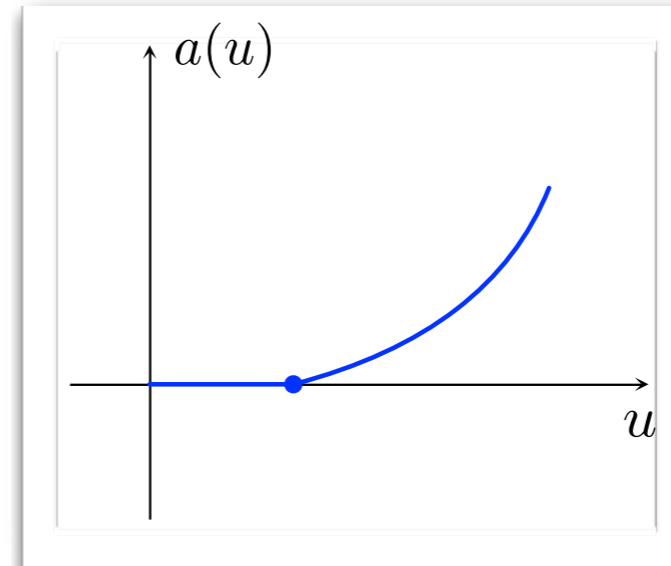
Mixed hyperbolic-parabolic

$$u_t + f(u)_x = (a(u)u_x)_x.$$



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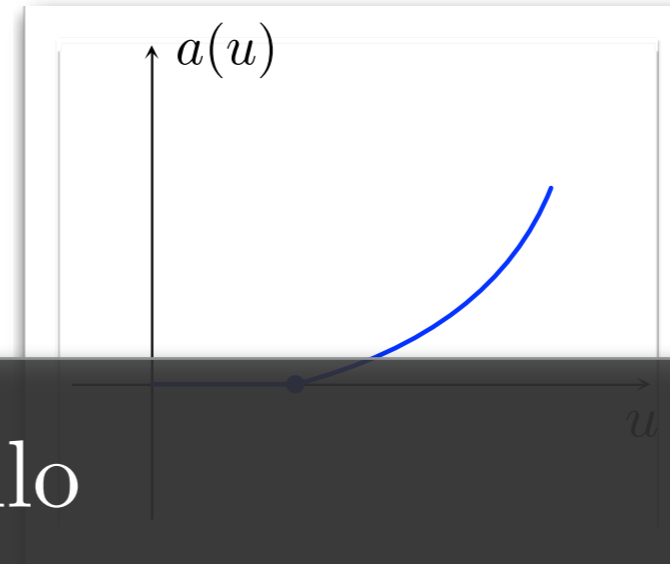
For all convex η with $q' = \eta' f'$, $r' = \eta' a$

$$\partial_t \eta(u) + \partial_x q(u) \leq \partial_x^2 r(u) - \eta''(u) a(u) (\partial_x u)^2 \quad \text{weakly}$$

Well-posedness theory in $L^1 \cap L^\infty$ of existence, uniqueness,
 L^1 contraction of entropy solutions ... (Carillo ...)

Mixed hyperbolic-parabolic

$$u_t + f(u)_x = (a(u)u_x)_x.$$



Entropy solution ala Carrillo

- $u \in L_t^\infty(L_x^1) \cap L^\infty \cap C_t(L_x^1)$
- $\nabla A(u) \in L^2 \quad A = \int a$
- $\partial_t |u - k| + \partial_x (\text{sgn}(u - k)(f(u) - f(k)))$
 $\quad - \text{sgn}(u - k) \partial_x A(u) \leq 0 \quad \text{weakly}$

Regularity issues for fractional Burgers equation

$$\partial_t u + \partial_x (u^2 / 2) = -(-\Delta)^\lambda u,$$

Subcritical ($\lambda > 1/2$), critical ($\lambda = 1/2$) cases:

solutions smooth in $t > 0$

(Droniou-Gallouet-Vovelle, Kiselev-Nazarov-Shterenberg
Chan-Czubak, Dong-Du-Li, ...)

[many parallel results quasi-geostrophic equation,
Kiselev et al., Caffarelli-Vasseur, ...]

Regularity issues for fractional Burgers equation

$$\partial_t u + \partial_x (u^2 / 2) = -(-\Delta)^\lambda u,$$

Supercritical case ($\lambda < 1/2$):

singularities indeed occur

(Alibaud-Droniou-Vovelle, Kiselev-Nazarov-Shterenberg, Dong-Du-Li)

—————> Weak (distributional) solutions

Regularity issues for fractional Burgers equation

$$\partial_t u + \partial_x (u^2 / 2) = -(-\Delta)^\lambda u,$$

Weak solution: $u \in L^\infty$

Supercritical case ($\lambda < 1/2$):

$$\iint u \partial_t \phi + \frac{u^2}{2} \partial_x \phi - u (-\Delta)^\lambda [\phi] dx dt = 0, \quad \forall \phi \in C_c^\infty$$

+ initial condition $u_0 \in L^\infty$ (Alibaud, Mikulevicius-Nazarov-Shterenberg, Dong-Du-Li)

→ Weak (distributional) solutions

Entropy solutions for fractional PDE

Conservation laws

$$u_t + f(u)_x = \mathcal{L}[u]$$

$$\mathcal{L}[u](t, x) = \int_{\mathbb{R} \setminus \{0\}} [u(t, x + z) - u(t, x) - z \partial_x u \mathbf{1}_{|z| < 1}] \pi(dz)$$

Viscosity regularized version

$$\partial_t u_\rho + \partial_x f(u_\rho) = \mathcal{L}[u_\rho(t, \cdot)] + \rho \Delta u_\rho, \quad \rho > 0.$$

Fix convex entropy η , entropy-flux q by $q' = \eta' f'$. Then

$$\partial_t \eta(u_\rho) + \partial_x q(u_\rho) = \mathcal{L}[\eta(u_\rho)] + \rho \Delta \eta(u_\rho) - \nu_\rho,$$

where $\nu_\rho = \nu_\rho^1 + \nu_\rho^2 + \nu_\rho^3$ consists of three parts:

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Entropy dissipation term

$$\nu_\rho^1 := \rho \Delta \eta(u_\rho) - \rho \eta'(u_\rho) \Delta u_\rho = \rho \eta''(u_\rho) |\nabla u_\rho|^2 ;$$

Fix convex entropy η , entropy-flux q by $q' = \eta' f'$. Then

$$\partial_t \eta(u_\rho) + \partial_x q(u_\rho) = \mathcal{L}[\eta(u_\rho)] + \rho \Delta \eta(u_\rho) - \nu_\rho,$$

where $\nu_\rho = \nu_\rho^1 + \nu_\rho^2 + \nu_\rho^3$ consists of three parts:

Fractional parabolic dissipation term

$$\nu_\rho^3 = \int_{\mathbb{R}^d \setminus \{0\}} \overline{\eta''}(u_\rho; z) (u_\rho(t, x + z) - u_\rho(t, x))^2 \pi(dz),$$

$$\overline{\eta''}(u_\rho; z) = \int_0^1 (1 - \tau) \eta''((1 - \tau)u_\rho(t, x) + \tau u_\rho(t, x + z)) d\tau$$

Fix convex entropy η , entropy-flux q by $q' = \eta' f'$. Then
 The commutator $\mathcal{L}[\eta(u_\rho)] - \eta'(u_\rho)\mathcal{L}[u_\rho]$ equals ν_ρ^3 , since

$$\eta(b) - \eta(a) = \eta'(a)(b - a) + \left(\int_0^1 (1 - \tau)\eta''((1 - \tau)a + \tau b) d\tau \right) (b - a)^2.$$

Fractional parabolic dissipation term

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Entropy solution $u \in L^\infty$ is an entropy solution if

\forall convex entropies η , entropy-fluxes q , $q' = \eta' f$

$$\partial_t \eta(u) + \partial_x q(u) \leq \mathcal{L}[\eta(u)] - m^{u,\eta} \quad \text{weakly}$$

$$m^{u,\eta} = \int_{\mathbb{R} \setminus \{0\}} \overline{\eta''}(u; z) (u(t, x + z) - u(t, x))^2 \pi(dz),$$

Entropy solution $\phi = \phi(t, x) \in C_c^\infty$ $u \in L^\infty$ is an entropy solution if

Can replace the term $\iint_{Q_T} \left(\eta(u) \mathcal{L}[\varphi] - m^{u, \eta} \right) dx dt$ by

$$\iint_{Q_T} \int_{|z| < r} \eta(u) [\varphi(t, x+z) - \varphi(t, x) - \nabla \varphi \cdot z] \pi(dz) dx dt,$$

$$+ \iint_{Q_T} \int_{|z| \geq r} \eta'(u) [u(t, x+z) - u(t, x)] \pi(dz) dx dt, \quad \forall r \in (0, 1),$$

Entropy formulation due to Alibaud (existence, uniqueness, etc.)

$$\partial_t \eta(u) + \partial_x q(u) \leq \mathcal{L}[\eta(u)] - m^{u, \eta} \quad \text{weakly}$$

$$m^{u, \eta} = \int_{\mathbb{R} \setminus \{0\}} \overline{\eta''}(u; z) (u(t, x+z) - u(t, x))^2 \pi(dz),$$

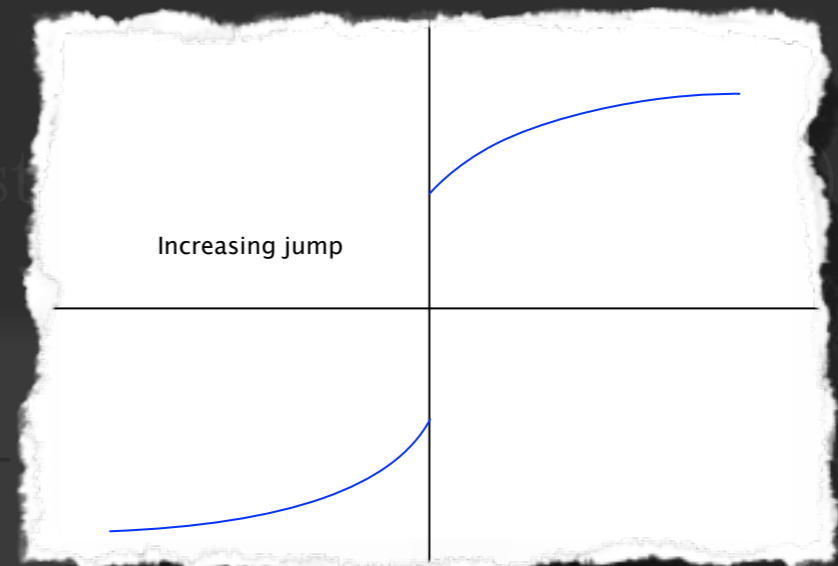
Entropy solution: $\phi = \phi(t, x) \in C_c^\infty$ $u \in L^\infty$ is an entropy solution if

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Not all weak solutions are entropy solutions !

Alibaud-Andreianov construct
a stationary weak solution
violating Oleinik's E condition



$$m^{u, \eta} = \int_{\mathbb{R} \setminus \{0\}} \overline{\eta''}(u; z) (u(t, x+z) - u(t, x))^2 \pi(dz),$$

Fractional convection-diffusion equations

$$u_t + f(u)_x = (a(u)u_x)_x + \mathcal{L}[u], \quad a \geq 0$$

$u \in L^\infty \cap L^1$ is an entropy solution if

\forall convex entropies η , entropy-fluxes q, r , $q' = \eta' f$, $r' = \eta' a$

$$\partial_t \eta(u) + \partial_x q(u) \leq \partial_x^2 r(u) - \eta''(u) a(u) (\partial_x u)^2 + \mathcal{L}[\eta(u)] - m^{u,\eta}$$

$$m^{u,\eta} = \int_{\mathbb{R} \setminus \{0\}} \overline{\eta''}(u; z) (u(t, x+z) - u(t, x))^2 \pi(dz),$$

(Chen-Perthame, Bendahmane-K, Ulusoy-K)

Uniqueness, stability, continuous dependence (Ulusoy-K) ...

$$\partial_t u + \operatorname{div} f(u) = \operatorname{div}(a(u) \nabla u) + \mathcal{L}[u], \quad u|_{t=0} = u_0$$

$$\partial_t v + \operatorname{div} \tilde{f}(v) = \operatorname{div}(\tilde{a}(v) \nabla v) + \tilde{\mathcal{L}}[v], \quad v|_{t=0} = v_0$$

$$\mathcal{L}[u] = \int [u(t, x+z) - u(t, x) - z \cdot \nabla_x u \mathbf{1}_{|z|<1}] \pi(dz), \quad \pi(dz) = m(z) dz$$

$$\tilde{\mathcal{L}}[v] = \int [v(t, x+z) - v(t, x) - z \cdot \nabla_x v \mathbf{1}_{|z|<1}] \tilde{\pi}(dz), \quad \tilde{\pi}(dz) = \tilde{m}(z) dz$$

Assume: $u \in L^\infty(0, T; BV(\mathbb{R}^d))$ entropy solution

with BV data $u_0 \in L^1 \cap L^\infty \cap BV$

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$$\partial_t v + \operatorname{div} \tilde{f}(v) = \operatorname{div}(\tilde{a}(v) \nabla v) + \tilde{\mathcal{L}}[v], \quad v|_{t=0} = v_0$$

$$\|u(t, \cdot) - v(t, \cdot)\|_{L^1(\mathbb{R}^d)} \leq \|u_0 - v_0\|_{L^1(\mathbb{R}^d)} + C_1 t \|f - \tilde{f}\|_{W^{1,\infty}(I; \mathbb{R}^d)} + C_2 \sqrt{t} \|\sqrt{a} - \sqrt{\tilde{a}}\|_{L^\infty(I; \mathbb{R}^{d \times K})}$$

$$\mathcal{L}[u] = \int [u(t, x+z) - u(t, x) - z \cdot \nabla_x u \mathbf{1}_{|z|<1}] \pi(dz), \quad \pi(dz) = m(z) dz$$

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$$+ C_3 \sqrt{t} \sqrt{\left(\int_{|z|<1} |z|^2 |m(z) - \tilde{m}(z)| dz \right)}$$

Assume: $u \in L^\infty(0, T; BV(\mathbb{R}^d))$ entropy solution with BV data $u_0 \in L^1 \cap L^\infty \cap BV$

$$+ C_4 t \int_{|z| \geq 1} |z| |m(z) - \tilde{m}(z)| dz,$$

1D entropy solutions in BV class

$$u_t + f(u)_x = (a(u)u_x)_x + \mathcal{L}[u], \quad a \geq 0$$

$$\mathcal{L}[u(x, t)] = c_\lambda \int_{|z|>0} \frac{u(x+z, t) - u(x, t)}{|z|^{1+\lambda}} dz, \quad \lambda \in (0, 1)$$

$u \in L^\infty(Q_T)$ is *BV* entropy solution if $(Q_T = (0, T) \times \mathbb{R})$

- $u \in L^\infty(0, T; L^1(\mathbb{R})) \cap BV(Q_T)$;
- $A(u) \in C^{1, \frac{1}{2}}(Q_T)$; $A = \int^u a$;
- Kruzkov-type entropy condition

1D entropy solutions in BV class

$$\forall 0 \leq \varphi \in C_c^\infty(\mathbb{R} \times [0, T)), \forall k \in \mathbb{R},$$

$$\iint_{Q_T} |u - k| \varphi_t + q_k(u) \varphi_x + r_k(u) \varphi_{xx}$$

$$+ \operatorname{sgn}(u - k) \mathcal{L}[u] \varphi \, dx dt$$

$u \in L^\infty(Q_T)$ is BV entropy solution if $(Q_T = (0, T) \times \mathbb{R})$

$$+ \int_{\mathbb{R}} |u_0 - k| \varphi(0, x) \, dx \geq 0$$

- $u \in L^\infty(0, T; L^1(\mathbb{R})) \cap BV(Q_T)$;

$$q_k(u) = \operatorname{sgn}(u - k)(f(u) - f(k)) \quad r_k(u) = |A(u) - A(k)|$$

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1D entropy solutions in BV class

