



# Introduction to Riemann surfaces, moduli spaces and its applications

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M2, Mathematical Physics

# Outline

## 1. Introduction to Moduli Spaces

### 1.1 Moduli of Lines

### 1.2 Line Bundles

## 2. Moduli space of curves

### 2.1 Riemann Surfaces

### 2.2 $g = 0$

### 2.3 $g = 1$

### 2.4 Higher genus

## Motivation

*Problem:*

Describe the collection of all lines in the real plane  $\mathbb{R}^2$  that pass through the origin.

## Motivation

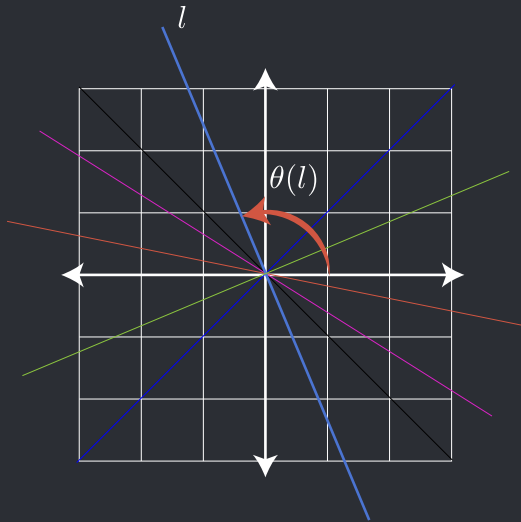
*Problem:*

Describe the collection of all lines in the real plane  $\mathbb{R}^2$  that pass through the origin.

A way to solve this is to assign to each line  $l$  a parameter

### Example

Define a function  $\theta(l)$  between  $l$  and the  $x$ -axis, so  $0 \leq \theta < \pi$ .



So the set of lines  $l$  or better known as  $\mathbb{RP}^1 = \{l \in \mathbb{R}^2 \mid 0 \in l\}$  is in one to one correspondence with the interval  $[0, \pi)$ .

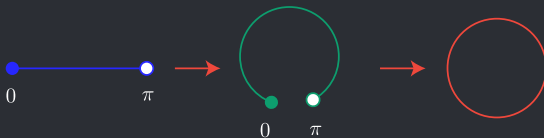
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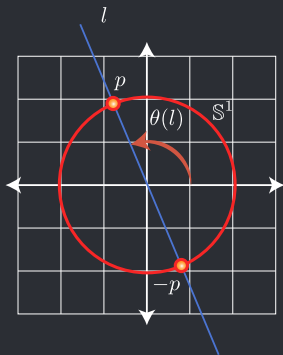
When we do this, we get a circle



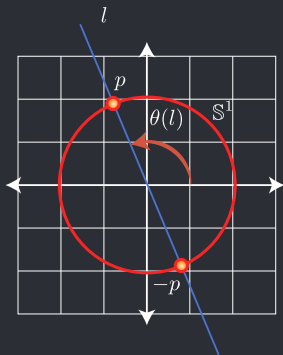


Another construction is to consider the unit circle  $\mathbb{S}^1 \subset \mathbb{R}^2$ , to each line we assign two points in  $\mathbb{S}^1$ .

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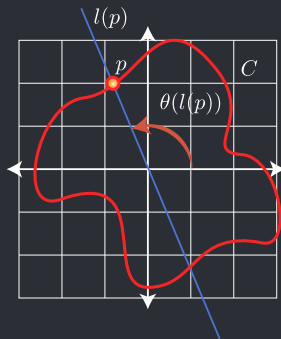
The advantage of this procedure is that we can endow  $\mathbb{RP}^1$  with a topology inherited of  $\mathbb{S}^1$ .

Now we are allowed to study continuous functions  $f : C \rightarrow \mathbb{R}P^1$  with  $C$  a topological space.

### Example

Let  $C \subset \mathbb{R}^2 \setminus \{0\}$  be a curve given by

$$\gamma : I \subset \mathbb{R} \rightarrow C$$



Because  $\gamma$  is continuous in  $\mathbb{R}^2$ ,  $l(c)$  is also a continuous function from

$$\begin{aligned}l &: C \rightarrow \mathbb{RP}^1 \\ c &\mapsto l(c)\end{aligned}$$

In the same way we can extend the notion of continuity for maps from  $\mathbb{R}^n$  to  $\mathbb{RP}^1$  by assigning to each  $x \in \mathbb{R}^n$ ,  $\theta(l(x)) \in \mathbb{RP}^1$ , in the case  $\theta(l) = 0$  or  $\pi$  we can use the angle  $\varphi$  from the vertical axis.

