Application

#### Asymptotics of Cholesky GARCH Models and Time-Varying Conditional Betas

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Problem: Given some information set  $\mathcal{F}_{t-1}$ , it is often of interest to regress  $y_t$  on the components of  $\boldsymbol{x}_t$ .

Solution:  $y_t - E(y_t | \mathcal{F}_{t-1}) = \beta'_{yx,t} \{ x_t - E(x_t | \mathcal{F}_{t-1}) \} + \eta_t$ , with the dynamic conditional beta (DCB)  $\beta_{yx,t} = \sum_{xx,t}^{-1} \sum_{xy,t} \sum_{xy,t}$ . Practical implementation: An ARCH-type model for the

conditional variance  $\begin{pmatrix} \boldsymbol{\Sigma}_{\boldsymbol{x}\boldsymbol{x},t} & \boldsymbol{\Sigma}_{\boldsymbol{x}\boldsymbol{y},t} \\ \boldsymbol{\Sigma}_{\boldsymbol{y}\boldsymbol{x},t} & \boldsymbol{\Sigma}_{\boldsymbol{y}\boldsymbol{y},t} \end{pmatrix}$  of  $\epsilon_t = \begin{pmatrix} \boldsymbol{x}_t - E(\boldsymbol{x}_t \mid \mathcal{F}_{t-1}) \\ y_t - E(y_t \mid \mathcal{F}_{t-1}) \end{pmatrix}$  is needed.

A Cholesky GARCH model directly specifies the DCB.

## Notation

Let  $\epsilon_t = (\epsilon_{1t}, \dots, \epsilon_{mt})'$  be a vector of  $m \ge 2$  log-returns satisfying

$$\boldsymbol{\epsilon}_t = \boldsymbol{\Sigma}_t^{1/2}(\boldsymbol{\vartheta}_0)\boldsymbol{\eta}_t,$$

where  $(\eta_t)$  is *iid*  $(0, I_n)$ ,

$$\mathbf{\Sigma}_t = \mathbf{\Sigma}_t(\boldsymbol{\vartheta}_0) = \mathbf{\Sigma}(\boldsymbol{\epsilon}_{t-1}, \boldsymbol{\epsilon}_{t-2}, \dots; \boldsymbol{\vartheta}_0) > \mathbf{0},$$

and  $\vartheta_0$  is a  $d \times 1$  vector.

## DCC of Engle

$$\boldsymbol{\Sigma}_t = \boldsymbol{D}_t \boldsymbol{R}_t \boldsymbol{D}_t = \left( \rho_{ijt} \sqrt{\sigma_{iit} \sigma_{jjt}} \right),$$

where  $D_t = diag(\sigma_{11t}^{1/2}, \dots, \sigma_{mmt}^{1/2})$  contains the volatilities of the individual returns, and  $R_t = (\rho_{ijt})$  the conditional correlations.

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$$\boldsymbol{Q}_t = (1 - \theta_1 - \theta_2) \boldsymbol{S} + \theta_1 \boldsymbol{u}_{t-1} \boldsymbol{u}_{t-1}' + \theta_2 \boldsymbol{Q}_{t-1},$$

with 
$$\boldsymbol{u}_t = (u_{1t} \dots u_{mt})', u_{it} = \epsilon_{it}/\sqrt{\sigma_{iit}}, \theta_1 + \theta_2 < 1.$$

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Application

## Engle (2016) DCB

#### Assuming

$$\left(\begin{array}{c} \boldsymbol{x}_{t} \\ \boldsymbol{y}_{t} \end{array}\right) \mid \mathcal{F}_{t-1} \sim \mathcal{N} \left\{ \left(\begin{array}{c} \mu_{\boldsymbol{x}_{t}} \\ \mu_{\boldsymbol{y}_{t}} \end{array}\right), \left(\begin{array}{c} \boldsymbol{\Sigma}_{\boldsymbol{x}\boldsymbol{x},t} & \boldsymbol{\Sigma}_{\boldsymbol{x}\boldsymbol{y},t} \\ \boldsymbol{\Sigma}_{\boldsymbol{y}\boldsymbol{x},t} & \boldsymbol{\Sigma}_{\boldsymbol{y}\boldsymbol{y},t} \end{array}\right) \right\}$$

we have

$$\boldsymbol{y}_t \mid \boldsymbol{x}_t \sim \mathcal{N}\left(\boldsymbol{\mu}_{\boldsymbol{y}_t} + \boldsymbol{\Sigma}_{\boldsymbol{y}\boldsymbol{x},t} \boldsymbol{\Sigma}_{\boldsymbol{x}\boldsymbol{x},t}^{-1} (\boldsymbol{x}_t - \boldsymbol{\mu}_{\boldsymbol{x}_t}), \boldsymbol{\Sigma}_{\boldsymbol{y}\boldsymbol{y},t} - \boldsymbol{\Sigma}_{\boldsymbol{y}\boldsymbol{x},t} \boldsymbol{\Sigma}_{\boldsymbol{x}\boldsymbol{x},t}^{-1} \boldsymbol{\Sigma}_{\boldsymbol{x}\boldsymbol{y},t}\right)$$

 $\Rightarrow \beta_{yx,t} = \sum_{xx,t}^{-1} \sum_{xy,t} \text{ can be obtained by first estimating a DCC}$ GARCH model.