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$$+ \operatorname{sgn}(u - k) \mathcal{L}[u] \varphi \, dx dt$$

$u \in L^\infty(Q_T)$ is BV entropy solution if $(Q_T = (0, T) \times \mathbb{R})$

Finite since u is BV $+ \int_{\mathbb{R}} |u_0 - k| \varphi(0, x) \, dx \geq 0$

$$q_k(u) = \operatorname{sgn}(u - k)(f(u) - f(k)) \quad r_k(u) = |A(u) - A(k)|$$

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Numerical approximation

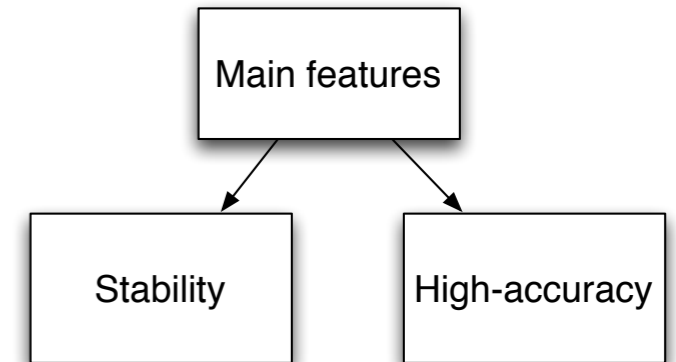
- Vast literature for nonlocal linear equations (finance applications)
- Nonlinear convection of compressible radiating fluids (Dedner-Rohde)
- Fractional conservation laws (Droniou)
 - convergence of monotone FV method
- Fractional conservation laws / convection-diffusion (Cifani-Jakobsen-K)
 - discontinuous Galerkin methods

Discontinuous Galerkin (DG) methods

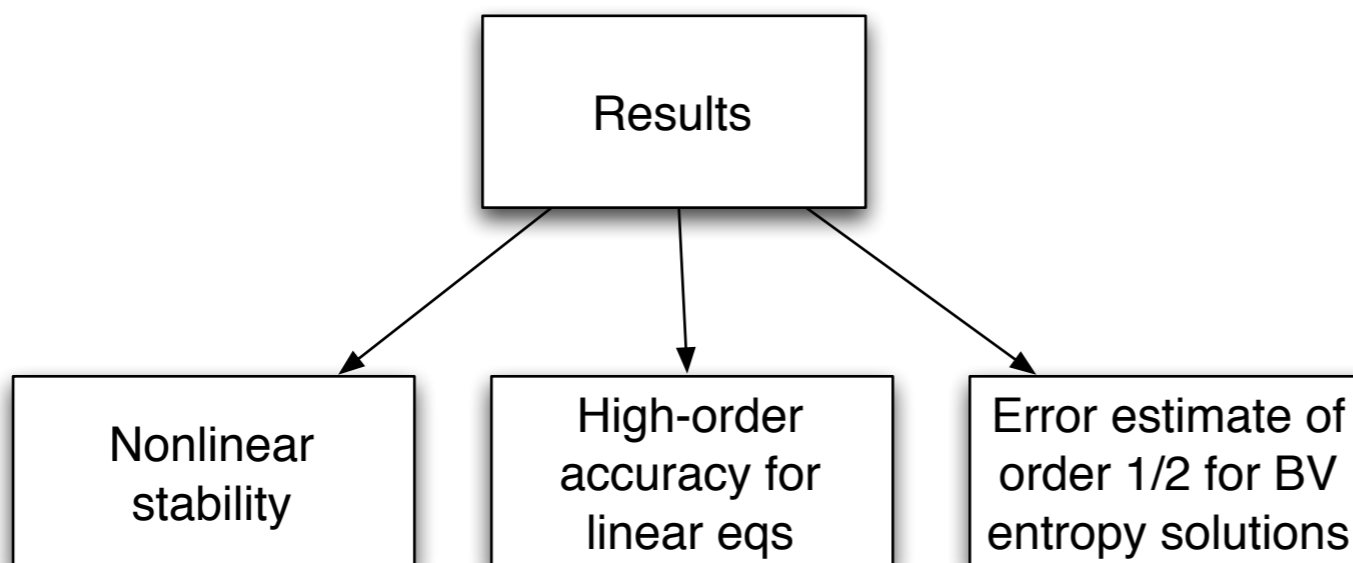
- Well established for the pure conservation law

$$\partial_t u + \partial_x f(u) = 0$$

(Cockburn-Shu + many other names)



- Aim is to extend to fractional CL / conv-diff



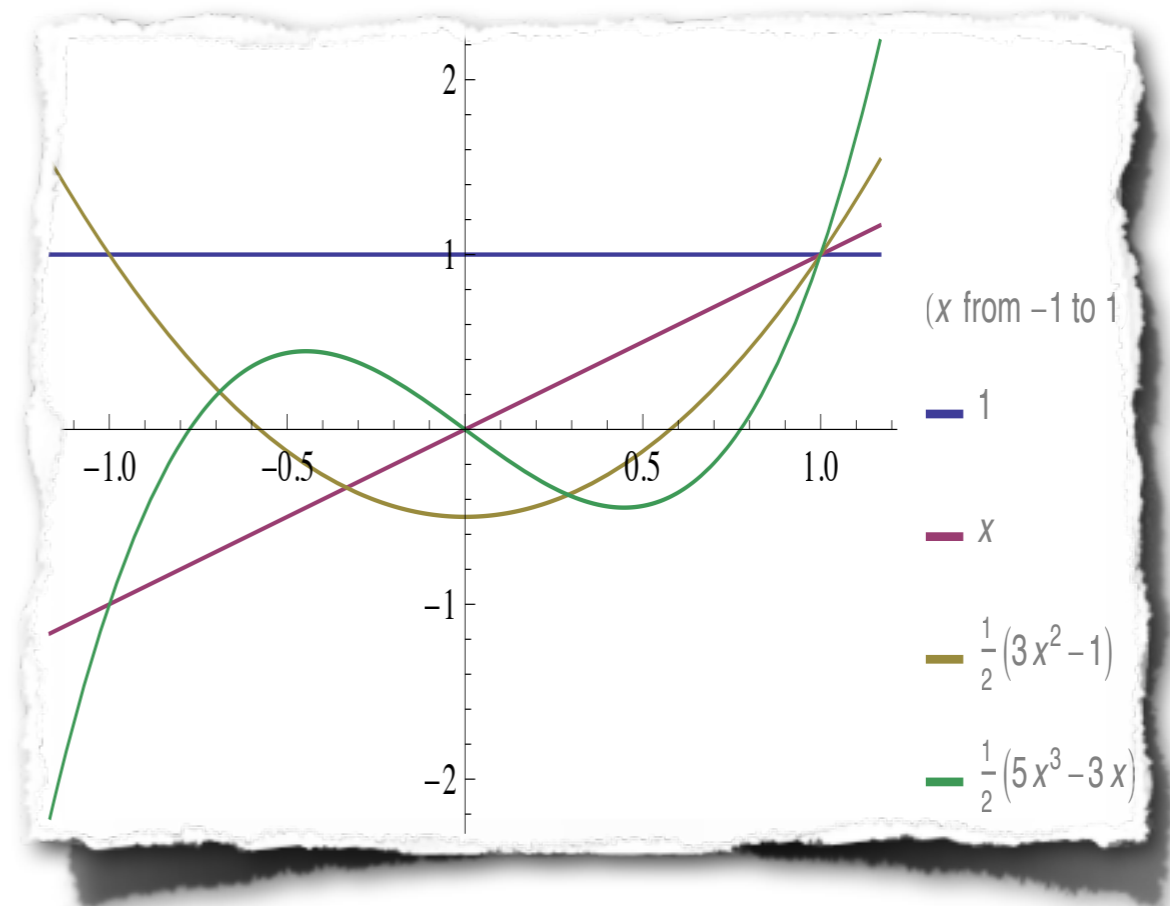
A semi-discrete DG method

- Spatial grid $x_i = i\Delta x$, $i \in \mathbb{Z}$; $I_i = (x_i, x_{i+1})$
- $P^k(I_i)$ polynomials of degree k

Orthogonal basis - Legendre polynomials

$$\{\varphi_{0,i}, \varphi_{1,i}, \dots, \varphi_{k,i}\},$$

$$\varphi_{j,i} \in P^j(I_i) \quad j = 0, \dots, k$$



- Multiply $u_t + f(u)_x = \mathcal{L}[u]$ by a $\varphi \in P^k(I_i)$,
 \int over the interval I_i and integrate by parts

Replace f by (consistent, monotone) numerical flux F

$$\int_{I_i} u_t \varphi - \int_{I_i} f(u) \varphi_x + F(u_{i+1}) \varphi(x_{i+1}^-) - F(u_i) \varphi(x_i^+) = \int_{I_i} \mathcal{L}[u] \varphi.$$

- Determine $\tilde{u}(x, t) = \sum_{i \in \mathbb{Z}} \sum_{p=0}^k U_{p,i}(t) \varphi_{p,i}(x)$,

such that equation holds $\forall \varphi \in P^k(I_i)$, $i \in \mathbb{Z}$.

• Multi-

$\int_{I_i} u$

Rep

$\int_{I_i} u$

(i) The Godunov flux:

$$\hat{f}^G(a, b) = \begin{cases} \min_{a \leq u \leq b} f(u), & \text{if } a \leq b \\ \max_{b \leq u \leq a} f(u), & \text{otherwise} \end{cases}$$

(ii) The Engquist–Osher flux:

$$\hat{f}^{EO}(a, b) = \int_0^b \min(f'(s), 0) ds + \int_0^a \max(f'(s), 0) ds + f(0)$$

(iii) The Lax–Friedrichs flux:

$$\hat{f}^{LF}(a, b) = \frac{1}{2} [f(a) + f(b) - C(b - a)]$$

$$C = \max_{\inf u^0(x) \leq s \leq \sup u^0(x)} |f'(s)|$$

• Det

flux F

(x_i^+)

such that equation holds $\forall \varphi \in P^k(I_i), i \in \mathbb{Z}$.

- Multiply $u_t + f(u)_x = \mathcal{L}[u]$ by a $\varphi \in P^k(I_i)$,
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Replace f by (consistent, monotone) numerical flux F

$$\int_{I_i} u_t \varphi - \int_{I_i} f(u) \varphi_x + F(u_{i+1}) \varphi(x_{i+1}^-) - F(u_i) \varphi(x_i^+) = \int_{I_i} \mathcal{L}[u] \varphi.$$

- Determine $\tilde{u}(x, t) = \sum_{i \in \mathbb{Z}} \sum_{p=0}^k U_{p,i}(t) \varphi_{p,i}(x),$

such that equation holds $\forall \varphi \in P^k(I_i), i \in \mathbb{Z}.$

- Multiply $u_t + f$ by Lemma: For $\varphi, \phi \in L^1(\mathbb{R}) \cap BV(\mathbb{R})$.

\int over the interval I_i and integrate by parts

$$\int_{\mathbb{R}} \varphi \mathcal{L}[\phi] dx = \int_{\mathbb{R}} \mathcal{L}[\varphi] \phi dx$$

Replace f by (consistent, monotone) numerical flux F

$$\begin{aligned} \int_{I_i} u_t \varphi - \int_{I_i} f(u) \varphi_x + F(u_{i+1}) \varphi(x_{i+1}^-) - F(u_i) \varphi(x_i^+) \\ = \int_{I_i} \mathcal{L}[u] \varphi. \end{aligned}$$

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such that equation holds $\forall \varphi \in P^k(I_i), i \in \mathbb{Z}.$

- Multiply $u_t + f(u)_x = \mathcal{L}[u]$ by a $\varphi \in P^k(I_i)$,
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$$\int_{I_i} u_t \varphi - \int_{I_i} f(u) \varphi_x + F(u_{i+1}) \varphi(x_{i+1}^-) - F(u_i) \varphi(x_i^+) = \int_{I_i} \mathcal{L}[u] \varphi.$$

- Determine $\tilde{u}(x, t) = \sum_{i \in \mathbb{Z}} \sum_{p=0}^k U_{p,i}(t) \varphi_{p,i}(x),$

such that equation holds $\forall \varphi \in P^k(I_i), i \in \mathbb{Z}.$

- Properties of Legendre polynomials $\in P^k(I_i)$,
 $\forall q = 0, \dots, k$ and $i \in \mathbb{Z}$,

$$\frac{\Delta x}{2q+1} \frac{d}{dt} U_{q,i} = \int_{I_i} f(\tilde{u}) \frac{d}{dx} \varphi_{q,i} + (-1)^q F(\tilde{u}_i) - F(\tilde{u}_{i+1})$$

$$+ \int_{I_i} \mathcal{L}[\tilde{u}] \varphi_{q,i},$$

$$= \int_{I_i} \mathcal{L}[u] \varphi_{q,i}.$$

$$U_{q,i}(0) = \frac{2q+1}{\Delta x} \int_{I_i} u_0(x) \varphi_{q,i}(x) dx.$$

- Determine $\tilde{u}(x, t) = \sum_{i \in \mathbb{Z}} \sum_{p=0}^k U_{p,i}(t) \varphi_{p,i}(x)$,

Time discretizations: Explicit, Runge–Kutta methods
 such that equation holds $\forall \varphi \in P^k(I_i), i \in \mathbb{Z}$.

Existence/uniqueness of solutions

- Properties of $U_{q,i}$ in $C^1([0, T]; V^k \cap L^2(\mathbb{R}))$ by Picard-Cauchy-Lipschitz theorem.
 $\forall q = 0, \dots, k$

$$\frac{\Delta x}{2q+1} \frac{d}{dt} U_{q,i} = \int_{I_i} f(\tilde{u}) \frac{d}{dx} \varphi_{q,i} + (-1)^q F(\tilde{u}_i) - F(\tilde{u}_{i+1})$$

$$+ \int_{I_i} \mathcal{L}[\tilde{u}] \varphi_{q,i},$$

$$U_{q,i}(0) = \frac{2q+1}{\Delta x} \int_{I_i} u_0(x) \varphi_{q,i}(x) dx.$$

- Determine $\tilde{u}(x, t) = \sum_{i \in \mathbb{Z}} \sum_{p=0}^k U_{p,i}(t) \varphi_{p,i}(x),$

Time discretizations: Explicit, Runge-Kutta methods such that equation holds $\forall \varphi \in P^k(I_i), i \in \mathbb{Z}.$

Nonlinear stability

$V^k := \{u : u|_{I_i} \in P^k(I_i) \text{ for all } i \in \mathbb{Z}\}$ piecewise polynomials

$H^{\lambda/2}(\mathbb{R})$ fractional Sobolev space

$$\|u\|_{H^{\lambda/2}(\mathbb{R})}^2 := \|u\|_{L^2(\mathbb{R})}^2 + |u|_{H^{\lambda/2}(\mathbb{R})}^2 < \infty$$

$$|u|_{H^{\lambda/2}(\mathbb{R})}^2 := \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{[u(z) - u(x)]^2}{|z - x|^{1+\lambda}} dz dx.$$

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$$V^k \cap L^2(\mathbb{R}) \subseteq H^{\lambda/2}(\mathbb{R})$$

Nonlinear stability

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$H^{\lambda/2}(\mathbb{R})$ fractional Sobolev space

$\|u\|_{H^{\lambda/2}}^2$ If $\phi \in V^k \cap L^2(\mathbb{R})$, then for all $\lambda \in (0, 1)$,

$$\|u\|_{H^{\lambda/2}(\mathbb{R})}^2 := \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{|u(z) - u(x)|^2}{|z-x|^{2-\lambda}} dx dz \leq \frac{C}{\Delta x} \|\phi\|_{L^2(\mathbb{R})}^2.$$

$$V^k \cap L^2(\mathbb{R}) \subseteq H^{\lambda/2}(\mathbb{R})$$

Nonlinear stability

$V^k := \{u : u|_{I_i} \in P^k(I_i) \text{ for all } i \in \mathbb{Z}\}$ piecewise polynomials

$H^{\lambda/2}(\mathbb{R})$ fractional Sobolev space

Theorem (Stability). $u_{\Delta x}$ numerical solution.

$$\|u\|_{H^{\lambda/2}(\mathbb{R})}^2 := \|u\|_{L^2(\mathbb{R})}^2 + |u|_{H^{\lambda/2}(\mathbb{R})}^2 < \infty$$

$$\|u_{\Delta x}(\cdot, T)\|_{L^2(\mathbb{R})}^2 + c_\lambda \int_0^T |u_{\Delta x}(\cdot, t)|_{H^{\lambda/2}(\mathbb{R})}^2 dt \leq \|u_0\|_{L^2(\mathbb{R})}^2.$$

$$|u|_{H^{\lambda/2}(\mathbb{R})}^2 := \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{|u(z) - u(x)|^2}{|z - x|^{1+\lambda}} dz dx.$$

Nonlinear stability

Proof.