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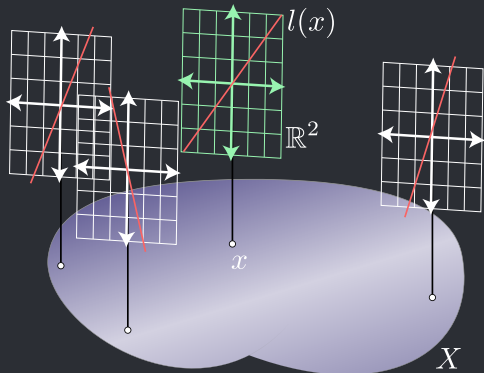
We say  $\mathbb{RP}^1$  is the **moduli space of lines** in  $\mathbb{R}^2$

## Line Bundles

Let  $X$  be a smooth manifold, for each  $x \in X$ , we assign a copy of  $\mathbb{R}^2$  so we can visualize  $l(x)$ . This is known as the **line bundle**.

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If  $X = \mathbb{R}P^1$ , we call this the **tautological line bundle**.

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- Family of lines in  $\mathbb{R}^2$  parametrized by a topological space  $X$
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- Line bundle on  $X$  contained in the trivial bundle  $X \times \mathbb{R}^2$

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## Moduli space of curves

*Problem* Classify compact Riemann surfaces

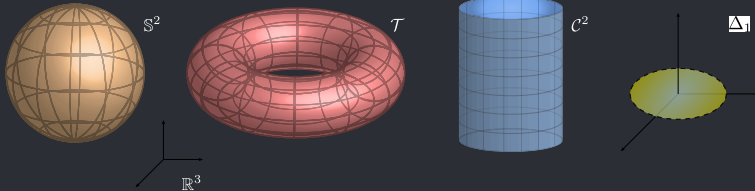
A geometric solution is Moduli spaces  $\mathcal{M}_g$

- Each point of  $\mathcal{M}_g$  is a Riemann surface
- Studying  $\mathcal{M}_g$  can tell us things of the geometry of the Riemann surfaces.

# Riemann Surfaces

A Riemann surface is a  $1_{\mathbb{C}}$ -dimensional manifold where the transition functions are holomorphic.

## Examples





- Classification of compact R.S. up to topological equivalence is given by the integer number  $g$  (genus), where  $g = 0$  corresponds to  $\mathbb{S}^2 \cong \mathbb{C}\mathbb{P}^1$ .
- Such Classification ignores the complex structure.
- Contrary to the genus (discrete), there are inequivalent R.S. that can be parametrized by continuous parameters.

$$g = 0$$

## Riemann Uniformization Theorem

Any simply connected R.S. is biholomorphic to either  $\mathbb{C}P^1$ ,  $\mathbb{C}$  or  $\mathbb{H}$ .

- Any compact R.S. with  $g = 0$  is simply connected, then by RUT, it can only be  $\mathbb{C}P^1$ .
- For this case the topological and holomorphic classifications agree.

$$g = 1$$

- Torus with one handle can be obtained by taking the quotient  $\mathbb{C}/(\mathbb{Z} \times \mathbb{Z})$
- Replace  $\mathbb{Z} \times \mathbb{Z}$  by a lattice  $L$ , and  $z \sim w$  if  $z - w \in L$ .
- A basis for  $L$  is a pair of numbers  $w_1, w_2 \in \mathbb{C}$ , such that  $\forall z \in L$ ,  $z = aw_1 + bw_2$  with  $a, b \in \mathbb{Z}$ .
- Any compact R.S with  $g = 1$  can be obtained as the quotient  $\mathbb{C}/L$ .
- The zero of  $\mathbb{C}$  is preserved by the quotient, such point is a marked point in the torus.

## Definition

An elliptic curve over  $C$  is a Riemann surface of genus one with a marked point.

