

Nonlocal models : from dune morphodynamics to signal processing.

Pascal AZERAD and Afaf BOUHARGUANE

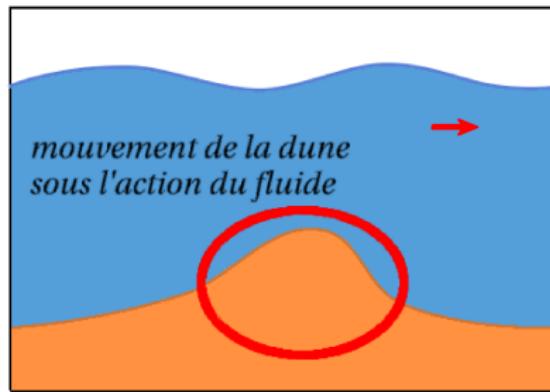
I3M, Université de Montpellier 2

Outline

- 1 A nice and strange PDE for morphodynamics.
- 2 Where does the strange nonlocal term come from ?

A nice and strange PDE for morphodynamics.

Dune morphodynamics



Dune profile $u(t, x)$ satisfies Fowler's equation

$$\begin{cases} u_t(t, x) + u u_x(t, x) + \int_0^{+\infty} s^{-\frac{1}{3}} u_{xx}(t, x - s) ds - u_{xx}(t, x) &= 0, \\ u(0, x) &= u_0(x) \end{cases}$$

A conservative nonlinear nonlocal and non-monotone model

$$\begin{cases} \partial_t u + \partial_x \left(\left(\frac{u^2}{2} \right) + \int_0^{+\infty} s^{-\frac{1}{3}} u_x(t, x-s) ds - u_x \right) = 0, \\ u(0, x) = u_0(x) \end{cases}$$

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Main results

- Existence, uniqueness and continuous dependence of the solution u w.r.t. initial datum in $L^2(\mathbb{R})$
- Maximum principle **violation** \Rightarrow can describe both **erosion and accretion** phenomena, contrary to hyperbolic models.
- Existence of **travelling waves** $u(x, t) = \varphi_c(x - c t)$, (may **not** be of **solitary** type). Local existence and uniqueness for initial datum in C_b^1

N. Alibaud, P. Azerad, D. Isèbe, *A non-monotone conservation law for dune morphodynamics*, Differential Integral Equations, 2010.

B. Alvarez-Samaniego, P. Azerad, *Travelling wave solutions of the Fowler equation*, Discrete and Continuous Dynamical Systems, B, 2009.

Some expressions for the non local term \mathcal{I}

$$\mathcal{I}[\varphi](x) = \int_0^{+\infty} s^{-\frac{1}{3}} \varphi_{xx}(x-s) ds$$

Lévy-Khintchine

For all $\varphi \in S(\mathbb{R})$ and $x \in \mathbb{R}$,

$$\mathcal{I}[\varphi](x) = \frac{4}{9} \int_0^{\infty} \frac{\varphi(x-s) - \varphi(x) - \varphi'(x)s}{s^{7/3}} ds.$$

- └ A nonlocal PDE

- └ Fowler's equation

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in Fourier variable

For all $\varphi \in \mathcal{S}(\mathbb{R})$ and $\xi \in \mathbb{R}$,

$$\mathcal{F}(\mathcal{I}[\varphi] - \varphi'')(\xi) = \left(\xi^2 - (a \pm ib)|\xi|^{\frac{4}{3}} \right) \mathcal{F}(\varphi)(\xi)$$

$$(a \pm ib) = \Gamma(2/3) \left(1/2 + i \operatorname{sgn}(\xi) \sqrt{3}/2 \right)$$

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- \mathcal{I} anti-diffusive differential operator of order $\frac{4}{3}$
- $\sim \xi^2$ when $|\xi| \rightarrow +\infty$
regularizing effect on initial datum

Existence, uniqueness and regularity.

Theorem

Let $T > 0$ and $u_0 \in L^2(\mathbb{R})$. There exists a *unique mild solution*
 $u \in L^\infty((0, T); L^2(\mathbb{R}))$. Moreover,

- i) $u \in C^\infty((0, T] \times \mathbb{R})$ and for all $t_0 \in (0, T]$, u as well as its derivatives of any order belong to $C([t_0, T]; L^2(\mathbb{R}))$.
- ii) u satisfies $u_t + (\frac{u^2}{2})_x + \mathcal{I}[u] - u_{xx} = 0$, on $(0, T] \times \mathbb{R}$, in the classical sense.
- iii) $u \in C([0, T]; L^2(\mathbb{R}))$ et $u(0, \cdot) = u_0$ a.e.