Choose test function $\varphi = u_{\Delta x}(\cdot, t)$ in the DG scheme

Sum over $i \in \mathbb{Z}$, rearrange terms + integrate in time

$$\|u\|_{H^{\lambda/2}(\mathbb{R})}^2 := \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{[u(z) - u(x)]^2}{|z - x|^{1+\lambda}} dz dx.$$

$$\iint (u_{\Delta x})_t u_{\Delta x} = \int_0^T \sum_{i \in \mathbb{Z}} \left[F(u_i) (u_{\Delta x}(x_i^+) - u_{\Delta x}(x_i^-)) \int_{u_{\Delta x}(x_i^-)}^{u_{\Delta x}(x_i^+)} f(\xi) d\xi \right] + \iint \mathcal{L}[\tilde{u}] \tilde{u}.$$

$F(u_i) = F(u_{\Delta x}(x_i^-), u_{\Delta x}(x_i^+))$

Nonlinear stability

Proof.

E-flux

Choose test function $\varphi = u_{\Delta x}(\cdot, t)$ in the DG scheme

$$F(u_i)(u_{\Delta x}(x_i^+) - u_{\Delta x}(x_i^-)) - \int_{u_{\Delta x}(x_i^-)}^{u_{\Delta x}(x_i^+)} f(\xi) d\xi \leq 0$$

$$\iint (u_{\Delta x})_t u_{\Delta x} = \int_0^T \sum_{i \in \mathbb{Z}} \left[F(u_i)(u_{\Delta x}(x_i^+) - u_{\Delta x}(x_i^-)) - \int_{u_{\Delta x}(x_i^-)}^{u_{\Delta x}(x_i^+)} f(\xi) d\xi \right]$$

$$F(u_i) = F(u_{\Delta x}(x_i^-), u_{\Delta x}(x_i^+))$$

$$+ \iint \mathcal{L}[\tilde{u}] \tilde{u}.$$

Nonlinear stability

Proof.

Choose test function $\varphi = u_{\Delta x}(\cdot, t)$ in the DG scheme

Sum over $i \in \mathbb{Z}$ “Integration-by-parts” + integrate in time

$$\iint_{\mathbb{R}} (u_{\Delta x})_t \int_{\mathbb{R}} \varphi g[\varphi] dx = -\frac{c_\lambda}{2} \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{(\varphi(z) - \varphi(x))^2}{|z - x|^{1+\lambda}} dz dx,$$

for $\varphi \in L^1(\mathbb{R}) \cap BV(\mathbb{R})$

$$F(u_i) = F(u_{\Delta x}(x_i^-), u_{\Delta x}(x_i^+))$$

$$+ \iint \mathcal{L}[\tilde{u}] \tilde{u}.$$

Higher-order accuracy (linear equations)

Exists a unique $H^{k+1}(Q_T)$ solution to the linear equation

$$\partial_t u + c \partial_x u = \mathcal{L}[u], \quad u(0, x) = u_0 \in H^k(\mathbb{R}), \quad (k \geq 0)$$

Theorem (error estimate). For any $T > 0$,

$$\|u(\cdot, T) - u_{\Delta x}(\cdot, T)\|_{L^2(\mathbb{R})} \leq c_{k,T} \Delta x^{k+\frac{1}{2}}.$$

Proof. • Error $e := u - u_{\Delta x} \in H^{\lambda/2}(\mathbb{R})$ obeys

Higher-order accuracy (linear equations)

$$B(e, \varphi) := \int_{\mathbb{R}} e_t \varphi + \sum_{i \in \mathbb{Z}} \left[F(e_i) (\varphi(x_i^-) - \varphi(x_i^+)) - \int_{I_i} c e \varphi_x \right]$$

Exists a unique $H^{k+1}(Q_T)$ solution to the linear equation

$$-\int_{\mathbb{R}} g[e] \varphi = 0$$

$$\partial_t u + c \partial_x u = \mathcal{L}[u], \quad u(0, x) = u_0 \in H^k(\mathbb{R}), \quad (k \geq 0)$$

Theorem (error estimate). For any $T > 0$,

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Exists a unique $H^{k+1}(Q_T)$ solution to the linear equation $-\int_{\mathbb{R}} g[e] \varphi = 0$

- Let \mathbf{u} be L^2 -projection of u into V^k and set $\mathbf{e} := \mathbf{u} - u_{\Delta x} \in H^{\lambda/2}(\mathbb{R})$. Then

$$\begin{aligned} \int_0^T \int_{\mathbb{R}} \mathbf{e}_t \mathbf{e} &= \int_0^T \int_{\mathbb{R}} (\mathbf{u} - u)_t \mathbf{e} - \int_0^T \sum_{i \in \mathbb{Z}} \left[F(\mathbf{e}_i) (\mathbf{e}(x_i^-) - \mathbf{e}(x_i^+)) - \int_{I_i} c \mathbf{e} \mathbf{e}_x \right] \\ &+ \int_0^T \sum_{i \in \mathbb{Z}} \left[F((\mathbf{u} - u)_i) (\mathbf{e}(x_i^-) - \mathbf{e}(x_i^+)) - \int_{I_i} c (\mathbf{u} - u) \mathbf{e}_x \right] \\ &+ \int_0^T \int_{\mathbb{R}} g[\mathbf{e}] \mathbf{e} - \int_0^T \int_{\mathbb{R}} g[\mathbf{e} - e] \mathbf{e}. \end{aligned}$$

Proof. • Error $e := u - u_{\Delta x} \in H^{\lambda/2}(\mathbb{R})$ obeys

$$B(e, \varphi) := \int_{\mathbb{R}} e_t \varphi + \sum_{i \in \mathbb{Z}} \left[F(e_i) (\varphi(x_i^-) - \varphi(x_i^+)) - \int_{I_i} c e \varphi_x \right]$$

Exists a unique $H^{k+1}(Q_T)$ solution $\int_{\mathbb{R}} g[e] \varphi = 0$
 Bounded by $c_{k,T} \Delta x^{2k+1}$

- Let \mathbf{u} be L^2 -projection of u into $H^k(\mathbb{R})$ and set $\mathbf{e} := \mathbf{u} - u_{\Delta x} \in H^{\lambda/2}(\mathbb{R})$. Then

$$\begin{aligned} \int_0^T \int_{\mathbb{R}} \mathbf{e}_t \mathbf{e} &= \int_0^T \int_{\mathbb{R}} (\mathbf{u} - u)_t \mathbf{e} - \int_0^T \sum_{i \in \mathbb{Z}} \left[F(\mathbf{e}_i) (\mathbf{e}(x_i^-) - \mathbf{e}(x_i^+)) - \int_{I_i} c \mathbf{e} \mathbf{e}_x \right] \\ &\quad + \int_0^T \sum_{i \in \mathbb{Z}} \left[F((\mathbf{u} - u)_i) (\mathbf{e}(x_i^-) - \mathbf{e}(x_i^+)) - \int_{I_i} c (\mathbf{u} - u) \mathbf{e}_x \right] \\ &\quad + \int_0^T \int_{\mathbb{R}} g[\mathbf{e}] \mathbf{e} - \int_0^T \int_{\mathbb{R}} g[\mathbf{e} - e] \mathbf{e}. \end{aligned}$$

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Exists a unique $H^{k+1}(Q_T)$ solution to the linear equation $-\int_{\mathbb{R}} g[e] \varphi = 0$

- Let \mathbf{u} be L^2 -projection of u into V^k and set $\mathbf{e} := \mathbf{u} - u_{\Delta x} \in H^{\lambda/2}(\mathbb{R})$. Then

$$\int_0^T \int_{\mathbb{R}} \mathbf{e}_t \mathbf{e} = \int_0^T \int_{\mathbb{R}} \left[F(\mathbf{e}_i) (\mathbf{e}(x_i^-) - \mathbf{e}(x_i^+)) - \int_{I_i} c \mathbf{e} \mathbf{e}_x \right]$$

Remains to estimate this term

$$+ \int_0^T \sum_{i \in \mathbb{Z}} \left[F((\mathbf{u} - u)_i) (\mathbf{e}(x_i^-) - \mathbf{e}(x_i^+)) - \int_{I_i} c(\mathbf{u} - u) \mathbf{e}_x \right]$$

$$+ \int_0^T \int_{\mathbb{R}} g[\mathbf{e}] \mathbf{e} - \int_0^T \int_{\mathbb{R}} g[\mathbf{e} - e] \mathbf{e}.$$

Proof. • Error $e := u - u_{\Delta x} \in H^{\lambda/2}(\mathbb{R})$ obeys

$$\begin{aligned}
 & \bullet \int_0^T \int_{\mathbb{R}} g[\mathbf{e}]\mathbf{e} - \int_0^T \int_{\mathbb{R}} g[\mathbf{e} - e]\mathbf{e} \\
 &= \frac{1}{2} \int_0^T \int_{\mathbb{R}} g[\mathbf{e}]\mathbf{e} + \frac{1}{2} \int_0^T \int_{\mathbb{R}} g[\mathbf{e}]\mathbf{e} - \frac{1}{2} \int_0^T \int_{\mathbb{R}} g\mathbf{e} - e \\
 &\leq \int_0^T \|(u - \mathbf{u})(\cdot, t)\|_{H^{\lambda/2}(\mathbb{R})}^2 dt
 \end{aligned}$$

and moreover

$$\begin{aligned}
 \int_0^T \|(u - \mathbf{u})(\cdot, t)\|_{H^{\lambda/2}(\mathbb{R})}^2 &\leq c_k \|u(\cdot, t)\|_{H^{k+1}(\mathbb{R})}^2 \Delta x^{2k+2-\lambda} \\
 &\leq C_k \Delta x^{2k+1+\varepsilon}, \quad \varepsilon := 1 - \lambda \in (0, 1).
 \end{aligned}$$

$$+ \int_0^T \int_{\mathbb{R}} g[\mathbf{e}]\mathbf{e} - \int_0^T \int_{\mathbb{R}} g[\mathbf{e} - e]\mathbf{e}.$$

Convergence / error estimate in nonlinear case

- Restrict to piecewise constant elements ($k = 0$):

$$\{\varphi_{0,i}, \varphi_{1,i}, \dots, \varphi_{k,i}\} = \{\varphi_{0,i}\}, \quad \varphi_{0,i} = \mathbf{1}_{I_i}$$

- Implicit-explicit method

$$\begin{cases} U_i^{n+1} = U_i^n - \Delta t D_- F(U_i^n, U_{i+1}^n) + \Delta t \mathcal{L} \langle U^{n+1} \rangle_i, \\ U_i^0 = \frac{1}{\Delta x} \int_{I_i} u_0(x) dx \end{cases}$$

Convergence / error estimate in nonlinear case

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- Nonlocal operator

$$\mathcal{L} \langle U^n \rangle_i := \frac{1}{\Delta x} \int_{I_i} \mathcal{L}[U_{\Delta x}^n] dx = \frac{1}{\Delta x} \sum_{j \in \mathbb{Z}} G_j^i U_j^n,$$
$$G_j^i := \int_{I_i} \mathcal{L}[\mathbf{1}_{I_j}] dx$$

Lemma.

For all $(i, j) \in \mathbb{Z} \times \mathbb{Z}$,

- $\sum_{k \in \mathbb{Z}} |G_k^i| < \infty$, $\sum_{k \in \mathbb{Z}} G_k^i = 0$, $G_j^i = G_i^j$, $G_{j+1}^{i+1} = G_j^i$.

Moreover, $G_j^i \geq 0$ whenever $i \neq j$, while

$$G_i^i = -d_\lambda \Delta x^{1-\lambda}, \text{ where } d_\lambda := c_\lambda \left(\int_{|z|<1} \frac{dz}{|z|^\lambda} + \int_{|z|>1} \frac{dz}{|z|^{1+\lambda}} \right) > 0.$$

- Nonlocal operator

$$\mathcal{L}\langle U^n \rangle_i := \frac{1}{\Delta x} \int_{I_i} \mathcal{L}[U_{\Delta x}^n] dx = \frac{1}{\Delta x} \sum_{j \in \mathbb{Z}} G_j^i U_j^n,$$

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$$G_j^i := \int_{I_i} \mathcal{L}[\mathbf{1}_{I_j}] dx$$

Lemma. Suppose $u_0 \in L^1(\mathbb{R}) \cap BV(\mathbb{R})$.

Let $u_{\Delta x}$ be piecewise constant numerical solution.

Then for all $t \geq 0$,

$$i) \quad \|u_{\Delta x}(\cdot, t)\|_{L^\infty(\mathbb{R})} \leq \|u_0\|_{L^\infty(\mathbb{R})},$$

$$ii) \quad \|u_{\Delta x}(\cdot, t)\|_{L^1(\mathbb{R})} \leq \|u_0\|_{L^1(\mathbb{R})},$$

$$iii) \quad |u_{\Delta x}(\cdot, t)|_{BV(\mathbb{R})} \leq |u_0|_{BV(\mathbb{R})}.$$

$$iv) \quad \|\tilde{u}(\cdot, s) - \tilde{u}(\cdot, t)\|_{L^1(\mathbb{R})} \leq c(|s - t| + \Delta x).$$

Theorem (convergence/error estimate).

Suppose $u_0 \in L^1(\mathbb{R}) \cap BV(\mathbb{R})$.

Let u be BV entropy solution of fractional CL.

Let $u_{\Delta x}$ be numerical solution.