- There is a one-to-one correspondence between elliptic curves and lattices.
- If  $L$  is a lattice  $\lambda L$  is also a lattice, also  $\mathbb{C}/L \cong \mathbb{C}/\lambda L$
- Given a lattice  $L$  and its oriented basis  $(w_1, w_2) = (1, \tau = \frac{w_2}{w_1})$ , where  $\tau \notin \mathbb{R}$ , this suggests  $\mathbb{H}$  is the parameter space.

Given two basis on  $\mathbb{H}$ , the change of basis is given by the matrix:

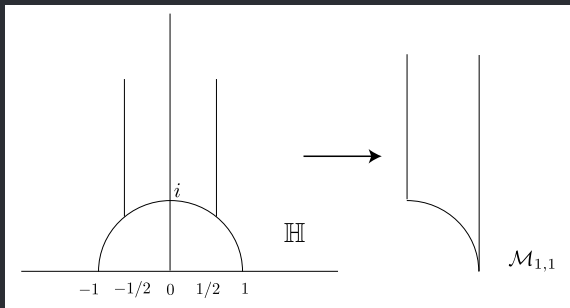
$$T = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad \text{where } a, b, c, d \in \mathbb{Z}$$

This is fact must be an element of  $PSL(2, \mathbb{R})$  as well, so:

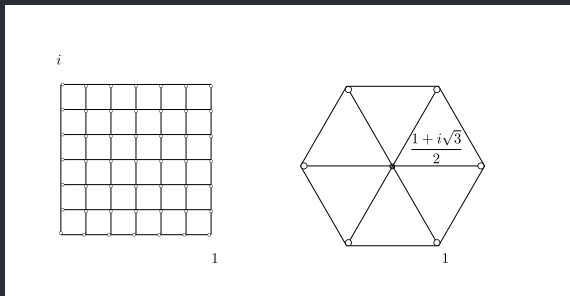
- Two points in  $\mathbb{H}$  correspond to the same elliptic curve if there exists an element  $T \in PSL(2, \mathbb{Z})$  that relates them.

Elliptic curves are in one-to-one correspondence with orbits of  $PSL(2, \mathbb{Z})$  in  $\mathbb{H}$ , i.e. elements of  $\mathbb{H}/PSL(2, \mathbb{Z})$

- However, NOT every continuous family of elliptic curves over a topological space  $X$  can be identified with a map from  $X$  to  $\mathcal{M}_{1,1}$
- There are two points in  $\mathbb{H}/PSL(2, \mathbb{Z})$  with additional symmetry.
- These two points have symmetries corresponding to the groups  $\mathbb{Z}/4\mathbb{Z}$  and  $\mathbb{Z}/6\mathbb{Z}$



To see this we note that one of the points correspond to the lattice  $(1, i)$ , this lattice is the same if we rotate it by  $\pi/2$  and  $\pi/6$  for the lattice  $(1, \frac{1+i\sqrt{3}}{2})$ , this means the automorphism group is discontinuous at these points.



Because of this "hidden" symmetry, we can no longer have the correspondence of maps from  $X$  to  $\mathcal{M}_{(1,1)}$ , because there will be more elliptic curves than maps in these points.

The structure that actually deals with this situations is called:  
**orbifold.**

Orbifolds can handle points with internal symmetries and therefore play an important role on the description of moduli spaces.



## Higher genus

- Any compact Riemann surface  $X$  of genus  $g > 1$  can be obtained as a quotient  $X = \mathbb{H}/\Gamma$ .
- $\Gamma$  is a representation of the fundamental group  $\pi_1(X)$  in  $PSL(2, \mathbb{R})$  with  $2g$  generators.

There is a one-to-one correspondence between holomorphic maps from a complex manifold  $Y$  to  $T_g$  and biholomorphism classes of marked Riemann surfaces of genus  $g$

- Unfortunately the Teichmüller space (space of parameters for the complex structure) associated to  $X$  might not have a complex structure.
- This is caused by the fact that  $\pi_1(X)$  is not abelian, therefore cannot be identified to the homology group  $H_1(X, \mathbb{Z})$
- Fortunately there is an "abelian" moduli, called: **Abelian varieties**, but such descriptions are quite complicated.

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