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- iii) $u \in C([0, T]; L^2(\mathbb{R}))$ et $u(0, \cdot) = u_0$ a.e.

Continuous dependence

Let two solutions (u, v) with initial data (u_0, v_0) in $L^2(\mathbb{R})$. Then, u and v fulfill

$$\|u - v\|_{C([0, T]; L^2(\mathbb{R}))} \leq C(T, \|u_0\|_{L^2(\mathbb{R})}, \|v_0\|_{L^2(\mathbb{R})}) \|u_0 - v_0\|_{L^2(\mathbb{R})}$$

The linearized problem

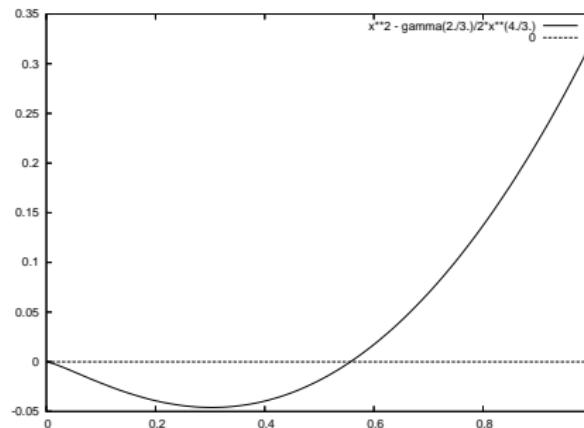
- Solution given by

$$u(t, x) = K(t, \cdot) * u_0(x).$$

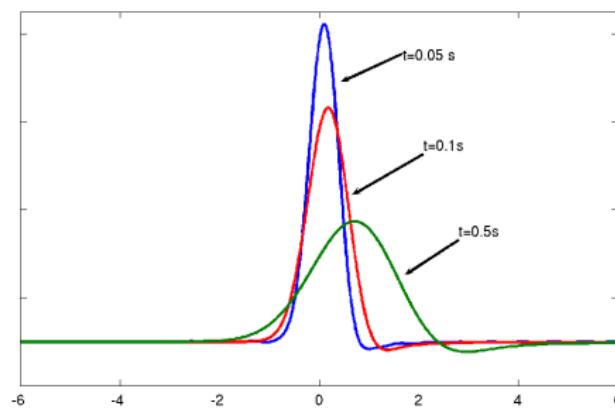
where the **kernel**

$$\mathcal{F}(K(t, \cdot))(\xi) := \exp\left(-t\left(\xi^2 - a|\xi|^{\frac{4}{3}} + i b \xi |\xi|^{\frac{1}{3}}\right)\right), \quad t > 0$$

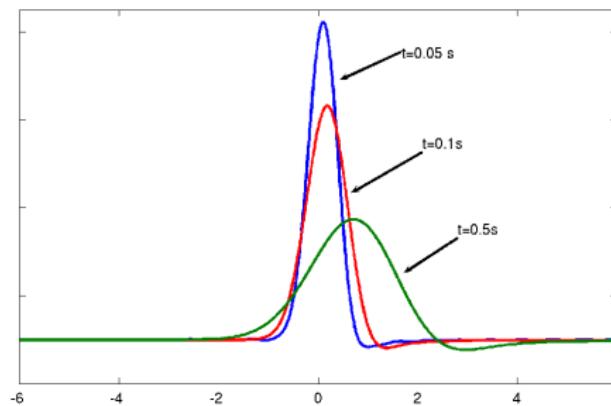
$$\psi(\xi) = \xi^2 - a|\xi|^{\frac{4}{3}}.$$



$K(\cdot, t)$ is not positive



$K(\cdot, t)$ is not positive



No maximum principle for $u_t + \mathcal{I}[u] - u_{xx} = 0$ but

$$\|K(t, \cdot) * u_0\|_{L^2(\mathbb{R})} \leq e^{\omega_0 t} \|u_0\|_{L^2(\mathbb{R})}$$

where $\omega_0 = -\min \psi$.