## Drawbacks of DCC-based DCB

- The stationarity and ergodicity conditions of the DCC are not weel known<sup>1</sup>.
- 2) The correlation constraints are complicated.
- 3) The asymptotic properties of the QMLE are unknown.
- 4) The effects of the DCC parameters on  $\beta_t$  are hardly interpretable.

We now introduce a class of Cholesky GARCH (CHAR) models that avoids all these drawbacks.

## Cholesky Decomposition of $\mathbf{\Sigma} = \text{Var}(\epsilon)$

Letting  $v_1 := \epsilon_1$ , we have

$$\epsilon_2 = \ell_{21} \mathbf{v}_1 + \mathbf{v}_2 = \beta_{21} \epsilon_1 + \mathbf{v}_2,$$

where  $\beta_{21} = \ell_{21}$  is the beta in the regression of  $\epsilon_2$  on  $\epsilon_1$ , and  $v_2$  is orthogonal to  $\epsilon_1$ . Recursively, we have

$$\epsilon_i = \sum_{j=1}^{i-1} \ell_{ij} \mathbf{v}_j + \mathbf{v}_i = \sum_{j=1}^{i-1} \beta_{ij} \epsilon_j + \mathbf{v}_i, \quad \text{ for } i = 2, \dots, m,$$

where  $v_i$  is uncorrelated to  $v_1, \ldots, v_{i-1}$ , and thus uncorrelated to  $\epsilon_1, \ldots, \epsilon_{i-1}$ .

## Cholesky Decomposition of $\boldsymbol{\Sigma} = \text{Var}(\epsilon)$

In matrix form,

$$\boldsymbol{\epsilon} = \boldsymbol{L} \boldsymbol{v}$$
 and  $\boldsymbol{B} \boldsymbol{\epsilon} = \boldsymbol{v},$ 

where *L* and  $B = L^{-1}$  are lower unitriangular and G := var(v) is triangular. We obtain the Cholesky decomposition

 $\Sigma = LGL'$ 

(see Pourahmadi, 1999).

## Example: $\Sigma = LGL'$ , m = 3

$$\boldsymbol{L} = \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix}, \quad \boldsymbol{B} = \begin{bmatrix} 1 & 0 & 0 \\ -\beta_{21} & 1 & 0 \\ -\beta_{31} & -\beta_{32} & 1 \end{bmatrix}, \quad \boldsymbol{G} = \begin{bmatrix} g_1 & 0 & 0 \\ 0 & g_2 & 0 \\ 0 & 0 & g_3 \end{bmatrix},$$

$$oldsymbol{\Sigma} = egin{bmatrix} g_1 & l_{21}g_1 & l_{31}g_1 \ l_{21}g_1 & l_{21}^2g_1 + g_2 & l_{21}l_{31}g_1 + l_{32}g_2 \ l_{31}g_1 & l_{21}l_{31}g_1 + l_{32}g_2 & l_{31}^2g_1 + l_{32}^2g_2 + g_3 \end{bmatrix}$$

Remark: In  $\Sigma = DRD$  the constraints on the elements of R are

$$\rho_{12}^2 + \rho_{13}^2 + \rho_{23}^2 - 2\rho_{12}\rho_{13}\rho_{23} \leq 1.$$

In  $\Sigma = LGL'$  there is no constraint on the  $\ell_{ij}$ 's.

## Sequential construction of $\Sigma_t = L_t G_t L'_t$

Let the factors  $\mathbf{v}_t = \mathbf{G}_t^{1/2} \boldsymbol{\eta}_t$ ,  $\boldsymbol{\eta}_t$  iid  $(0, \boldsymbol{I}_m)$  ( $v_{it} = \sqrt{g_{it}} \eta_{it}$ ). Taking  $\Sigma_t^{1/2} = L_t G_t^{1/2}$ , we have  $\epsilon_t = \Sigma_t^{1/2} \eta_t = L_t v_t$ . Step 1:  $V_{1t} = \epsilon_{1t}$  $q_{1t} = \text{Var}(v_{1t} | \mathcal{F}_{t-1})$ Step 2:  $\epsilon_{2t} = l_{21t} V_{1t} + V_{2t}$  $V_{2t} = \epsilon_{2t} - l_{21t} V_{1t}$  $q_{2t} = \text{Var}(v_{2t} | \mathcal{F}_{t-1})$ Step 3:  $\epsilon_{3t} = l_{31,t}v_{1t} + l_{32,t}v_{2t} + v_{3t}$  $V_{3t} = \epsilon_{3t} - l_{31} t V_{1t} - l_{32} t V_{2t}$  $g_{3,t} = \text{Var}(v_{3t} | \mathcal{F}_{t-1})$ 