There exists a constant $C_T > 0$ such that

$$\|u(\cdot, T) - u_{\Delta x}(\cdot, T)\|_{L^1(\mathbb{R})} \leq C_T \sqrt{\Delta x}.$$

Proof based on adaption of Kuznetsov's lemma

Lemma (Kuznetsov)

Let u be the exact BV entropy solution

Let \tilde{u} be an approximate solution

For any $\epsilon > 0$, $0 < \delta < T$,

$$\|u(\cdot, T) - \tilde{u}(\cdot, T)\|_{L^1(\mathbb{R})} \leq c(\epsilon + \delta + \Delta x) - \Lambda_{\epsilon, \delta}[\tilde{u}, u].$$

Kruzkov form:

$$\begin{aligned} \Lambda[u, \varphi, k] := & \iint |u - k| \varphi_t + q_k(u) \varphi_x + \operatorname{sgn}(u - k) \mathcal{L}[u] \varphi dx dt \\ & + \int_{\mathbb{R}} |u_0(x) - k| \varphi(x, 0) dx - \int_{\mathbb{R}} |u(x, T) - k| \varphi(x, T) dx \end{aligned}$$

Proof based on adaption of Kuznetsov's lemma

Lemma (Kuznetsov)

Let u be the exact BV entropy solution

$$q_k(u) = \operatorname{sgn}(u - k)(f(u) - f(k))$$

Let \tilde{u} be an approximate solution

$$\varphi(x, y, t, s) = \omega_\epsilon(x - y)\omega_\delta(t - s)$$

$\omega_\alpha \in C_c^\infty(\mathbb{R})$, $\alpha > 0$, is an approximate delta function.

Kruzkov form:

$$\begin{aligned} \Lambda[u, \varphi, k] := & \iint |u - k| \varphi_t + q_k(u) \varphi_x + \operatorname{sgn}(u - k) \mathcal{L}[u] \varphi dx dt \\ & + \int_{\mathbb{R}} |u_0(x) - k| \varphi(x, 0) dx - \int_{\mathbb{R}} |u(x, T) - k| \varphi(x, T) dx \end{aligned}$$

Convection / diffusion / fractional diffusion

- DG for diffusion equation $u_t - u_{xx} = 0$

$$\int_{I_j} u_t v + \int_{I_j} u_x v_x dx - \widehat{(u_x)}_{j+1/2} v_{j+1/2}^- + \widehat{(u_x)}_{j-1/2} v_{j-1/2}^+ = 0,$$

u, v piecewise polynomials

with respect to cells $I_j = (x_{j-1/2}, x_{j+1/2})$

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Numerical fluxes

Convection / diffusion / fractional diffusion

- DG for diffusion equation $u_t - u_{xx} = 0$

$$\int_{I_j} u_t v + \int_{I_j} u_x v_x dx - \widehat{(u_x)}_{j+1/2} v_{j+1/2}^- + \widehat{(u_x)}_{j-1/2} v_{j-1/2}^+ = 0,$$

u, v piecewise polynomials

with respect to cells $I_j = (x_{j-1/2}, x_{j+1/2})$

Naive choice does not work
(not consistent):

$$\widehat{(u_x)}_{j+1/2} = \left((u_x)_{j+1/2}^- + (u_x)_{j+1/2}^+ \right) / 2$$

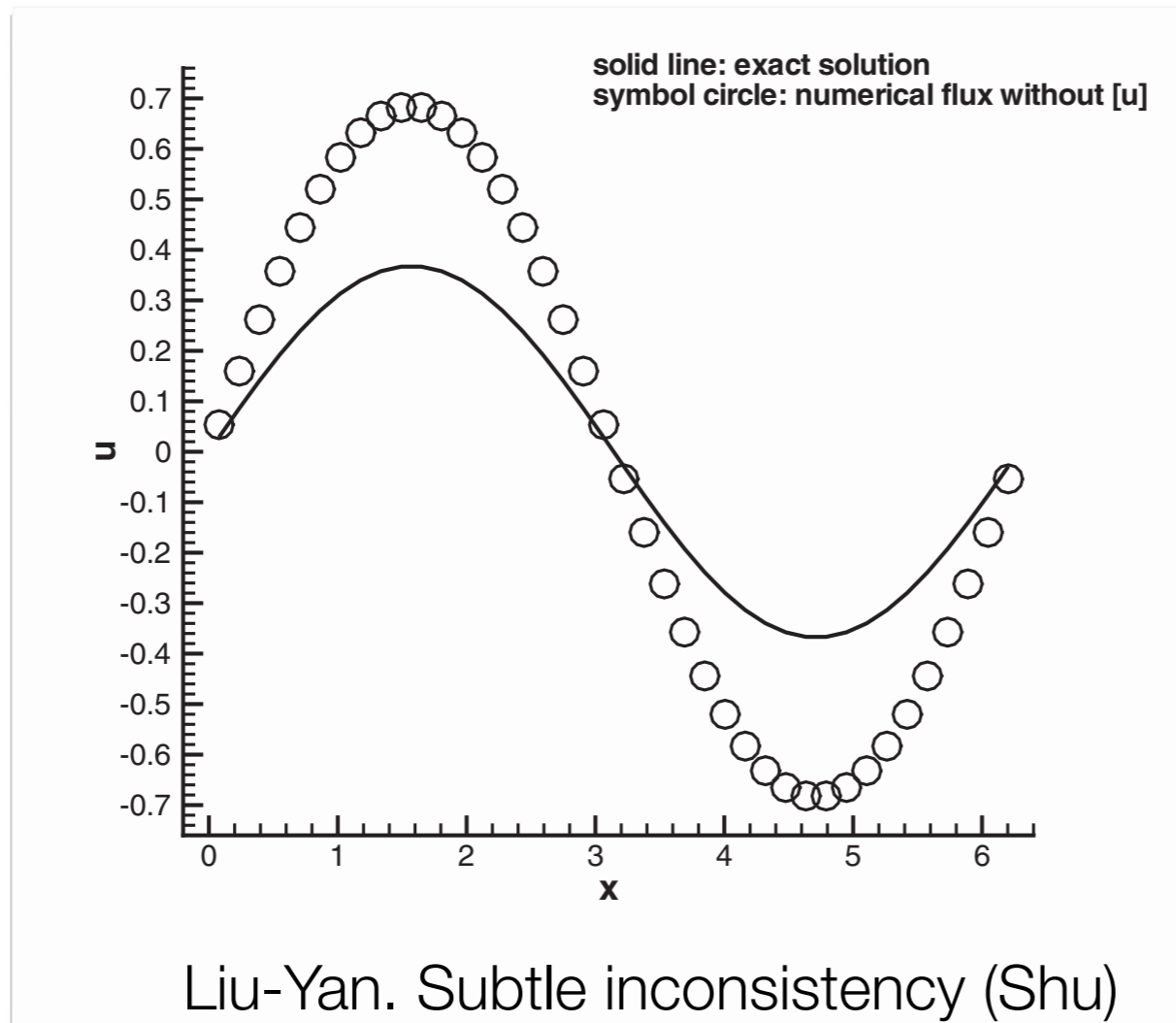
Convection

- DG for

$$\int_{I_j} u_t v$$

u, v P

with



diffusion

$$= 0$$

$$\widehat{(u_x)}_{j-1/2} v_{j-1/2}^+ = 0,$$

$$j+1/2)$$

Naive choice does not work
(not consistent):

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- Local DG method (LDG) of Cockburn & Shu

Rewrite heat equation $u_t - u_{xx} = 0$ as 1st order system

$$u_t - q_x = 0, \quad q - u_x = 0.$$

Apply DG method to system.

So both solution u and flux q are evolved in each cell !

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Rewrite heat equation $u_t - u_{xx} = 0$ as 1st order system

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- Direct DG method (DDG) of Liu & Yan

Based on the standard weak formulation

+ convenient choice of numerical flux.

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$$\int_{I_j} u_t v + \int_{I_j} u_x v_x dx - \widehat{(u_x)}_{j+1/2} v_{j+1/2}^- + \widehat{(u_x)}_{j-1/2} v_{j-1/2}^+ = 0$$

- Local DG method (LDG) of Cockburn & Shu

Piecewise constant approximation ($k = 0$):

Rewrite heat equation $u_t - u_{xx} = 0$ as 1st order system

$$u_t - \widehat{u_x} = 0, \quad \Delta x q - u_x = 0.$$

Apply DG method to system yields standard central differencing.

So both solution u and flux q are evolved in each cell !

- Direct DG method (DDG) of Liu & Yan

Based on the standard weak formulation

+ convenient choice of numerical flux.

$$\int_{I_j} u_t v + \int_{I_j} u_x v_x dx - (\widehat{u_x})_{j+1/2} v_{j+1/2}^- + (\widehat{u_x})_{j-1/2} v_{j-1/2}^+ = 0$$

- Local DG method (LDG) of Cockburn & Shu

Rewrite heat equation $u_t - u_{xx} = 0$ as 1st order system

$$u_t - q_x = 0, \quad q - u_x = 0.$$

Apply DG method to system.

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- Local DG method (LDG) of Cockburn & Shu

Piecewise linear approximation ($k = 1$):

Rewrite heat equation $u_t - u_{xx} = 0$ as 1st order system

$$\widehat{u_x} = \frac{u_+ - u_-}{\Delta x} + \frac{1}{2} \left((u_x)^+ + (u_x)^- \right).$$

Apply DG method to system.
yields a second order approximation.

So both solution u and flux q are evolved in each cell !

- Direct DG method (DDG) of Liu & Yan

Based on the standard weak formulation

+ convenient choice of numerical flux.

$$\int_{I_j} u_t v + \int_{I_j} u_x v_x dx - \widehat{(u_x)}_{j+1/2} v_{j+1/2}^- + \widehat{(u_x)}_{j-1/2} v_{j-1/2}^+ = 0$$

- Local DG method (LDC) of Cockburn & Shu

Piecewise linear approximation ($k = 1$):

Rewrite heat equation $u_t - u_{xx} = 0$ as 1st order system

$$\widehat{u_x} = \frac{u_+ - u_-}{\Delta x} + \frac{1}{2} \left((u_x)^+ + (u_x)^- \right).$$

Apply DG method to system

So be

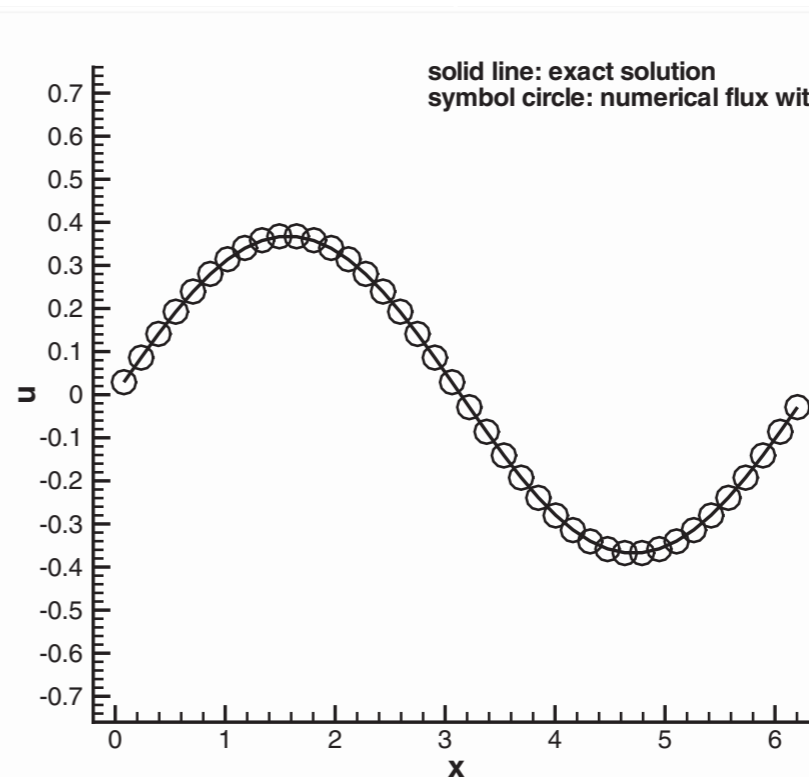
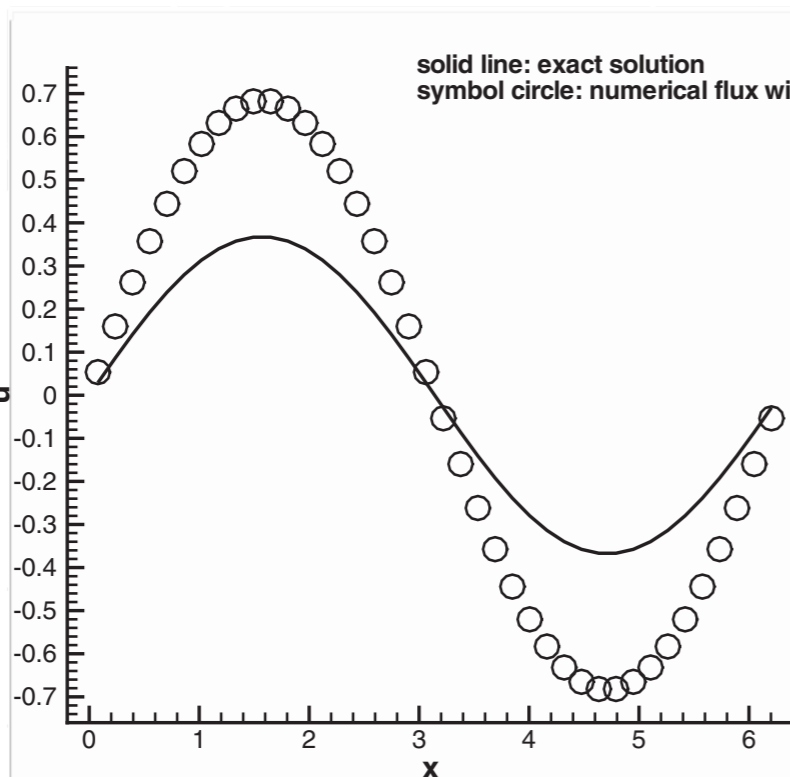
- Directional

Based on

+ control

$$\int_{I_j} u$$

(Liu-Yan)



well !

0

\int_{I_j}

- Solution of heat equation

$$u(x, t) = \frac{1}{\sqrt{4\pi t}} \int_{-\infty}^{\infty} e^{-(x-y)^2/(4t)} g(y) dy$$

with data g having a discontinuity at $x = 0$.

Formula for gradient of solution to heat equation:
(Liu-Yan)

- $$u_x(0, t) = \sum \frac{2^{m-1}}{(2m-1)!!} t^m [\partial_x^{2m} g] / \sqrt{\pi t} + \sum \frac{2^m}{(2m)!!} t^m \overline{\partial_x^{2m+1} g}$$
- $$= \frac{1}{\sqrt{4\pi t}} [g] + \overline{\partial_x g} + \sqrt{\frac{t}{\pi}} [\partial_x^2 g] + t \overline{\partial_x^3 g} + \dots,$$

$$\int_{I_j} u_t v + \int_{I_j} u_x v_x dx - (\widehat{u_x})_{j+1/2} v_{j+1/2}^- + (\widehat{u_x})_{j-1/2} v_{j-1/2}^+ = 0$$

- Local Solution of heat equation

$$u(x, t) = \frac{1}{\sqrt{4\pi t}} \int_{-\infty}^{\infty} e^{-(x-y)^2/(4t)} g(y) dy$$

with data g having a discontinuity at $x = 0$.