- └ A nonlocal PDE

- └ Fowler's equation

Properties of $K(t, \cdot)$, $t > 0$

- **C^0 - Semi-group :**

$$\begin{aligned} K(t) * K(s) &= K(t + s) \\ \forall u_0 \in L^2(\mathbb{R}), \quad \lim_{t \rightarrow 0} K(t) * u_0 &= u_0 \text{ in } L^2(\mathbb{R}). \end{aligned}$$

- **Regularity :**

$$K(t, x) \in C^\infty((0, +\infty) \times \mathbb{R})$$

- **Estimates for the gradient :**

$$\|\partial_x K(t)\|_{L^2(\mathbb{R})} \leq C t^{-\frac{3}{4}}$$

$$\|\partial_x K(t)\|_{L^1(\mathbb{R})} \leq C t^{-\frac{1}{2}}$$

Mild solution

Definition

Let $T > 0$ and $u_0 \in L^2(\mathbb{R})$. We say that $u \in L^\infty((0, T); L^2(\mathbb{R}))$ is a *mild solution* if for a.e. $t \in (0, T)$ and $x \in \mathbb{R}$,

$$u(t, x) = K(t, \cdot) * u_0(x) - \frac{1}{2} \int_0^t \partial_x K(t-s, \cdot) * u^2(s, \cdot)(x) ds.$$

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\Rightarrow local existence by contracting fixed point .

- └ A nonlocal PDE

- └ Fowler's equation

L^2 a priori estimate

$$\frac{d}{dt} \frac{1}{2} \int_{\mathbb{R}} u^2 dx + \int_{\mathbb{R}} (\mathcal{I}[u] - \partial_{xx}^2 u) u dx = 0.$$

$$\int_{\mathbb{R}} (\mathcal{I}[u] - \partial_{xx}^2 u) u dx = \int_{\mathbb{R}} \psi(\xi) |\mathcal{F}u(\xi)|^2 d\xi$$

$$\frac{d}{dt} \frac{1}{2} \int_{\mathbb{R}} u^2 dx \leq \omega_0 \int_{\mathbb{R}} u^2 dx$$

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where $\omega_0 = -\min \psi$.
⇒ global existence.

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⇒ global existence .

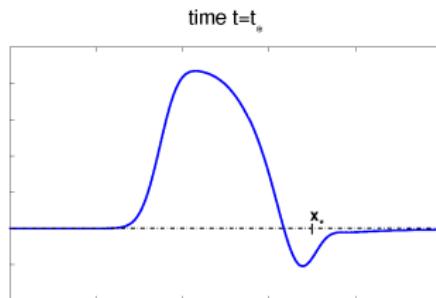
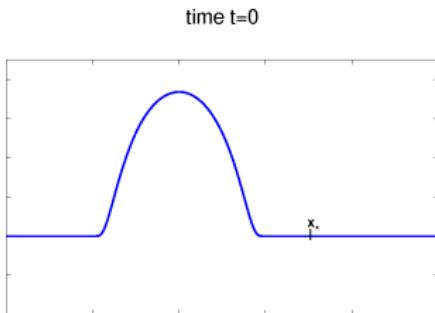
Violation of Maximum principle

Theorem

Let $u_0 \in C^2(\mathbb{R}) \cap H^2(\mathbb{R})$ positive such that there exists $x_* \in \mathbb{R}$ with $u_0(x_*) = u'_0(x_*) = u''_0(x_*) = 0$ and

$$\int_0^\infty \frac{u_0(x_* - s)}{s^{7/3}} ds > 0.$$

then there exists $t_* > 0$ such that $u(t_*, x_*) < 0$.



Travelling waves

- Existence but may not be solitary and $\notin L^2$
- Local existence theory in C_b^1
- global existence theory in C_b^1 ??? OPEN

Let $\lambda > 0$ and $\eta > 0$. Define

$$u_{\lambda}(x, t) := \frac{1}{\lambda} u\left(\frac{x}{\lambda}, \frac{t}{\lambda^2}\right), \text{ for } x \in \mathbb{R} \text{ and } t \geq 0. \quad (1)$$

It is straightforward to check that if u is a solution to the **general** equation

$$\partial_t u(x, t) + \partial_x \left(\frac{u^2}{2} - \partial_x u + \eta g[u] \right)(x, t) = 0, \quad (2)$$

then u_{λ} satisfies equation (3).