## Alternative construction of $\Sigma_t^{-1} = B_t' G_t^{-1} B_t$

 $\epsilon_t = \mathbf{L}_t \mathbf{v}_t$  and therefore  $\mathbf{B}_t \epsilon_t = \mathbf{v}_t$ , where the subdiagonal elements of the lower unitriangular matrix  $\mathbf{B}_t = \mathbf{L}_t^{-1}$  are  $-\beta_{ij,t}$ Step 1:  $v_{1t} = \epsilon_{1t}$  $g_{1,t} = \operatorname{Var}(v_{1t} | \mathcal{F}_{t-1})$ 

Step 2: 
$$\epsilon_{2t} = \beta_{21,t}\epsilon_{1t} + V_{2t}$$
  
 $V_{2t} = \epsilon_{2t} - \beta_{21,t}\epsilon_{1t}$   
 $g_{2,t} = \operatorname{Var}(V_{2t} | \mathcal{F}_{t-1})$   
Step 3:  $\epsilon_{3t} = \beta_{31,t}\epsilon_{1t} + \beta_{32,t}\epsilon_{2t} + V_{3t}$   
 $V_{3t} = \epsilon_{3t} - \beta_{31,t}\epsilon_{1t} - \beta_{32,t}\epsilon_{2t}$   
 $g_{3,t} = \operatorname{Var}(V_{3t} | \mathcal{F}_{t-1})$ 

## The order of the series

Replace  $\epsilon_t = (\epsilon_{1t}, \epsilon_{2t}, \epsilon_{3t})'$  by  $\epsilon_t^* = (\epsilon_{2t}, \epsilon_{1t}, \epsilon_{3t})'$  (the position of

the last component is imposed by the problem)

Step 1\*: 
$$v_{1t}^* = \epsilon_{2t}, \quad g_{1,t}^* = \operatorname{Var}(v_{1t}^* \mid \mathcal{F}_{t-1})$$
  
Step 2\*:  $\epsilon_{1t} = \beta_{12,t}\epsilon_{2t} + v_{2t}^* \quad (v_{2t}^* \neq v_{2t})$   
 $g_{2,t}^* = \operatorname{Var}(v_{2t}^* \mid \mathcal{F}_{t-1})$   
Step 3\*:  $\epsilon_{3t} = \beta_{32,t}\epsilon_{2t} + \beta_{31,t}\epsilon_{1t} + v_{3t}^* \quad (v_{3t}^* = v_{3t})$   
 $g_{3,t}^* = \operatorname{Var}(v_{3t} \mid \mathcal{F}_{t-1})$ 

In particular,  $\beta_{12,t} = \beta_{21,t} \frac{g_{1t}}{\beta_{21,t}^2 g_{1t} + g_{2t}}$ : for most parametric specifications, the order matters.

## The order of the series (matrix form)

$$\boldsymbol{\Sigma}^{-1} = \begin{bmatrix} \boldsymbol{g}_{1}^{-1} + \beta_{21}^{2} \boldsymbol{g}_{2}^{-1} + \beta_{31,t}^{2} \boldsymbol{g}_{3,t}^{-1} & -\beta_{21} \boldsymbol{g}_{2}^{-1} + \beta_{31,t} \beta_{32,t} \boldsymbol{g}_{3,t}^{-1} & -\beta_{31,t} \boldsymbol{g}_{3,t}^{-1} \\ -\beta_{21} \boldsymbol{g}_{2}^{-1} + \beta_{31,t} \beta_{32,t} \boldsymbol{g}_{3,t}^{-1} & \beta_{32,t}^{2} \boldsymbol{g}_{3,t}^{-1} + \boldsymbol{g}_{2}^{-1} & -\beta_{32,t} \boldsymbol{g}_{3,t}^{-1} \\ -\beta_{31,t} \boldsymbol{g}_{3,t}^{-1} & -\beta_{32,t} \boldsymbol{g}_{3,t}^{-1} & \boldsymbol{g}_{3,t}^{-1} \end{bmatrix}.$$