Asymptotic Formula for gradient of solution to heat equation:
(Liu-Yan)

- Discontinuity in gradient

$$u_x(0, t) = \sum \frac{2^{m-1}}{(2m-1)!!} t^m [\partial_x^{2m} g] / \sqrt{\pi t} + \sum \frac{2^m}{(2m)!!} t^m \overline{\partial_x^{2m+1} g}$$

$$= \frac{1}{\sqrt{4\pi t}} [g] + \overline{\partial_x g} + \sqrt{\frac{t}{\pi}} [\partial_x^2 g] + t \overline{\partial_x^3 g} + \dots,$$

$$\int_{I_j} u_t v + \int_{I_j} u_x v_x dx - \widehat{(u_x)}_{j+1/2} v_{j+1/2}^- + \widehat{(u_x)}_{j-1/2} v_{j-1/2}^+ = 0$$

↑
Jump

- Local Solution of heat equation

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Asymptotic Formula for gradient of solution to heat equation:
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$$= \frac{1}{\sqrt{4\pi t}} [g] + \overline{\partial_x g} + \sqrt{\frac{t}{\pi}} [\partial_x^2 g] + t \overline{\partial_x^3 g} + \dots,$$

Average

Local Discontinuous Galerkin (LDG) method

$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

Rewrite as a system

$$u_t + (f(u) - \sqrt{a(u)}q)_x = b\mathcal{L}[u]$$

$$q - g(u)_x = 0, \quad g = \int \sqrt{a}$$

Apply DG method

Local Discontinuous Galerkin (LDG) method

$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|} dz$$
$$\mathbf{h}(\mathbf{w}) = \mathbf{h}(u, q) = \begin{pmatrix} h_u(\mathbf{w}) \\ h_q(u) \end{pmatrix} = \begin{pmatrix} f(u) - \sqrt{a(u)}q \\ -g(u) \end{pmatrix}.$$

Rewrite as a system

$$u_t + (f(u) - \sqrt{a(u)}q)_x = b\mathcal{L}[u]$$

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$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|} dz$$

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Rewrite as a system

Variational form

For all $v_u, v_q \in P^k(I_i)$

$$\int_{I_i} \partial_t u v_u - \int_{I_i} h_u(\mathbf{w}) \partial_x v_u + h_u(\mathbf{w}_{i+1}) v_{u,i+1}^- - h_u(\mathbf{w}_i) v_{u,i}^+ = \int_{I_i} \mathcal{L}[u] v_u,$$

$$\int_{I_i} q v_q - \int_{I_i} h_q(u) \partial_x v_q + h_q(u_{i+1}) v_{q,i+1}^- - h_q(u_i) v_{q,i}^+ = 0,$$

Apply DG method

Local Discontinuous Galerkin (LDG) method

$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c(u) \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|} dz$$

$$\mathbf{h}(\mathbf{w}) = \mathbf{h}(u, q) = \begin{pmatrix} h_u(\mathbf{w}) \\ h_q(u) \end{pmatrix} = \begin{pmatrix} f(u) - \sqrt{a(u)}q \\ -g(u) \end{pmatrix}.$$

Rewrite as a system

Variational form

For all $v_u, v_q \in P^k(I_i)$

$$\int_{I_i} \partial_t u v_u - \int_{I_i} h_u(\mathbf{w}) \partial_x v_u + \boxed{h_u(\mathbf{w}_{i+1})} v_{u,i+1}^- - \boxed{h_u(\mathbf{w}_i)} v_{u,i}^+ = \int_{I_i} \mathcal{L}[u] v_u,$$

$$\int_{I_i} q v_q - \int_{I_i} h_q(u) \partial_x v_q + \boxed{h_q(u_{i+1})} v_{q,i+1}^- - \boxed{h_q(u_i)} v_{q,i}^+ = 0,$$

Apply DG method

Replace h_u, h_q by numerical fluxes ala Cockburn & Shu.

Local Discontinuous Galerkin (LDG) method

$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|} dz$$

$$\mathbf{h}(\mathbf{w}) = \mathbf{h}(u, q) = \begin{pmatrix} h_u(\mathbf{w}) \\ h_q(u) \end{pmatrix} = \begin{pmatrix} f(u) - \sqrt{a(u)}q \\ -g(u) \end{pmatrix}$$

Local DG method

$$\int_{I_i} \partial_t u v_u - \int_{I_i} h_u(\mathbf{w}) \partial_x v_u + \hat{h}_u(\mathbf{w}_{i+1}) v_{u,i+1}^- - \hat{h}_u(\mathbf{w}_i) v_{u,i}^+ = b \int_{I_i} \mathcal{L}[u] v_u,$$

$$\int_{I_i} q v_q - \int_{I_i} h_q(u) \partial_x v_q + \hat{h}_q(u_{i+1}) v_{q,i+1}^- - \hat{h}_q(u_i) v_{q,i}^+ = 0,$$

$$\text{for all } v_u, v_q \in P^k(I_i), i \in \mathbb{Z}$$

Theorem (nonlinear stability).

Let $\tilde{\mathbf{w}} = (\tilde{u}, \tilde{q})$ be a solution of LDG method. Then

$$\begin{aligned} \|\tilde{u}(\cdot, T)\|_{L^2(\mathbb{R})}^2 + 2\|\tilde{q}\|_{L^2(Q_T)}^2 + 2\Theta_T(\tilde{\mathbf{w}}) \\ + c_\lambda \int_0^T \|\tilde{u}(\cdot, t)\|_{H^{\lambda/2}(\mathbb{R})}^2 dt \leq \|u_0\|_{L^2(\mathbb{R})}^2, \end{aligned}$$

where

$$\Theta_T[\mathbf{w}] = \int_0^T \sum_{i \in \mathbb{Z}} [\mathbf{w}_i]' \mathbb{C}[\mathbf{w}_i] (\geq 0).$$

(the matrix \mathbb{C} is semipositive definite)

Theorem (error estimate linear eqs).

Let $\tilde{\mathbf{w}} = (\tilde{u}, \tilde{q})$ be a solution of LDG method.

With $e_u = u - \tilde{u}$ and $e_q = q - \tilde{q}$,

$$\int_{\mathbb{R}} e_u^2(x, T) + \int_0^T \int_{\mathbb{R}} e_q^2 + \Theta_T[\mathbf{e}] + c_\lambda \int_0^T |e_u|_{H^{\lambda/2}(\mathbb{R})}^2 = \mathcal{O}(1) \Delta x^{2k}.$$

NB! Error estimate is optimal without fractional diffusion.

Direct Discontinuous Galerkin (LDG) method

$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

For an arbitrary $v \in P^k(I_i)$,

$$\begin{aligned} & \int_{I_i} u_t v - \int_{I_i} f(u) v_x + f(u_{i+1}) v_{i+1}^- - f(u_i) v_i^+ \\ & + \int_{I_i} a(u) u_x v_x - h(u_{i+1}, u_{x,i+1}) v_{i+1}^- + h(u_i, u_{x,i}) v_i^+ \\ & = \int_{I_i} \mathcal{L}[u] v, \quad (h(u, u_x) = a(u) u_x) \end{aligned}$$

Direct Discontinuous Galerkin (LDG) method

$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

For an arbitrary $v \in P^k(I_i)$,

$$\begin{aligned} \int_{I_i} u_t v - \int_{I_i} f(u) v_x + \boxed{f(u_{i+1})} v_{i+1}^- - \boxed{f(u_i)} v_i^+ & \text{Numerical fluxes} \\ + \int_{I_i} a(u) u_x v_x - \boxed{h(u_{i+1}, u_{x,i+1})} v_{i+1}^- + \boxed{h(u_i, u_{x,i})} v_i^+ & \\ = \int_{I_i} \mathcal{L}[u] v, & \text{Numerical fluxes} \quad (h(u, u_x) = a(u) u_x) \end{aligned}$$

Direct Discontinuous Galerkin (LDG) method

For convection, choose any consistent and monotone flux

$$\partial_t u + \partial_x f(u) = \int_{|z|>0} (u(x+z) - u(t, x)) \frac{dz}{|z|^{1+\lambda}}$$

$$\hat{f}(u_i) = \hat{f}(u(x_i^-), u(x_i^+)).$$

For an arbitrary $v \in P^k(I_i)$,

$$\begin{aligned} \int_{I_i} u_t v &= \int_{I_i} f(u) v_x + \boxed{f(u_{i+1})} v_{i+1}^- - \boxed{f(u_i)} v_i^+ \\ &+ \int_{I_i} a(u) u_x v_x - \boxed{h(u_{i+1}, u_{x,i+1})} v_{i+1}^- + \boxed{h(u_i, u_{x,i})} v_i^+ \\ &= \int_{I_i} \mathcal{L}[u] v, \quad \text{Numerical fluxes} \\ &\quad \quad \quad (h(u, u_x) = a(u) u_x) \end{aligned}$$

Direct Discontinuous Galerkin (LDG) method

$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

For an arbitrary $v \in P^k(I_i)$,

$$\begin{aligned} \int_{I_i} u_t v - \int_{I_i} f(u) v_x + \boxed{f(u_{i+1})} v_{i+1}^- - \boxed{f(u_i)} v_i^+ & \quad \text{Numerical fluxes} \\ + \int_{I_i} a(u) u_x v_x - \boxed{h(u_{i+1}, u_{x,i+1})} v_{i+1}^- + \boxed{h(u_i, u_{x,i})} v_i^+ & \\ = \int_{I_i} \mathcal{L}[u] v, & \quad \text{Numerical fluxes} \\ & \quad (h(u, u_x) = a(u) u_x) \end{aligned}$$

For diffusion flux $h = a(u)u_x = A(u)_x$, we follow Liu-Yan

$$\begin{aligned}\hat{h}(u_i) &= \hat{h}(u(x_i^-), \dots, \partial_x^k u(x_i^-), u(x_i^+), \dots, \partial_x^k u(x_i^+)) \\ &= \beta_0 \frac{[A(u_i)]}{\Delta x} + \overline{A(u_i)_x} + \sum_{m=1}^{\lfloor k/2 \rfloor} \beta_m \Delta x^{2m-1} [\partial_x^{2m} A(u_i)],\end{aligned}$$

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$\{\beta_0, \dots, \beta_{\lfloor k/2 \rfloor}\}$ satisfy for some $\gamma \in (0, 1)$ and $\alpha \geq 0$

$$\sum_{i \in \mathbb{Z}} \hat{h}(u_i)[u_i] \geq \alpha \sum_{i \in \mathbb{Z}} \frac{[A(u_i)]}{\Delta x} [u_i] - \gamma \sum_{i \in \mathbb{Z}} \int_{I_i} a(u)(u_x)^2.$$

For diffusion flux $h = a(u)u_x = A(u)_x$, we follow Liu-Yan

For example, if $k = 0$ and $\beta_0 = 1$,

$$\hat{h}(u_i) = \hat{h}(u(x_i^-), \dots, \partial_x^k u(x_i^-), u(x_i^+), \partial_x^k u(x_i^+))$$

$$\hat{h}(u_i) = \frac{1}{\Delta x} [A(u_i)] = \frac{A(u(x_i^+)) - A(u(x_i^-))}{\Delta x}.$$

$$= \beta_0 \frac{[A(u_i)]}{\Delta x} + A(u_i)_x + \sum_{m=1} \beta_m \Delta x^{2m-1} [\partial_x^{2m} A(u_i)],$$

$\{\beta_0, \dots, \beta_{\lfloor k/2 \rfloor}\}$ satisfy for some $\gamma \in (0, 1)$ and $\alpha \geq 0$

$$\sum_{i \in \mathbb{Z}} \hat{h}(u_i) [u_i] \geq \alpha \sum_{i \in \mathbb{Z}} \frac{[A(u_i)]}{\Delta x} [u_i] - \gamma \sum_{i \in \mathbb{Z}} \int_{I_i} a(u) (u_x)^2.$$

For diffusion flux $h = a(u)u_x = A(u)_x$, we follow Liu-Yan

$$\begin{aligned} \hat{h}(u_i) &= \hat{h}(u(x_i^-), \dots, \partial_x^k u(x_i^-), u(x_i^+), \dots, \partial_x^k u(x_i^+)) \\ &= \beta_0 \frac{[A(u_i)]}{\Delta x} + \overline{A(u_i)_x} + \sum_{m=1}^{\lfloor k/2 \rfloor} \beta_m \Delta x^{2m-1} [\partial_x^{2m} A(u_i)], \end{aligned}$$

With $k = 2$,

$\{\beta_0, \dots, \beta_{\lfloor k/2 \rfloor}\}$ satisfy for some $\gamma \in (0, 1)$ and $\alpha \geq 0$

$$\begin{aligned} \sum_{m=1}^{\lfloor k/2 \rfloor} \beta_m \Delta x^{2m-1} [\partial_x^{2m} A(u_i)] \\ \hat{h}(u_i)[u_i] &\geq \alpha \sum_{i \in \mathbb{Z}} \frac{[A(u_i)]}{\Delta x} [u_i] - \gamma \sum_{i \in \mathbb{Z}} \int_{I_i} a(u)(u_x)^2. \\ &= \beta_1 \Delta x [\partial_x^2 A(u_i)] \\ &= \beta_1 \Delta x [a'(u_i)(\partial_x u_i)^2 + a(u_i)\partial_x^2 u_i]. \end{aligned}$$

Theorem (nonlinear stability).

Let \hat{u} be DDG solution. Then

$$\|\hat{u}(\cdot, T)\|_{L^2(\mathbb{R})}^2 + 2\Gamma_T[\hat{u}] + c_\lambda \int_0^T \|\hat{u}(\cdot, t)\|_{H^{\lambda/2}(\mathbb{R})}^2 dt \leq \|u_0\|_{L^2}^2$$

$$\Gamma_T[u] = (1 - \gamma) \int_0^T \sum_{i \in \mathbb{Z}} \int_{I_i} a(u) (u_x)^2 + \alpha \int_0^T \sum_{i \in \mathbb{Z}} \frac{[A(u_i)]}{\Delta x} [u_i].$$

Theorem (error estimate for linear eqs).

Let $u \in H^{k+1}(Q_T)$ be a solution of IPDE.

Let \hat{u} be a DDG solution.

With $e = u - \hat{u}$,

$$\begin{aligned} \int_{\mathbb{R}} e^2(x, T) + \frac{|c|}{2} \int_0^T \sum_{i \in \mathbb{Z}} [e_i]^2 + (1 - \gamma) \int_0^T \int_{\mathbb{R}} (e_x)^2 \\ + \alpha \int_0^T \sum_{i \in \mathbb{Z}} \frac{[e_i]^2}{\Delta x} \\ + c_\lambda \int_0^T |e|_{H^{\lambda/2}(\mathbb{R})}^2 = \mathcal{O}(1) \Delta x^{2k}. \end{aligned}$$

Convergence of DDG method in nonlinear case

$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

Piecewise constant elements ($k = 0$):

$$\Delta x \frac{d}{dt} U_i + \hat{f}(U_i, U_{i+1}) - \hat{f}(U_{i-1}, U_i) - \frac{[A(U_{i+1})]}{\Delta x} + \frac{[A(U_i)]}{\Delta x} = \sum_{j \in \mathbb{Z}} U_j \int_{I_i} \mathcal{L}[\mathbf{1}_{I_j}].$$

Convergence of DDG method in nonlinear case

$$\partial_t u + \partial_x f(u) = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

Explicit method

$$\begin{cases} \frac{U_i^{n+1} - U_i^n}{\Delta t} + D_- \left[\hat{f}(U_i^n, U_{i+1}^n) - D_+ A(U_i^n) \right] = \mathcal{L} \langle U^n \rangle_i, \\ U_i^0 = \frac{1}{\Delta x} \int_{I_i} u_0(x) dx. \end{cases}$$

Lemma (a priori estimates).

$$i) \quad \|U^n\|_{L^1(\mathbb{Z})} \leq \|u_0\|_{L^1(\mathbb{R})},$$

$$ii) \quad \|U^n\|_{L^\infty(\mathbb{Z})} \leq \|u_0\|_{L^\infty(\mathbb{R})},$$

$$iii) \quad |U^n|_{BV(\mathbb{Z})} \leq |u_0|_{BV(\mathbb{R})}.$$

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$$iii) \quad |U^n|_{BV(\mathbb{Z})} \leq |u_0|_{BV(\mathbb{R})}.$$

Moreover,

$$\begin{aligned} & \left\| \hat{f}(U_i^n, U_{i+1}^n) - D_+ A(U_i^n) - \sum_{k=-\infty}^i \sum_{j \in \mathbb{Z}} G_j^k U_j^n \right\|_{L^\infty(\mathbb{Z})} \\ & \leq \left\| \hat{f}(U_i^0, U_{i+1}^0) - D_+ A(U_i^0) - \sum_{k=-\infty}^i \sum_{j \in \mathbb{Z}} G_j^k U_j^0 \right\|_{L^\infty(\mathbb{Z})}, \end{aligned}$$

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- i)* $\|U^n\|_{L^1(\mathbb{Z})} \leq \|u_0\|_{L^1(\mathbb{R})},$
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Moreover,

$$\begin{aligned} & \left\| \hat{f}(U_i^n, U_{i+1}^n) - D_+ A(U_i^n) - \sum_{k=-\infty}^i \sum_{j \in \mathbb{Z}} G_j^k U_j^n \right\|_{BV(\mathbb{Z})} \\ & \leq \left\| \hat{f}(U_i^0, U_{i+1}^0) - D_+ A(U_i^0) - \sum_{k=-\infty}^i \sum_{j \in \mathbb{Z}} G_j^k U_j^0 \right\|_{BV(\mathbb{Z})}, \end{aligned}$$

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$$iii) \quad |U^n|_{BV(\mathbb{Z})} \leq |u_0|_{BV(\mathbb{R})}.$$

Consequently,

$$\sum_{i \in \mathbb{Z}} |U_i^m - U_i^n| \leq C \frac{\Delta t}{\Delta x} |m - n|.$$

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$$i) \quad \|U^n\|_{L^1(\mathbb{Z})} \leq \|u_0\|_{L^1(\mathbb{R})},$$

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$$iii) \quad |U^n|_{BV(\mathbb{Z})} \leq |u_0|_{BV(\mathbb{R})}.$$

Consequently,

$$\sum_{i \in \mathbb{Z}} |U_i^m - U_i^n| \leq C \frac{\Delta t}{\Delta x} |m - n|.$$

This implies strong compactness / convergence
of DDG solution $u_{\Delta x}$.