$$\partial_t u(x, t) + \partial_x \left(\frac{u^2}{2} - \partial_x u + \lambda^{-2/3} \eta g[u] \right)(x, t) = 0, \quad (3)$$

$\eta = 1$: Fowler's equation, $\eta = 0$: viscous Burgers equation

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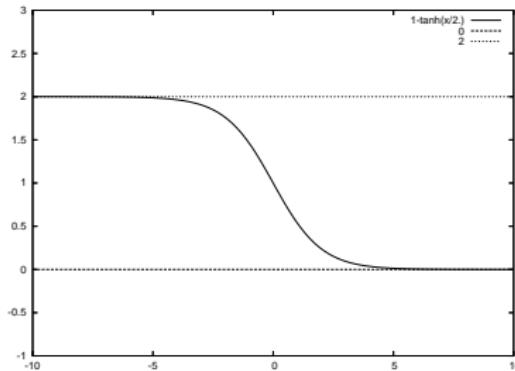
$\eta = 1$: **Fowler's equation**, $\eta = 0$: **viscous Burgers equation**

- └ A nonlocal PDE

- └ Fowler's equation

Case $\eta = 0$: For any $c \in \mathbb{R}$ the Taylor shock wave

$u_c(x, t) = c \left[1 - \tanh\left(\frac{c}{2}(x - c t)\right) \right]$ is a travelling wave solution to viscous Burgers equation.



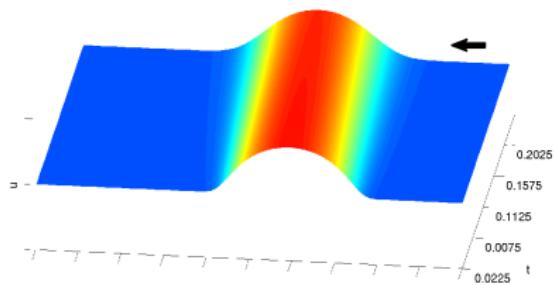
By **implicit function theorem**, it is possible to build travelling wave solution ϕ of equation (2) with speed c for very **small** η . Then by **suitable scaling**, then $\phi_\lambda(\cdot) = \frac{1}{\lambda}\phi(\frac{1}{\lambda}\cdot)$ is a travelling-wave solution of Fowler's equation (case $\eta = 1$) with speed c/λ .

Stability of the travelling waves

Ph. D. thesis A. Bouharguane,

- Global existence , uniqueness, regularity, continuous dependence for L^2 - initial **perturbation** of a C_b^1 solution
- **Instability of constant solutions** , no flat bathymetry in nature !
- according to **frequency of perturbation** : quick **dampening** of **high frequencies**, slow **amplification of low frequencies** !

some numerical simulations



viscous Burgers equations

$$\partial_t u + \partial_x \left(\frac{u^2}{2} \right) - \partial_{xx}^2 u = 0$$

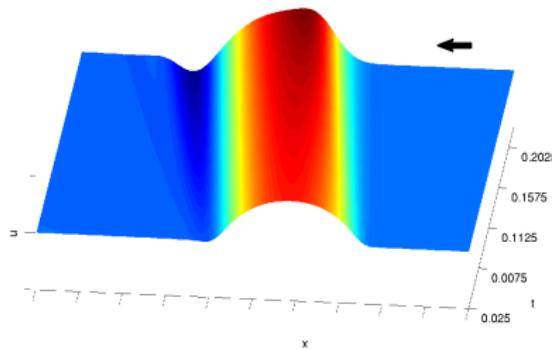
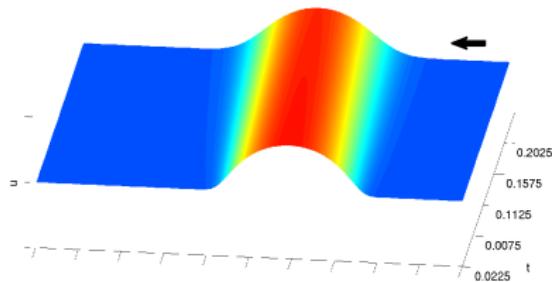
centered FD scheme

stability : CFL-Péclet

- └ A nonlocal PDE

- └ Numerical simulations.

some numerical simulations



non-local term creates erosion and accretion

$$\partial_t u + \partial_x \left(\frac{u^2}{2} + g[u] \right) - \partial_{xx}^2 u = 0$$

with

$$g[u](x) := \int_0^{+\infty} s^{-\frac{1}{3}} u_x(x-s) ds.$$

$$g[u_i^n] \approx \sum_{j=0}^i |j \Delta x|^{-\frac{1}{3}} \frac{(u_{i-j+1}^n - u_{i-j-1}^n)}{2}$$

- └ A nonlocal PDE

- └ Numerical simulations.