$$\boldsymbol{\epsilon}_t^* = \Delta \boldsymbol{\epsilon}_t, \qquad \Delta \boldsymbol{\Sigma}^{*-1} \Delta =$$

$$\begin{bmatrix} \beta_{31,t}^2 g_{3,t}^{-1} + g_2^{*-1} & -\beta_{12} g_2^{*-1} + \beta_{31,t} \beta_{32,t} g_{3,t}^{-1} & -\beta_{31,t} g_{3,t}^{-1} \\ -\beta_{12} g_2^{*-1} + \beta_{31,t} \beta_{32,t} g_{3,t}^{-1} & g_1^{*-1} + \beta_{12}^2 g_2^{*-1} + \beta_{32,t}^2 g_{3,t}^{-1} & -\beta_{32,t} g_{3,t}^{-1} \\ -\beta_{31} g_{3,t}^{-1} & -\beta_{32,t} g_{3,t}^{-1} & g_{3,t}^{-1} \end{bmatrix}$$

We have  $\Delta \Sigma^{*-1} \Delta = \Sigma^{-1}$  when  $\beta_{12} = \beta_{21}g_1/(\beta_{21}^2g_1 + g_2), g_1^* = \beta_{21}^2g_1 + g_2$  and  $g_2^* = g_1 - \beta_{21}^2g_1^2/(\beta_{21}^2g_1 + g_2)$ When the first parameters are time-invariant, the order does not matter.

Application

## A general model for the factors

Assume

$$\boldsymbol{v}_t = \boldsymbol{G}_t^{1/2} \boldsymbol{\eta}_t, \qquad (\boldsymbol{\eta}_t) \text{ iid } (0, I_n),$$

where  $\boldsymbol{G}_t = \text{diag}(\boldsymbol{g}_t)$  follows a GJR-like equation

$$\boldsymbol{g}_{t} = \boldsymbol{\omega}_{0} + \sum_{i=1}^{q} \left\{ \boldsymbol{A}_{0i,+} \boldsymbol{v}_{t-i}^{2+} + \boldsymbol{A}_{0i,-} \boldsymbol{v}_{t-i}^{2-} \right\} + \sum_{j=1}^{p} \boldsymbol{B}_{0j} \boldsymbol{g}_{t-j},$$

with positive coefficients and

$$\mathbf{v}_{t}^{2+} = \left(\left\{\mathbf{v}_{1t}^{+}\right\}^{2}, \cdots, \left\{\mathbf{v}_{mt}^{+}\right\}^{2}\right)', \quad \mathbf{v}_{t}^{2-} = \left(\left\{\mathbf{v}_{1t}^{-}\right\}^{2}, \cdots, \left\{\mathbf{v}_{mt}^{-}\right\}^{2}\right)'.$$

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## Markovian representation of the factors

Letting 
$$\boldsymbol{z}_{t} = \left(\boldsymbol{v}_{t:(t-q+1)}^{2+\prime}, \boldsymbol{v}_{t:(t-q+1)}^{2-\prime}, \boldsymbol{g}_{t:(t-p+1)}^{\prime}\right)^{\prime}$$
,  
 $\boldsymbol{h}_{t} = \left(\omega_{0}^{\prime} \boldsymbol{\Upsilon}_{t}^{+\prime}, \mathbf{0}_{m(q-1)}^{\prime}, \omega_{0}^{\prime} \boldsymbol{\Upsilon}_{t}^{-\prime}, \mathbf{0}_{(q-1)m}^{\prime}, \omega_{0}^{\prime}, \mathbf{0}_{(p-1)m}^{\prime}\right)^{\prime}$ , with  
 $\boldsymbol{\Upsilon}_{t}^{+} = \operatorname{diag}\left(\eta_{t}^{2+}\right) \boldsymbol{\Upsilon}_{t}^{-} = \operatorname{diag}\left(\eta_{t}^{2-}\right)$  and obvious notations, we rewrite the model as

 $\boldsymbol{z}_t = \boldsymbol{h}_t + \boldsymbol{H}_t \boldsymbol{z}_{t-1},$ 

where, in the case p = q = 1,

$$\boldsymbol{H}_{t} = \begin{pmatrix} \boldsymbol{\Upsilon}_{t}^{+}\boldsymbol{A}_{01,+} & \boldsymbol{\Upsilon}_{t}^{+}\boldsymbol{A}_{01,-} & \boldsymbol{\Upsilon}_{t}^{+}\boldsymbol{B}_{01} \\ \boldsymbol{\Upsilon}_{t}^{-}\boldsymbol{A}_{01,+} & \boldsymbol{\Upsilon}_{t}^{-}\boldsymbol{A}_{01,-} & \boldsymbol{\Upsilon}_{t}^{-}\boldsymbol{B}_{01} \\ \boldsymbol{A}_{01,+} & \boldsymbol{A}_{01,-} & \boldsymbol{B}_{01} \end{pmatrix}$$