Lemma (diffusion term)

There holds

$$|A(U_i^m) - A(U_j^n)| = \mathcal{O}(1) \left[|i - j| \Delta x + \sqrt{|m - n| \Delta t} \right].$$

Consequently, the limit obeys $A(u) \in C^{1/2,1}(Q_T)$.

Lemma (cell entropy inequality)

$$\eta_i^{n+1} - \eta_i^n + \Delta t D_- Q_i^n - \Delta t D_- D_+ |A(U_i^n) - A(k)| \leq \Delta t \eta'_k(U_i^{n+1}) \mathcal{L}\langle U^n \rangle_i,$$

$$Q_i^n = \hat{f}(U_i^n \vee k, U_{i+1}^n \vee k) - \hat{f}(U_i^n \wedge k, U_{i+1}^n \wedge k)$$

Theorem (convergence).

Suppose $u_0 \in L^1 \cap BV$ is s.t. $|f(u_0) - \partial_x A(u_0)|_{BV} < \infty$.

Let $\hat{u}_{\Delta x}$ be explicit DGG solution.

Then $\{\hat{u}_{\Delta x}\}_{\Delta x > 0}$ converges in L^1_{loc}

to the BV entropy solution of the IPDE.

Numerical examples

- Implemented in the cases $k = 0, 1, 2$.
- Set our numerical solutions to zero outside the region $\Omega = \{(x, t) : |x| \leq 3/2, t \geq 0\}$.

Example. Pure fractional equation $\partial_t u = \mathcal{L}[u]$

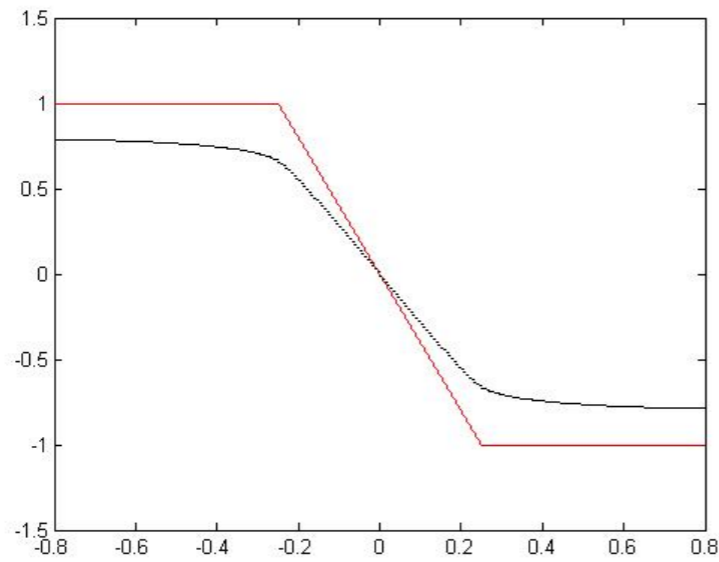
$$\mathcal{L}[\varphi(x)] = c_\lambda \int_{|z|>0} \frac{\varphi(x+z) - \varphi(x)}{|z|^{1+\lambda}} dz$$

Numerical

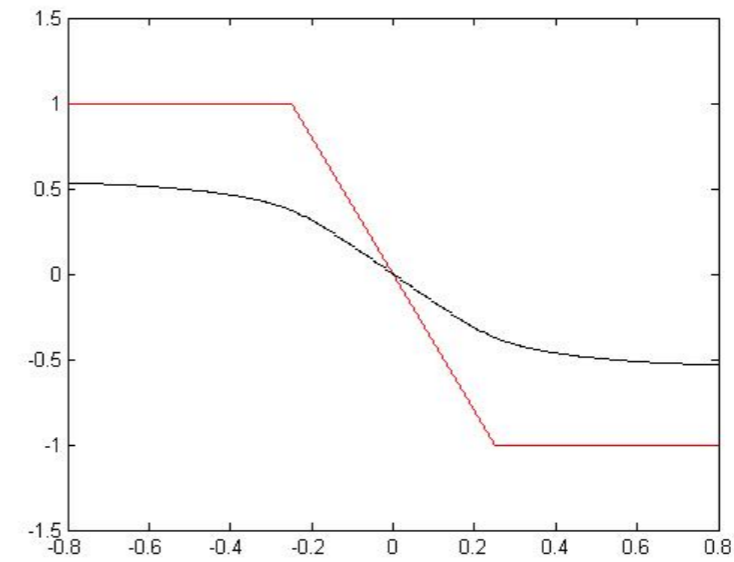
- Implement
- Set of

$$\Omega =$$

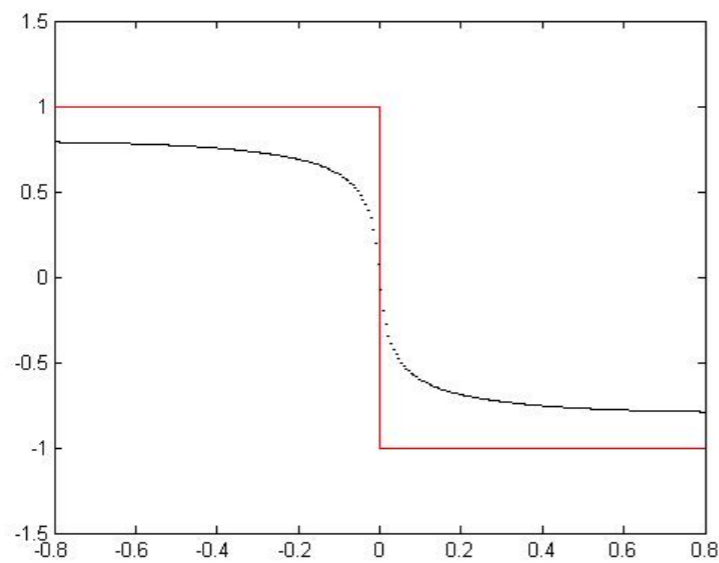
Example



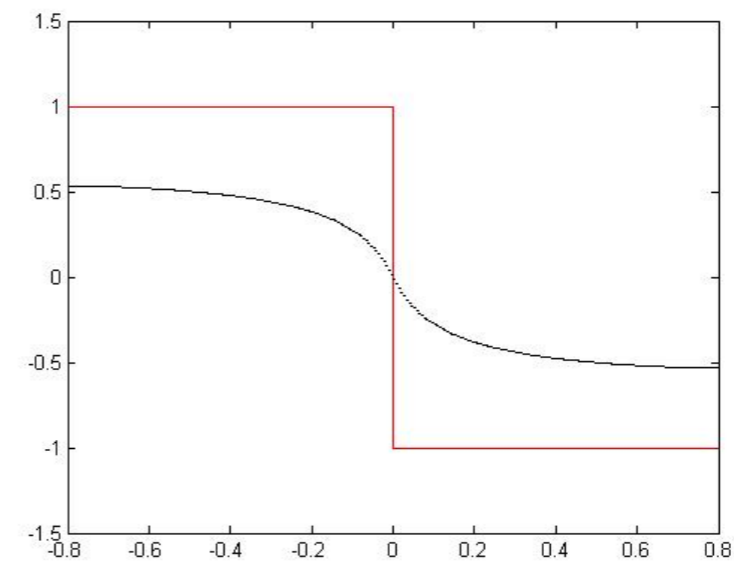
(a) $T = 0.5$



(b) $T = 1.3$



(c) $T = 0.5$



(d) $T = 1.3$

FIGURE 1. Initial data (piecewise linear) and solutions of the pure fractional equation ($\lambda = 0.5$) with $k = 0$ and $\Delta x = 1/160$.

the region

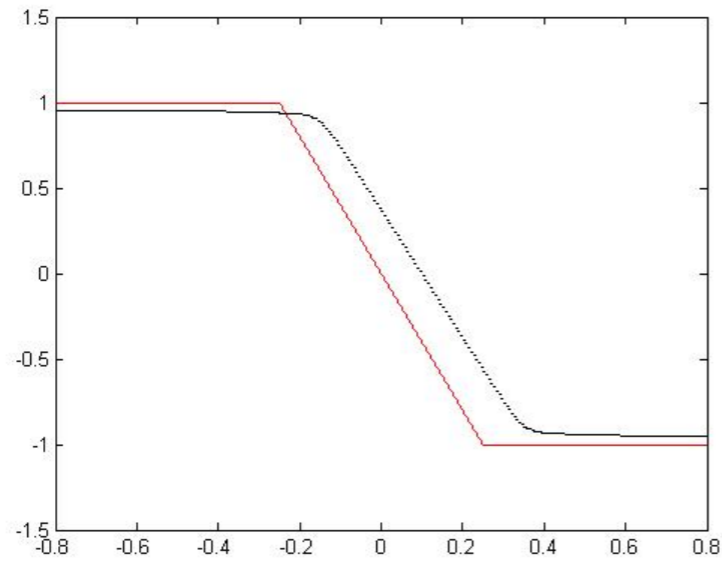
dz

Example. Fractional transport equation

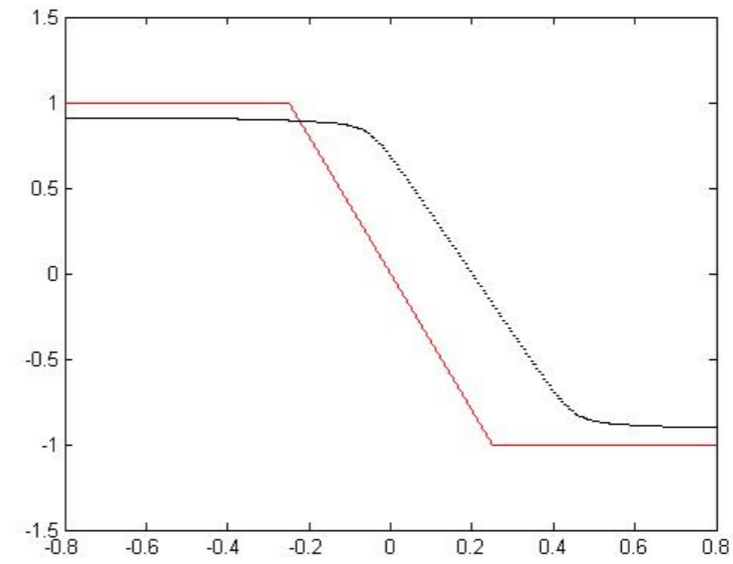
$$\partial_t u + \partial_x u = c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

Solution is smooth.

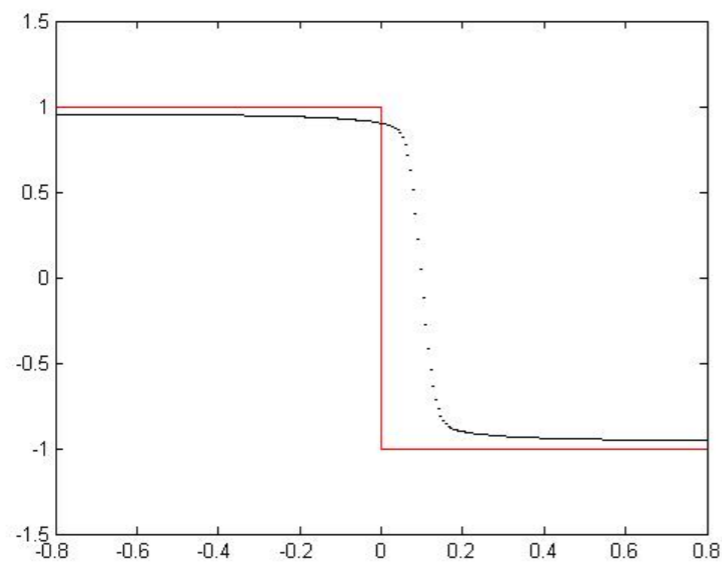
Exam



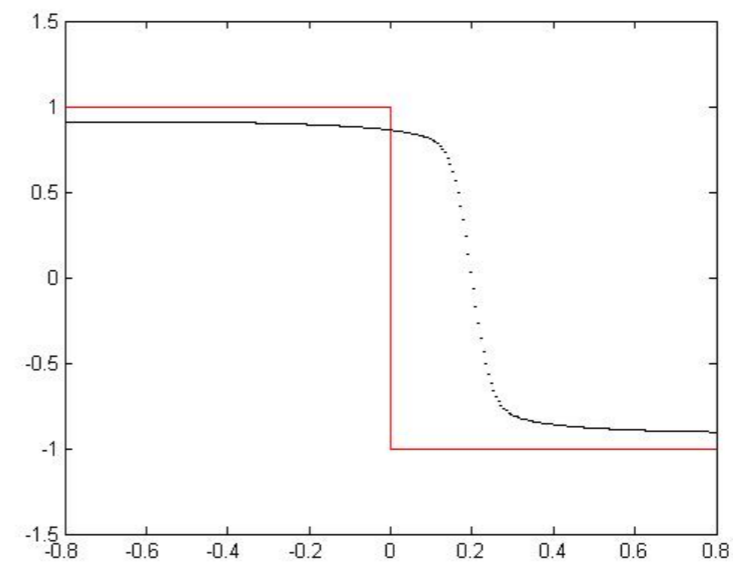
(a) $T = 0.1$



(b) $T = 0.2$



(c) $T = 0.1$



(d) $T = 0.2$

FIGURE 2. Initial data (piecewise linear) and solutions of the fractional transport equation ($\lambda = 0.5$) with $k = 0$ and $\Delta x = 1/160$.

Example. Fractional Burgers' equation

$$\partial_t u + u \partial_x u = c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

Solution not necessarily smooth.