Application to Signal Processing.

$$\begin{cases} \partial_t u(t, x) - \textcolor{blue}{a} \partial_{xx}^2 u(t, x) + \textcolor{red}{b} \mathcal{I}_{\textcolor{green}{\lambda}}[u(t, .)](x) = 0 & t \in (0, T), x \in \mathbb{R}, \\ u(0, x) = u_0(x) & x \in \mathbb{R}, \end{cases} \quad (4)$$

where $0 < \textcolor{green}{\lambda} < 2$

$$\mathcal{F}(\mathcal{I}_{\lambda}[\varphi])(\xi) := -|\xi|^{\lambda} \mathcal{F}(\varphi)(\xi) \quad (5)$$

For $1 < \textcolor{green}{\lambda} < 2$, explicit formula (Imbert, JDE, 2005)

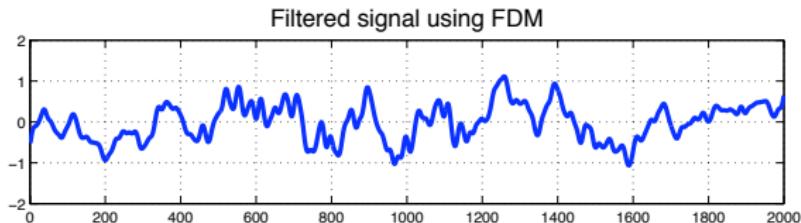
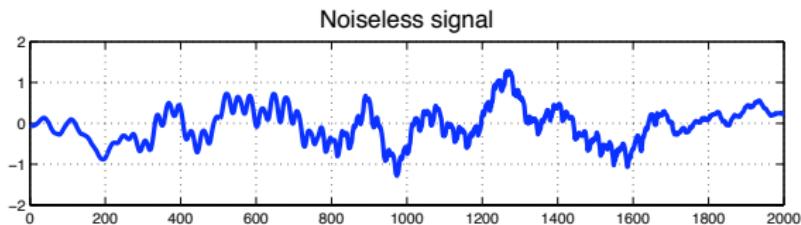
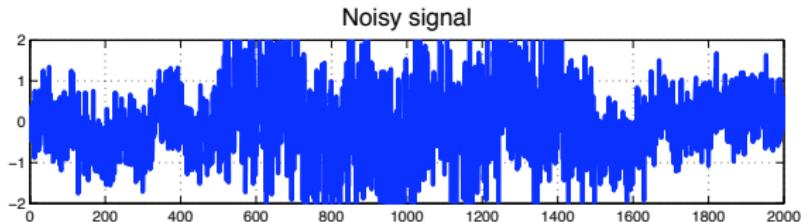
$$\mathcal{I}_{\lambda}[\varphi](x) = \int_{\mathbb{R}} \frac{\varphi''(x-s)}{|s|^{\lambda-1}} d\xi \quad (6)$$

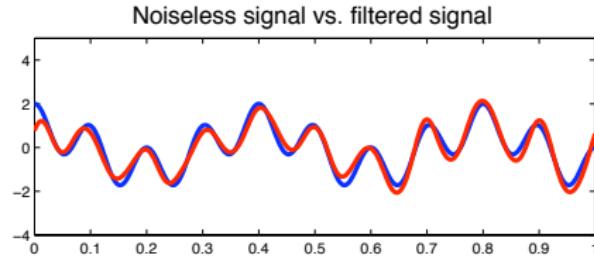
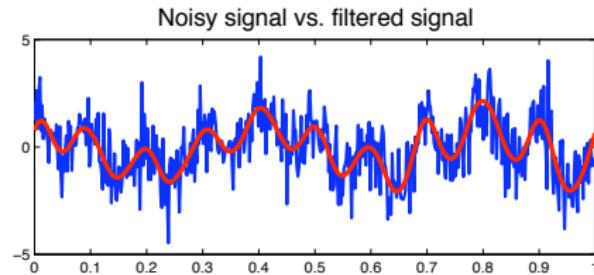
Alternatively, (slightly different definition inspired by **fractional calculus**) :

$$\mathcal{I}_{\lambda}[\varphi](x) = \int_0^{+\infty} \frac{\varphi''(x-s)}{|s|^{\lambda-1}} d\xi. \quad (7)$$

└ A nonlocal PDE

└ Numerical simulations.