## Stationarity of the factors

In view of

$$\boldsymbol{z}_t = \boldsymbol{h}_t + \boldsymbol{H}_t \boldsymbol{z}_{t-1},$$

there exists a stationary and ergodic sequence ( $v_t$ ) satisfying  $v_t = G^{1/2} \eta_t$  if and only if

$$\gamma_0 = \inf_{t\geq 1} \frac{1}{t} E(\log \|\boldsymbol{H}_t \boldsymbol{H}_{t-1} \dots \boldsymbol{H}_1\|) < 0.$$

## Stationarity of $\beta_t := -\text{vech}^0 \boldsymbol{B}_t$

If ( $v_t$ ) is stationary and ergodic ( $\gamma_0 < 0$ ), and

$$\det\left\{\boldsymbol{I}_{m_0}-\sum_{i=1}^{\boldsymbol{s}}\boldsymbol{C}_{0i}\boldsymbol{z}^i\right\}\neq 0 \text{ for all } |\boldsymbol{z}|\leq 1,$$

then

$$\boldsymbol{\beta}_{t} = \boldsymbol{c}_{0}\left(\boldsymbol{v}_{t-1}, \ldots, \boldsymbol{v}_{t-r}, \boldsymbol{g}_{t-1}^{1/2}, \ldots, \boldsymbol{g}_{t-r}^{1/2}\right) + \sum_{j=1}^{s} \boldsymbol{C}_{0j} \boldsymbol{\beta}_{t-j}.$$

defines a stationary and ergodic sequence (and thus the existence of a stationary CHAR model).

## Existence of moments

If in addition

$$|\mathcal{E}||\eta_1||^{2k_1} < \infty$$
 and  $\varrho(\mathcal{EH}_1^{\otimes k_1}) < 1$ ,

for some integer  $k_1 > 0$ , and

$$\|\boldsymbol{c}_0(\boldsymbol{x}) - \boldsymbol{c}_0(\boldsymbol{y})\| \le K \|\boldsymbol{x} - \boldsymbol{y}\|^a$$

for some constants K > 0 and  $a \in (0, 1]$ , then the CHAR model satisfies  $E \|\epsilon_1\|^{2k_1} < \infty$ .

## A simpler parameterization

#### A tractable submodel is

$$g_{it} = \omega_{0i} + \gamma_{0i+} \left(\epsilon_{1,t-1}^{+}\right)^2 + \gamma_{0i-} \left(\epsilon_{1,t-1}^{-}\right)^2 + \sum_{k=2}^{i} \alpha_{0i}^{(k)} v_{k,t-1}^2 + b_{0i} g_{i,t-1}$$

with positivity coefficients, and

$$\beta_{ij,t} = \varpi_{0ij} + \varsigma_{0ij+} \epsilon_{1,t-1}^{+} + \varsigma_{0ij-} \epsilon_{1,t-1}^{-} + \sum_{k=2}^{i} \tau_{0ij}^{(k)} \mathbf{v}_{k,t-1} + \mathbf{c}_{0ij} \beta_{ij,t-1}$$

without positivity constraints. Notice the triangular structure and note that the asymmetry is introduced via the first (observed) factor only.

## Stationarity for the previous specification

There exists a strictly stationary, non anticipative and ergodic solution to the CHAR model when

1) 
$$E \log \left\{ \omega_{01} + \gamma_{01+} \left( \eta_{1,t-1}^+ \right)^2 + \gamma_{01-} \left( \eta_{1,t-1}^- \right)^2 + b_{01} \right\} < 0,$$
  
2)  $E \log \left\{ \alpha_{0i}^{(i)} \eta_{it}^2 + b_{0i} \right\} < 0$  for  $i = 2, \dots, m,$   
3)  $|c_{0ij}| < 1$  for all  $(i, j)$ .

Moreover, the stationary solution satisfies  $E \|\epsilon_1\|^{2s_0} < \infty$ ,  $E \|\boldsymbol{g}_1\|^{s_0} < \infty$ ,  $E \|\boldsymbol{v}_1\|^{s_0} < \infty$ ,  $E \|\boldsymbol{\beta}_1\|^{s_0} < \infty$  and  $E \|\boldsymbol{\Sigma}_1\|^{s_0} < \infty$ for some  $s_0 > 0$ .