Accuracy improves with $k = 0, 1, 2$.

A third order Runge-Kutta (RK3) time discretization
and slope limiters

Lax-Friedrichs flux $F(a, b) = \frac{1}{2}[f(a) + f(b) - c(b - a)],$

$$c = \max\{|f'(a)| : |a| \leq \|u_0\|_{L^\infty(\mathbb{R})}\}.$$

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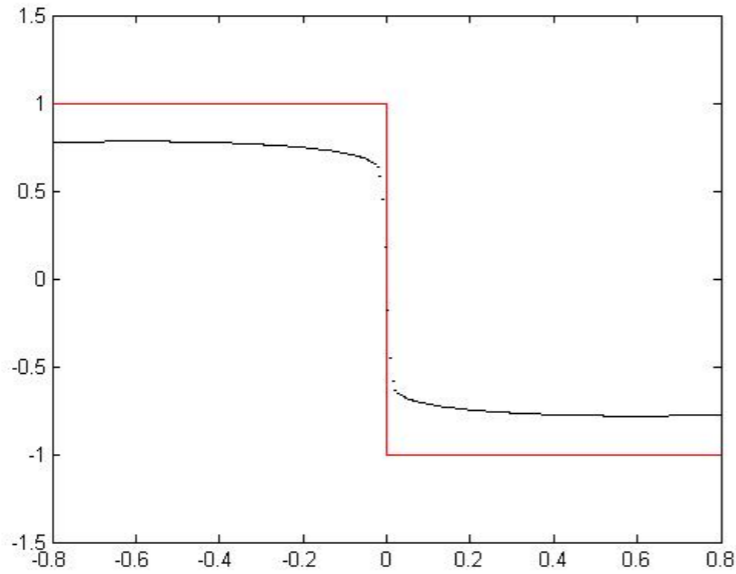
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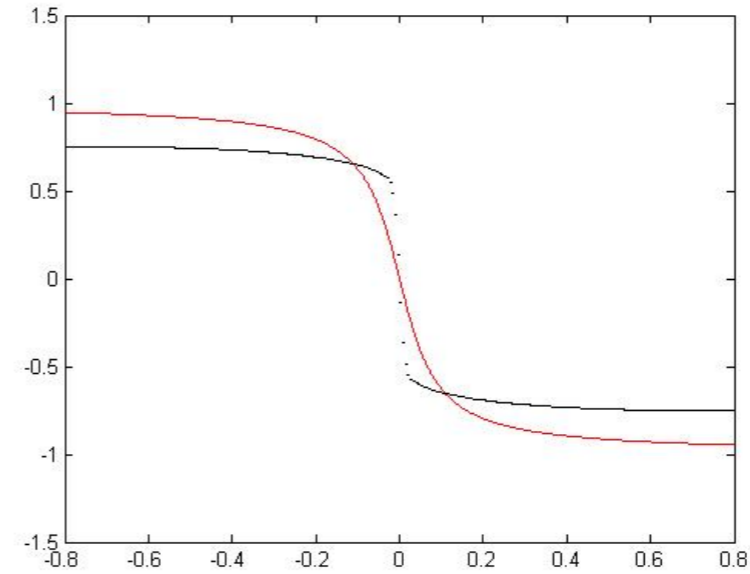
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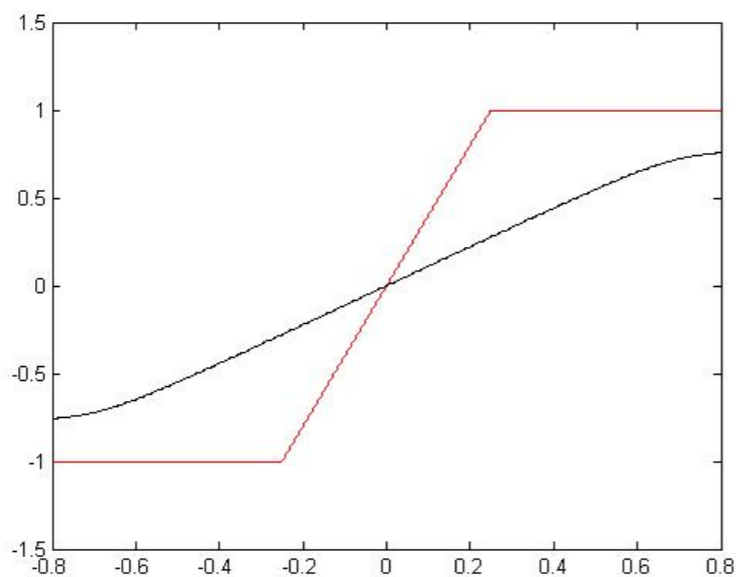
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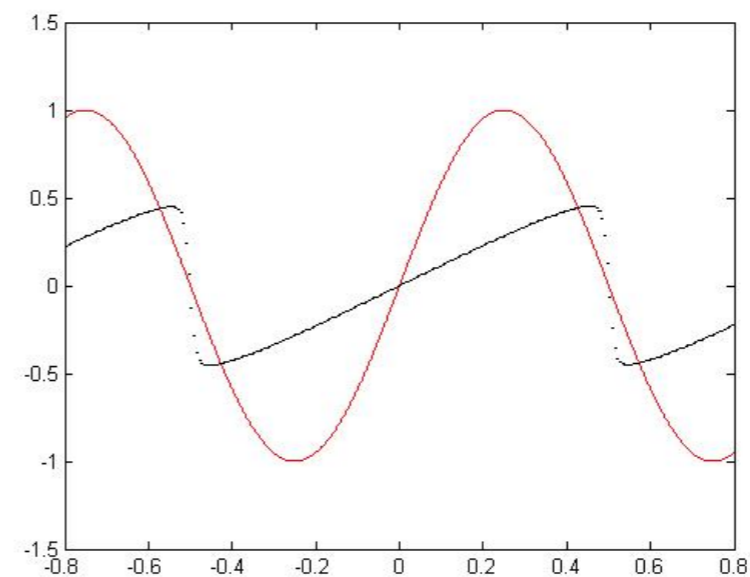
(a) $u_0(x) = -\text{sgn}(x)$



(b) $u_0(x) = -\arctan(15x)/90$



(c) $u_0(x) = \text{sgn}(x)\mathbf{1}_{|x|>1/4} + 4x\mathbf{1}_{|x|\leq 1/4}$



(d) $u_0(x) = \sin(2\pi x)$

FIGURE 3. Initial data and solutions of the fractional Burgers' equation ($\lambda = 0.5$) using $k = 0$; $T = 0.5$ and $\Delta x = 1/160$.

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Example. Fractional Burgers' equation

$$\partial_t u + u \partial_x u = c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

Solution not necessarily smooth.

Accuracy improves with $k = 0, 1, 2$.

A third order Runge-Kutta (RK3) time discretization
and slope limiters

Lax-Friedrichs flux $F(a, b) = \frac{1}{2}[f(a) + f(b) - c(b - a)],$

$$c = \max\{|f'(a)| : |a| \leq \|u_0\|_{L^\infty(\mathbb{R})}\}.$$

Example

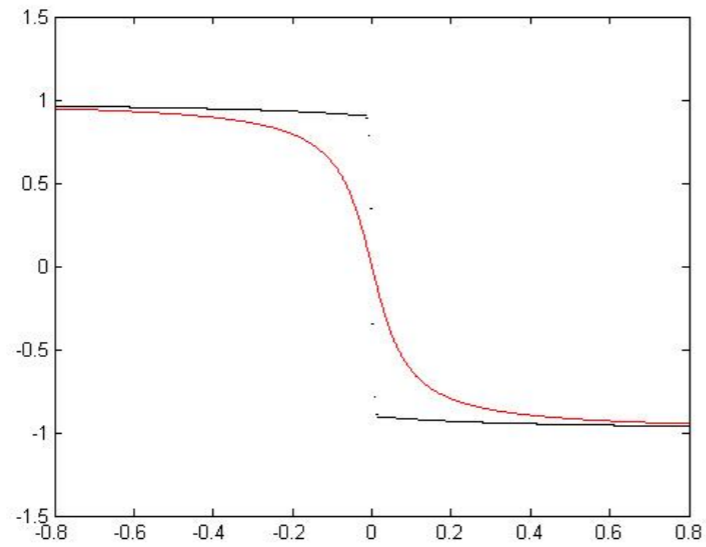
Solution

Accuracy

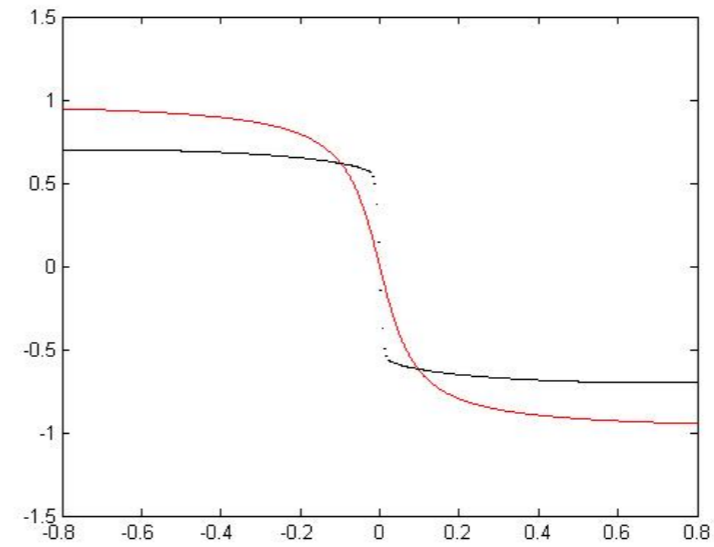
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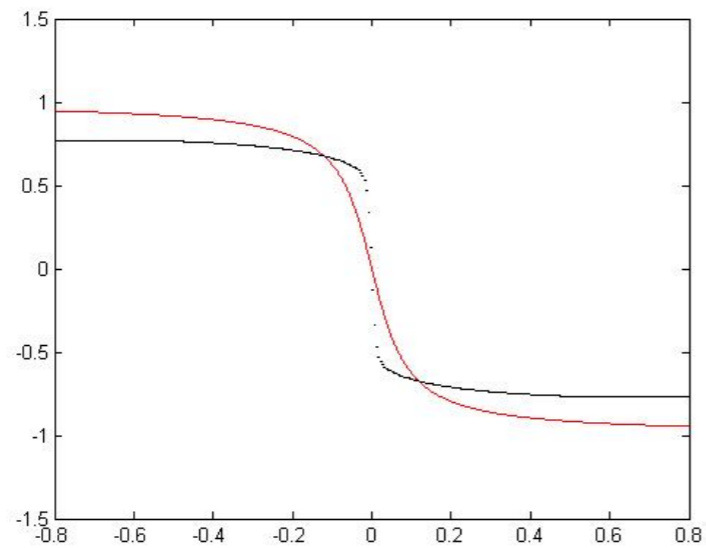
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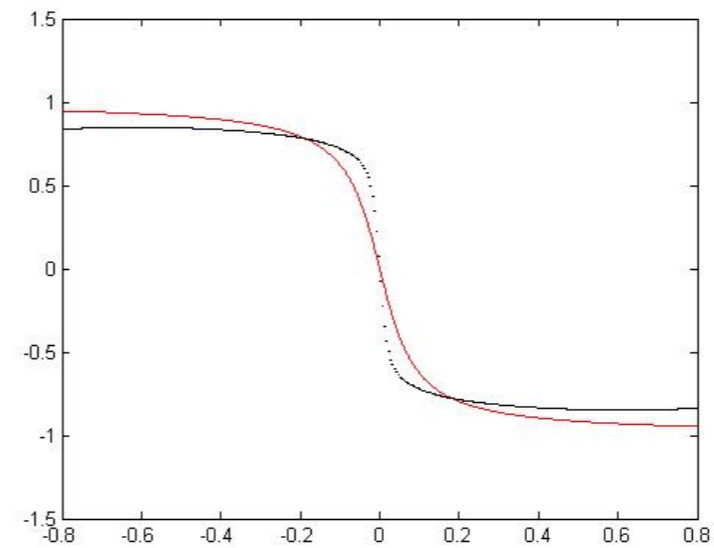
(a) $\lambda = 0.1$



(b) $\lambda = 0.3$



(c) $\lambda = 0.7$



(d) $\lambda = 0.99$

FIGURE 4. Initial data and solutions of the fractional Burgers' equation for different values of λ using $k = 0$; $T = 0.5$, $\Delta x = 1/200$, and $u_0(x) = -\arctan(15x)/90$.

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Example. Fractional Burgers' equation

$$\partial_t u + u \partial_x u = c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

Solution not necessarily smooth.

Accuracy improves with $k = 0, 1, 2$.