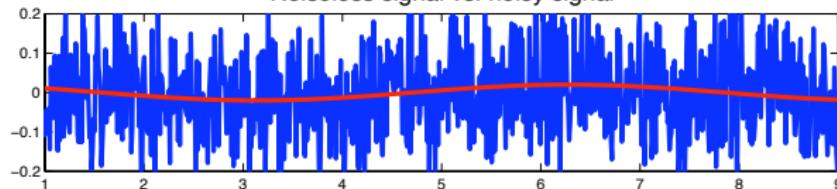




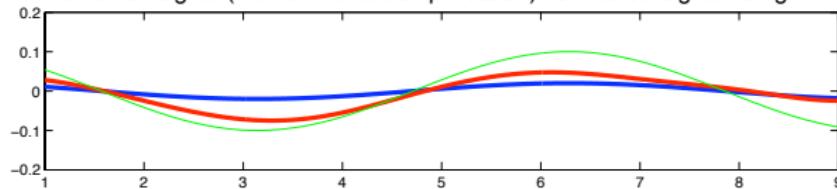
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- └ Numerical simulations.

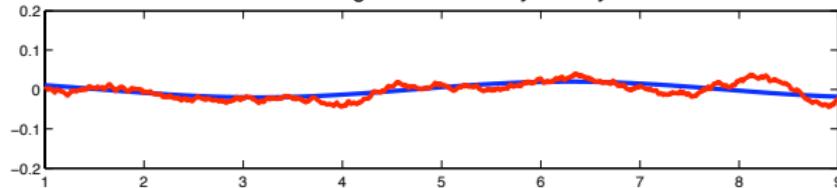
Noiseless signal vs. noisy signal



Noiseless signal (with or without amplification) vs. filtered signal using FFT



Noiseless signal vs. Savitzky–Golay filter



Where does the strange nonlocal term come
from ?

Define the antiderivative

$$\frac{d^{-1}f}{dx^{-1}} = \int_0^x f(t) dt$$

Again

$$\frac{d^{-2}f}{dx^{-2}} = \int_0^x \int_0^t f(s) ds dt = \int \int_{0 < s < t < x} f(s) ds dt = \int_0^x f(s) \left(\int_s^x dt \right) ds$$

$$\frac{d^{-2}f}{dx^{-2}} = \int_0^x f(s)(x-s) ds$$

And again

$$\frac{d^{-3}f}{dx^{-3}} = \int_0^x \int_0^u \int_0^t f(s) ds dt du = \int \int \int_{0 < s < t < u < x} f(s) ds dt du$$

$$= \int_0^x f(s) \left(\int \int_{s < t < u < x} du dt \right) ds = \int_0^x f(s) \left(\int_s^x (x-t) dt \right) ds$$

$$\frac{d^{-3}f}{dx^{-3}} = \int_0^x f(s) \frac{(x-s)^2}{2!} ds$$

What is the link with our nonlocal term ?

This can be extended for real negative exponents : [Riemann Liouville](#) formula (circa 1847, “Versuch einer Auffassung der Integration und Differentiation”).

$$\frac{d^{-q}f}{dx^{-q}}(x) = \int_0^x f(s) \frac{(x-s)^{q-1}}{\Gamma(q)} ds$$

Rediscovered many times, see e.g. [Caputo's differintegral](#)

Other generalization possible, see e.g. Oldham and Spanier, “the fractional calculus”, Academic Press, 1974

Now take f causal, i.e. $f(t) = 0$, $\forall t < 0$. Compute the $4/3 = 2 - 2/3$ derivative (right way) :

$$\frac{d^{4/3}}{dx^{4/3}} f(x) = \frac{d^{-2/3}}{dx^{-2/3}} f'' = \int_0^x f''(s) \frac{(x-s)^{-1/3}}{\Gamma(2/3)} ds = \int_{-\infty}^x f''(s) \frac{(x-s)^{-1/3}}{\Gamma(2/3)} ds$$

$$\frac{d^{4/3}}{dx^{4/3}} f(x) = \frac{1}{\Gamma(2/3)} \int_0^{+\infty} f''(x-s) s^{-1/3} ds$$