Application

## Invertibility of the CHAR

Under the stationarity conditions

$$\boldsymbol{g}_t = \boldsymbol{g}(\boldsymbol{\eta}_u, u < t), \qquad \boldsymbol{\beta}_t = \boldsymbol{\beta}(\boldsymbol{\eta}_u, u < t).$$

For practical use, we need (uniform) invertibility:

$$\boldsymbol{g}_t(\vartheta) = \boldsymbol{g}(\vartheta; \boldsymbol{\epsilon}_u, u < t), \qquad \boldsymbol{\beta}_t(\vartheta) = \boldsymbol{\beta}(\vartheta; \boldsymbol{\epsilon}_u, u < t)$$

with some abuse of notation.

Application

## Invertibility of the CHAR

For practical use, we need uniform invertibility:

$$\boldsymbol{\beta}_t(\boldsymbol{\vartheta}) = \boldsymbol{\beta}(\boldsymbol{\vartheta}; \boldsymbol{\epsilon}_u, u < t).$$

More precisely, we need

$$\sup_{\boldsymbol{\vartheta}\in\Theta}\left\|\boldsymbol{\beta}_t(\boldsymbol{\vartheta})-\widetilde{\boldsymbol{\beta}}_t(\boldsymbol{\vartheta})\right\|\leq K\rho^t,$$

where  $\widetilde{\beta}_{t}(\vartheta) = \beta(\vartheta; \epsilon_{t-1}, \dots, \epsilon_{1}, \widetilde{\epsilon}_{0}, \widetilde{\epsilon}_{-1}, \dots)$  for fixed initial values  $\widetilde{\epsilon}_{0}, \widetilde{\epsilon}_{-1}, \dots$ , and  $\beta_{t}(\vartheta_{0}) = \beta_{t}$ .

## Invertibility conditions for the "triangular" model

In vector form, the model

$$\begin{split} \widetilde{\mathbf{v}}_{kt}(\boldsymbol{\vartheta}) &= \epsilon_{kt} - \sum_{j=1}^{k-1} \widetilde{\beta}_{kj,t}(\boldsymbol{\vartheta}) \epsilon_{jt}, \\ \widetilde{\beta}_{ij,t}(\boldsymbol{\vartheta}) &= \omega_{ij,t-1} + \sum_{k=2}^{i} \tau_{ij}^{(k)} \widetilde{\mathbf{v}}_{k,t-1}(\boldsymbol{\vartheta}) + \mathbf{c}_{ij} \widetilde{\beta}_{ij,t-1}(\boldsymbol{\vartheta}), \end{split}$$

with  $\omega_{ijt} = \varpi_{ij} + \varsigma_{ij+}\epsilon^+_{1t} + \varsigma_{ij-}\epsilon^-_{1t}$ , writes

$$\begin{split} \widetilde{\boldsymbol{\beta}}_{t}(\vartheta) = & \boldsymbol{w}_{t-1} + \boldsymbol{T}\widetilde{\boldsymbol{B}}_{t-1}(\vartheta)\boldsymbol{\epsilon}_{t-1} + \boldsymbol{C}\widetilde{\boldsymbol{\beta}}_{t-1}(\vartheta) \\ = & \boldsymbol{w}_{t-1} + \boldsymbol{T}\boldsymbol{\epsilon}_{t-1} + \Big\{ \boldsymbol{C} - (\boldsymbol{\epsilon}_{t-1}' \otimes \boldsymbol{T}) \mathbf{D}_{m}^{0} \Big\} \widetilde{\boldsymbol{\beta}}_{t-1}(\vartheta) \\ := & \boldsymbol{w}_{t-1}^{*} + \boldsymbol{S}_{t-1} \widetilde{\boldsymbol{\beta}}_{t-1}(\vartheta). \end{split}$$

## Invertibility conditions for the "triangular" model

By the Cauchy rule, the triangular model

$$\widetilde{\boldsymbol{\beta}}_t(\boldsymbol{\vartheta}) = \boldsymbol{w}_{t-1}^* + \boldsymbol{S}_{t-1}\widetilde{\boldsymbol{\beta}}_{t-1}(\boldsymbol{\vartheta}).$$

is uniformly invertible under the conditions

$$E \log^{+} \sup_{\vartheta \in \Theta} \|\boldsymbol{w}_{1} + \boldsymbol{T}\boldsymbol{\epsilon}_{1}\| < \infty,$$
$$\gamma_{S} := \limsup_{n \to \infty} \frac{1}{n} \log \sup_{\vartheta \in \Theta} \left\| \prod_{i=1}^{n} \boldsymbol{S}_{t-i} \right\| < 0.$$