A third order Runge-Kutta (RK3) time discretization
and slope limiters

Lax-Friedrichs flux $F(a, b) = \frac{1}{2}[f(a) + f(b) - c(b - a)],$

$$c = \max\{|f'(a)| : |a| \leq \|u_0\|_{L^\infty(\mathbb{R})}\}.$$

Example

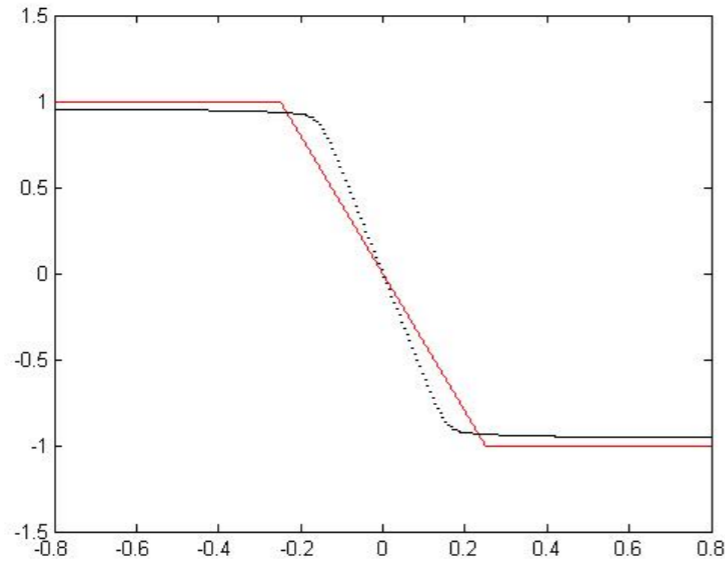
Solution

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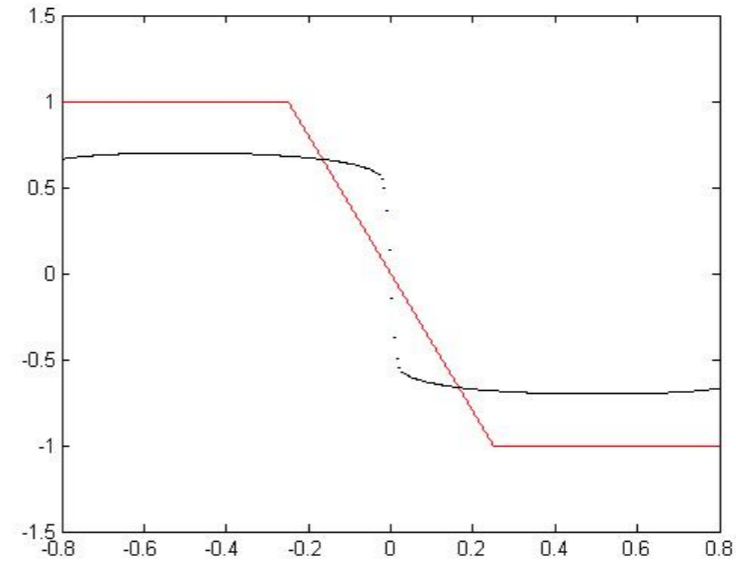
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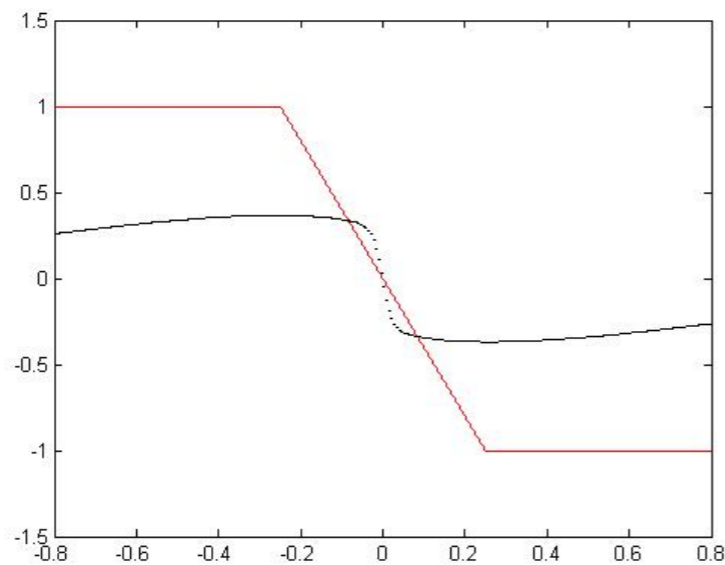
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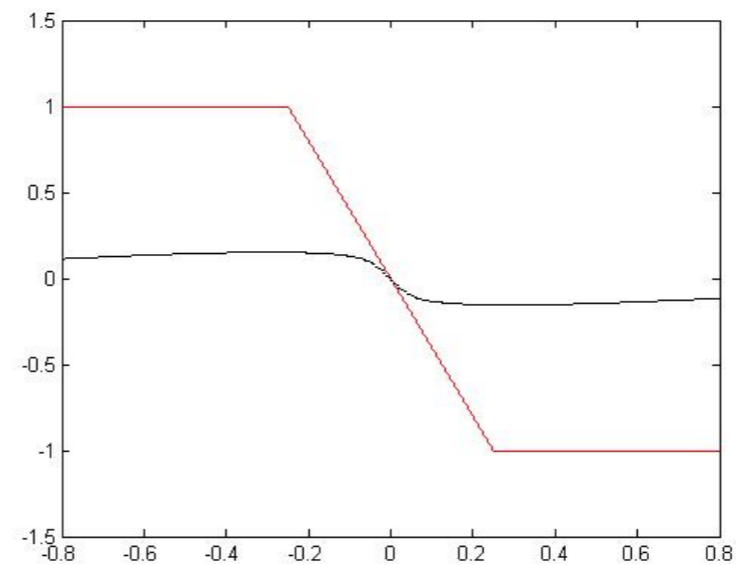
(a) $T = 0.1$



(b) $T = 0.7$



(c) $T = 1.7$



(d) $T = 2.9$

FIGURE 5. Initial data (piecewise linear) and solutions of the fractional Burgers' equation ($\lambda = 0.5$) at different times T using $k = 0$; $\Delta x = 1/200$.

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Example. Fractional Burgers' equation

$$\partial_t u + u \partial_x u = c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

Solution not necessarily smooth.

Accuracy improves with $k = 0, 1, 2$.

A third order Runge-Kutta (RK3) time discretization
and slope limiters

Lax-Friedrichs flux $F(a, b) = \frac{1}{2}[f(a) + f(b) - c(b - a)],$

$$c = \max\{|f'(a)| : |a| \leq \|u_0\|_{L^\infty(\mathbb{R})}\}.$$

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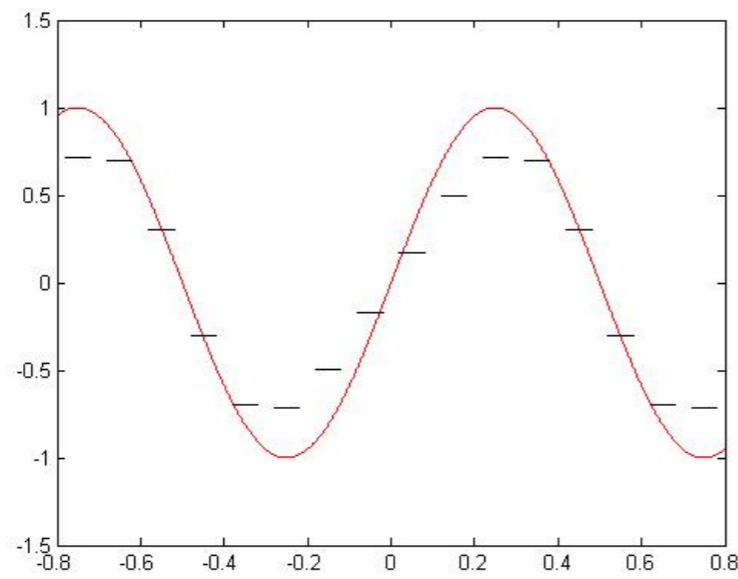
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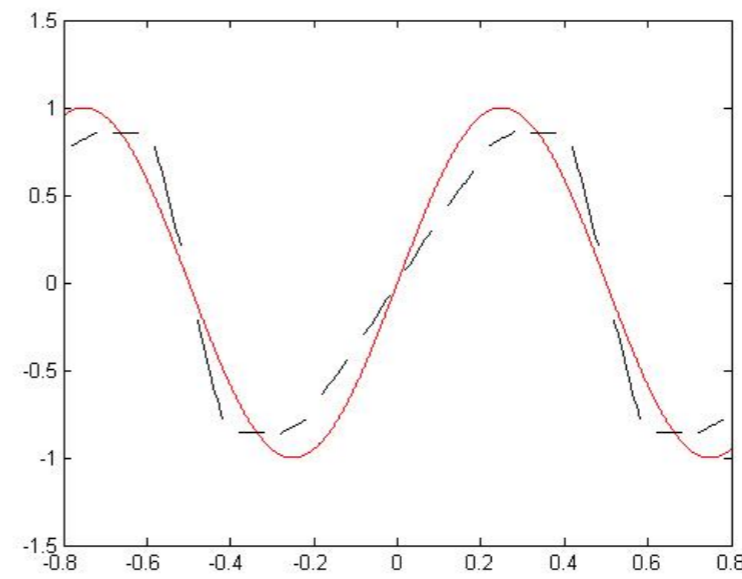
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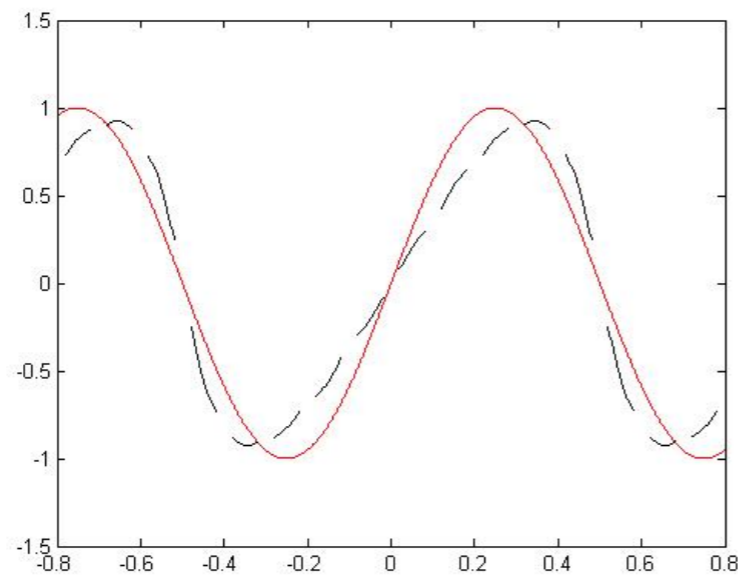
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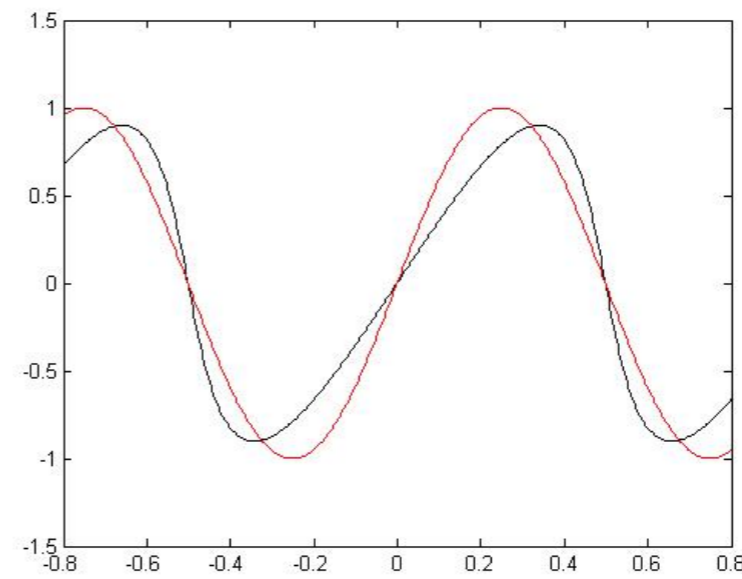
(a) $k = 0$



(b) $k = 1$



(c) $k = 2$



(d) Solution computed using $\Delta x = 1/640$

FIGURE 6. Initial data and solutions of the fractal Burgers' equation at $T = 1/10$ using different values of $k = 0, 1, 2$; $\Delta x = 1/10$, and $u_0(x) = \sin(2\pi x)$.

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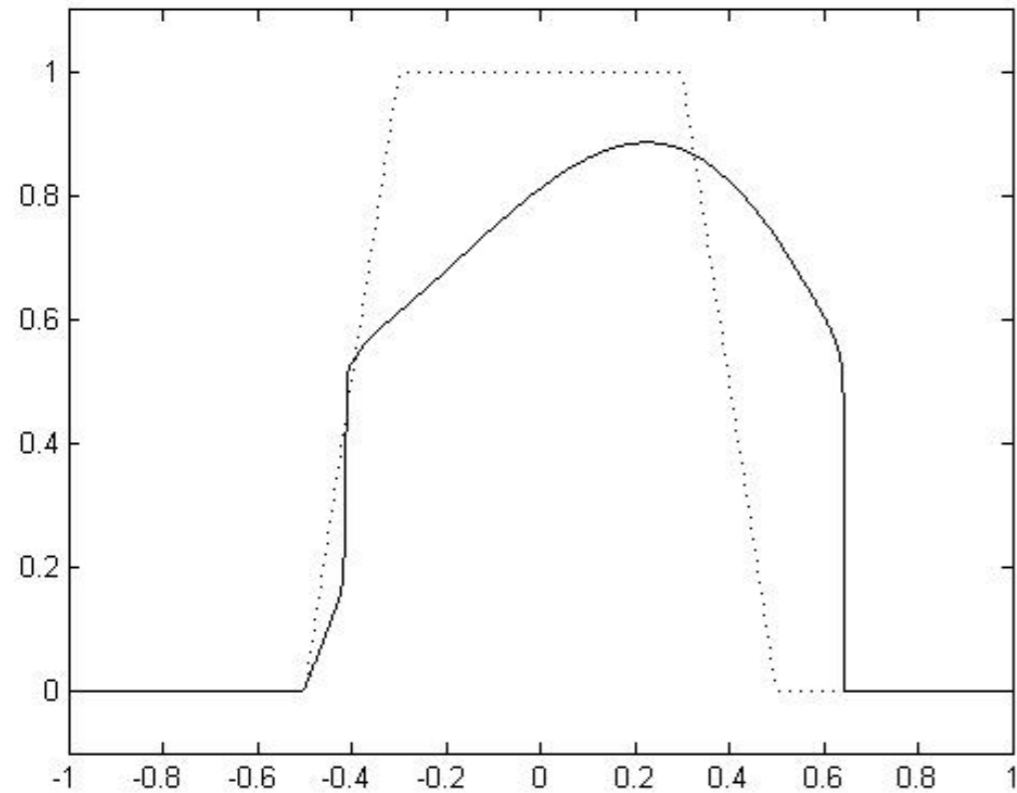
$\mathcal{L}^\infty(\mathbb{R})$ }.

Example. Convection / diffusion / fractional diffusion

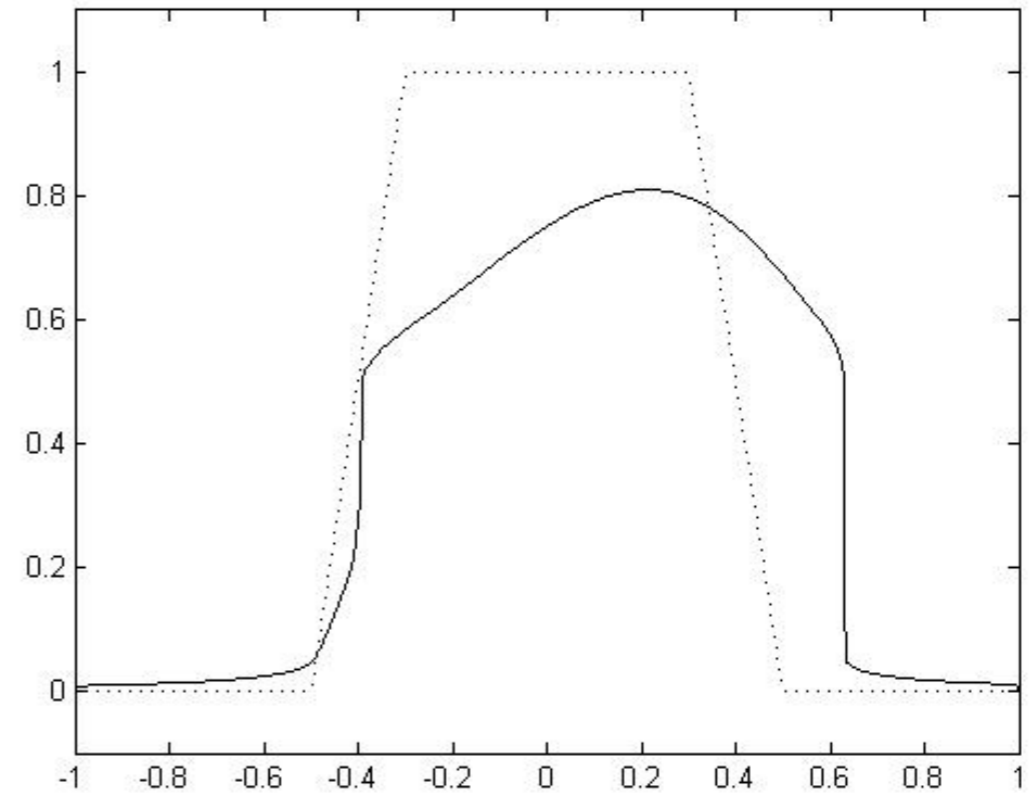
$$\partial_t u + \partial_x u^2 = \partial_x (a(u) \partial_x u) + c_\lambda \int_{|z|>0} \frac{u(t, x+z) - u(t, x)}{|z|^{1+\lambda}} dz$$

$$a(u) = \begin{cases} 0 & \text{for } u \leq 0.5 \\ 2.5u - 1.25 & \text{for } 0.5 < u \leq 0.6 \\ 0.25 & \text{for } u > 0.6, \end{cases}$$

Example. Convection / diffusion / fractional diffusion



(a) $u_t + f(u)_x = (a(u)u_x)_x$



(b) Equation (1.1) with $\lambda = 0.5$

FIGURE 1. (Ex.1): $T = 0.15$ and $\Delta x = 1/640$.