Modelling

English school asymptotics, Fowler, Oxford¹

$$\text{Couette flow over a bump. } U' = U/h, \quad Re = \frac{UL}{h} \frac{L}{\nu} = \frac{U'L^2}{\nu}$$

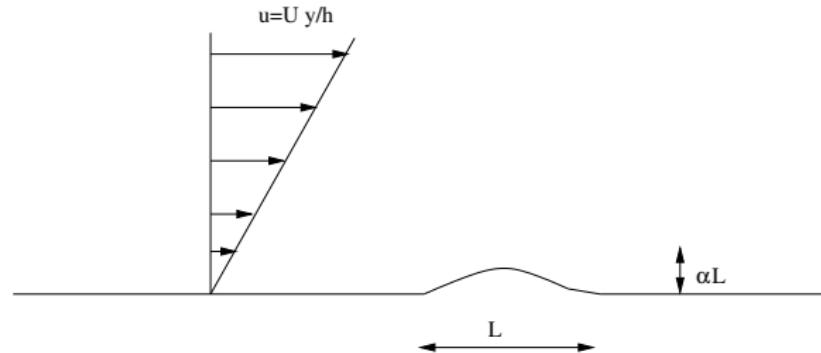


FIGURE: Shear flow perturbed by a small bump $\alpha \ll 1$.

suitable scaling : Double Deck theory Van Dyke, thin layer of size ϵ

1. thanks to P.-Y. Lagrée for french rigorous explanations.

Principle of least degeneracy :

Stretch the vertical scale

$$x = \bar{x}, \quad y = \epsilon \bar{y}, \quad u = \epsilon \bar{u}$$

Balance of convective term and diffusive terms reads

$$u \frac{\partial u}{\partial x} \sim \frac{1}{Re} \frac{\partial^2 u}{\partial y^2}$$

$$\epsilon^2 \bar{u} \frac{\partial \bar{u}}{\partial \bar{x}} \sim \frac{\epsilon}{\epsilon^2} \frac{1}{Re} \frac{\partial^2 \bar{u}}{\partial \bar{y}^2}$$

$$\epsilon \sim Re^{-1/3}$$

Prandtl equations

$$v = \epsilon^2 \bar{v}, \quad p = \epsilon^2 \bar{p}$$

Dropping bars

$$\begin{cases} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} &= 0 \\ u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} &= -\frac{\partial p}{\partial x} + \frac{\partial^2 u}{\partial y^2} \\ 0 &= -\frac{\partial p}{\partial y} \end{cases}$$

Boundary conditions :

- **bottom** no slip $u = v = 0$ on $y = f(x)$
- **far upstream** no perturbation $u \rightarrow y$ when $x \rightarrow -\infty$,
- **matching** $u \rightarrow y$ when $y \rightarrow \infty$

Linearization

Bump is **small** $\Rightarrow f(x) = \alpha f_1$ with $\alpha \leq \epsilon \ll 1$.

$$u = y + \alpha u_1, \quad v = \alpha v_1 \quad p = \alpha p_1$$

$$\begin{cases} \frac{\partial u_1}{\partial x} + \frac{\partial v_1}{\partial y} &= 0 \\ y \frac{\partial u_1}{\partial x} + v_1 &= -\frac{\partial p_1}{\partial x} + \frac{\partial^2 u_1}{\partial y^2} \\ 0 &= -\frac{\partial p_1}{\partial y} \end{cases}$$

Boundary conditions : **Bottom no slip**

$$0 = u(x, \alpha f_1) = u(x, 0) + \alpha f_1 \frac{\partial u}{\partial y}(x, 0) + O(\alpha^2)$$