## Full QMLE of the general CHAR

#### A QMLE of the CHAR parameter $\vartheta_0$ is

$$\widehat{\vartheta}_n = \operatorname*{arg\,min}_{\vartheta\in\Theta} \widetilde{O}_n(\vartheta), \qquad \widetilde{O}_n(\vartheta) = n^{-1} \sum_{t=1}^n \widetilde{q}_t(\vartheta),$$

where 
$$\widetilde{\boldsymbol{\Sigma}}_{t}(\boldsymbol{\vartheta}) = \boldsymbol{\Sigma} \left( \epsilon_{t-1}, \ldots, \epsilon_{1}, \widetilde{\epsilon}_{0}, \widetilde{\epsilon}_{-1}, \ldots; \boldsymbol{\vartheta} \right)$$
 and

$$\widetilde{q}_t(\vartheta) = \epsilon_t' \widetilde{\boldsymbol{B}}_t'(\vartheta) \widetilde{\boldsymbol{G}}_t^{-1}(\vartheta) \widetilde{\boldsymbol{B}}_t(\vartheta) \epsilon_t + \sum_{i=1}^m \log \widetilde{g}_{it}(\vartheta).$$

- Does not require matrix inversion.
- CAN under general regularity conditions.

$$g_{it}(\vartheta) = \omega_{i,t-1} + \sum_{k=2}^{i} \alpha_i^{(k)} v_{k,t-1}^2(\vartheta) + b_i g_{i,t-1}(\vartheta)$$
$$\beta_{ij,t}(\vartheta) = \omega_{ij,t-1} + \sum_{k=2}^{i} \tau_{ij}^{(k)} v_{k,t-1}(\vartheta) + c_{ij} \beta_{ij,t-1}(\vartheta)$$

are **B1**  $|c_{0ij}| < 1$  and other stationarity conditions.

$$g_{it}(\vartheta) = \omega_{i,t-1} + \sum_{k=2}^{i} \alpha_i^{(k)} v_{k,t-1}^2(\vartheta) + b_i g_{i,t-1}(\vartheta)$$
$$\beta_{ij,t}(\vartheta) = \omega_{ij,t-1} + \sum_{k=2}^{i} \tau_{ij}^{(k)} v_{k,t-1}(\vartheta) + c_{ij} \beta_{ij,t-1}(\vartheta)$$

#### are

**B2** For i = 2, ..., m, the distribution of  $\eta_{it}^2$  conditionally on  $\{\eta_{jt}, j \neq i\}$  is non-degenerate. The support of  $\eta_{1t}$  contains at least two positive points and two negative points.

$$g_{it}(\vartheta) = \omega_{i,t-1} + \sum_{k=2}^{i} \alpha_i^{(k)} v_{k,t-1}^2(\vartheta) + b_i g_{i,t-1}(\vartheta)$$
$$\beta_{ij,t}(\vartheta) = \omega_{ij,t-1} + \sum_{k=2}^{i} \tau_{ij}^{(k)} v_{k,t-1}(\vartheta) + c_{ij} \beta_{ij,t-1}(\vartheta)$$

are

**B3** Positivity conditions:  $\gamma_{i+}, \gamma_{i-}, \alpha_i^{(k)} \ge 0$  for all  $\vartheta, \omega_{0i} > 0$ ,  $|b_{0i}| < 1$  and  $|c_{0ij}| < 1$ .

$$g_{it}(\vartheta) = \omega_{i,t-1} + \sum_{k=2}^{i} \alpha_i^{(k)} v_{k,t-1}^2(\vartheta) + b_i g_{i,t-1}(\vartheta)$$
$$\beta_{ij,t}(\vartheta) = \omega_{ij,t-1} + \sum_{k=2}^{i} \tau_{ij}^{(k)} v_{k,t-1}(\vartheta) + c_{ij} \beta_{ij,t-1}(\vartheta)$$

#### are

**B4** Identifiability conditions:  $(\gamma_{0i+}, \gamma_{0i-}, \alpha_{0i}^{(2)}, \dots, \alpha_{0i}^{(i)}) \neq 0$  and  $(\varsigma_{0ij+}, \varsigma_{0ij-}, \tau_{0ij}^{(2)}, \dots, \tau_{0ij}^{(i)}) \neq 0$ .

$$g_{it}(\vartheta) = \omega_{i,t-1} + \sum_{k=2}^{i} \alpha_i^{(k)} v_{k,t-1}^2(\vartheta) + b_i g_{i,t-1}(\vartheta)$$
$$\beta_{ij,t}(\vartheta) = \omega_{ij,t-1} + \sum_{k=2}^{i} \tau_{ij}^{(k)} v_{k,t-1}(\vartheta) + c_{ij} \beta_{ij,t-1}(\vartheta)$$

are **B5** Uniform invertibility condition.

$$g_{it}(\vartheta) = \omega_{i,t-1} + \sum_{k=2}^{i} \alpha_i^{(k)} v_{k,t-1}^2(\vartheta) + b_i g_{i,t-1}(\vartheta)$$
$$\beta_{ij,t}(\vartheta) = \omega_{ij,t-1} + \sum_{k=2}^{i} \tau_{ij}^{(k)} v_{k,t-1}(\vartheta) + c_{ij} \beta_{ij,t-1}(\vartheta)$$