Since $u = y + \alpha u_1$, $u(x, 0) = 0 + \alpha u_1(x, 0)$ and $\frac{\partial u}{\partial y}(x, 0) = 1 + \alpha \frac{\partial u_1}{\partial y}$

$$\Rightarrow u_1(x, 0) = -f_1(x, 0)$$

- └ Modelling

- └ the basal shear stress

Fourier transform w.r.t. x : $\widehat{\phi}(k, y) = \frac{1}{\sqrt{2\pi}} \int \phi(x, y) e^{-ikx} dx, \Rightarrow \partial_x \rightarrow x ik$

$$ik \widehat{u}_1 + \frac{\partial \widehat{v}_1}{\partial y} = 0 \quad (8)$$

$$ik y \widehat{u}_1 + \widehat{v}_1 = -ik \widehat{p}_1 + \frac{\partial^2 \widehat{u}_1}{\partial y^2} \quad (9)$$

$$0 = -\frac{\partial \widehat{p}_1}{\partial y} \quad (10)$$

Let the **shear stress**

$$\widehat{\tau}_1(k) = \frac{\partial \widehat{u}_1}{\partial y}(k, y)$$

Differentiate w.r.t. y horizontal momentum equation (9)

$$ik \widehat{u}_1 + ik y \widehat{\tau}_1 + \frac{\partial \widehat{v}_1}{\partial y} = -ik \frac{\partial \widehat{p}_1}{\partial y} + \frac{\partial^2 \widehat{u}_1}{\partial y^2}$$

With incompressibility (8) and hydrostatic pressure (10)

$$ik y \widehat{\tau}_1 = \frac{\partial^2 \widehat{\tau}_1}{\partial y^2} \quad (11)$$

Airy equation

$$\phi''(z) = z \phi(z)$$

Solution vanishing at $+\infty \propto Ai(z)$

Scaling property :

$$\frac{d^2\phi(\lambda y)}{dy^2} = \lambda^3 y \phi(\lambda y)$$

$$\widehat{\tau}_1(k, y) = C_k Ai((ik)^{1/3} y)$$

Integrate $\int_0^\infty \widehat{\tau}_1(k, y) dy = \widehat{u}_1(k, \infty) - \widehat{u}_1(k, 0)$ with matching condition
 $\widehat{u}_1(k, \infty) = 0$ and bottom b.c. $u_1(x, 0) = -f_1(x, 0)$ we get

$$\int_0^\infty \widehat{\tau}_1(k, y) dy = \widehat{f}_1(k)$$

Ask wolframalpha.com for

$$\int_0^\infty Ai(z) dz = 1/3 \Rightarrow \int_0^\infty C_k Ai((ik)^{1/3} y) dy = C_k \frac{ik^{-1/3}}{3}$$

Finally we get $C_k = 3(ik)^{1/3} \widehat{f}_1(k)$ and

$$\widehat{\tau}_1(k, y) = 3(ik)^{1/3} Ai((ik)^{1/3} y) \widehat{f}_1(k)$$

Back to Physical variables

Bottom shear stress

$$\widehat{\tau}_1(k, 0) = 3(i k)^{1/3} A i(0) \widehat{f}_1(k)$$

Ask again wolframalpha.com $A i(0) = \frac{1}{3^{2/3} \Gamma(2/3)}$

$$\widehat{\tau}_1(k, 0) = \frac{3^{1/3}}{\Gamma(2/3)} (i k)^{1/3} \widehat{f}_1(k)$$

Use the slope of the bump f'_1 instead of f_1

$$\widehat{\tau}_1(k) = \frac{3^{1/3}}{\Gamma(2/3)} (i k)^{-2/3} \widehat{f}'_1(k)$$

Since $\int_0^\infty x^{-1/3} e^{-ikx} = (i k)^{-2/3} \Gamma(2/3)$ we obtain

$$\tau_1(x, 0) = \frac{3^{1/3}}{\Gamma(2/3)^2} (H(x) x^{-1/3} * f'_1) = \frac{3^{1/3}}{\Gamma(2/3)^2} \int_0^\infty \frac{f'_1(x - \xi)}{\xi^{1/3}} d\xi$$

since $\bar{\tau} = 1 + \alpha \tau_1$,

$$\tau = U' \left(1 + \frac{3^{1/3}}{\Gamma(2/3)^2} \int_0^\infty \frac{f'(x - s)}{s^{1/3}} ds \right)$$

Outline

1 A nice and strange PDE for morphodynamics.

- Mathematical analysis of the model.
- Numerical simulations.

2 Where does the strange nonlocal term come from ?

- Did you say differintegral ?
- The basal shear stress