# are **B6** Moments conditions (larger than 6) on

$$\|\boldsymbol{\epsilon}_t\|, \quad \sup_{\boldsymbol{\vartheta}\in V(\boldsymbol{\vartheta}_0)} \|\boldsymbol{\beta}_t(\boldsymbol{\vartheta})\|, \quad \sup_{\boldsymbol{\vartheta}\in V(\boldsymbol{\vartheta}_0)} \left\| \frac{\partial \boldsymbol{\beta}_t(\boldsymbol{\vartheta})}{\partial \boldsymbol{\vartheta}'} \right\|.$$

## Equation-by-Equation (EbE) estimator

Consider the triangular model. In a first step, the parameter  $\vartheta_0^{(1)} = (\omega_{01}, \gamma_{01+}, \gamma_{01-}, b_{01})$  is estimated by

$$\widehat{\vartheta}_n^{(1)} = \operatorname*{arg\,min}_{\vartheta^{(1)} \in \Theta^{(1)}} \sum_{t=1}^n \widetilde{q}_{1t}(\vartheta^{(1)}),$$

where

$$\widetilde{q}_{1t}(\vartheta^{(1)}) = \frac{\epsilon_{1t}^2}{\widetilde{g}_{1t}(\vartheta^{(1)})} + \log \widetilde{g}_{1t}(\vartheta^{(1)}),$$

and  $\widetilde{g}_{1t}(\vartheta^{(1)}) = \omega_1 + \gamma_{1+} \left(\epsilon_{1t}^+\right)^2 + \gamma_{1-} \left(\epsilon_{1t}^-\right)^2 + b_1 \widetilde{g}_{1,t-1}(\vartheta^{(1)}).$ 

## EbE second step

Let  $\vartheta_0^{(2)} = (\varphi_0^{(2)}, \theta_0^{(2)})$ , where  $\tilde{\beta}_{21,t} = \tilde{\beta}_{21,t}(\varphi_0^{(2)})$  and  $\tilde{g}_{2t} = \tilde{g}_{2t}(\theta_0^{(2)})$ . Independently or in parallel to  $\vartheta_0^{(1)}$ , one can estimate  $\vartheta_0^{(2)}$  by

$$\widehat{\vartheta}_n^{(2)} = \operatorname*{arg\,min}_{\vartheta^{(2)} \in \Theta^{(2)}} \sum_{t=1}^n \widetilde{q}_{2t}(\vartheta^{(2)}),$$

where, for t = 1, ..., n,

$$\begin{split} \widetilde{q}_{2t}(\vartheta^{(2)}) &= \frac{\widetilde{V}_{2t}^{2}(\varphi^{(2)})}{\widetilde{g}_{2t}(\vartheta^{(2)})} + \log \widetilde{g}_{2t}(\vartheta^{(2)}), \\ \widetilde{g}_{2t}(\vartheta^{(2)}) &= \omega_{2,t-1} + \alpha_{2}^{(2)}\widetilde{V}_{2,t-1}^{2}(\varphi^{(2)}) + b_{2}\widetilde{g}_{2,t-1}(\varphi^{(2)}), \\ \widetilde{V}_{2t}(\varphi^{(2)}) &= \epsilon_{2t} - \widetilde{\beta}_{21,t}(\varphi^{(2)})\epsilon_{1t}, \\ \widetilde{\beta}_{21,t}(\varphi^{(2)}) &= \omega_{21,t-1} + \tau_{21}^{(2)}\widetilde{V}_{2,t-1}(\varphi^{(2)}) + c_{21}\widetilde{\beta}_{21,t-1}(\varphi^{(2)}). \end{split}$$

## EbE remaining steps

For  $i \ge 3$ ,  $\tilde{\beta}_{ij,t}$  depends on  $\varphi_0^{(+i)} = \left(\varphi_0^{(i)}, \varphi_0^{(-i)}\right)$ , where  $\varphi_0^{(-i)}$  has been estimated in the previous steps. The volatility  $\tilde{g}_{2t}$  depends on  $\vartheta_0^{(+i)} = (\theta_0^{(i)}, \varphi_0^{(+i)})$ , and  $\vartheta_0^{(i)} = (\theta_0^{(i)}, \varphi_0^{(i)})$  can be estimated by

$$\begin{split} \widehat{\vartheta}_{n}^{(i)} &= \underset{\vartheta^{(i)} \in \Theta^{(i)}}{\arg\min} \sum_{t=1}^{n} \widetilde{q}_{it}(\vartheta^{(i)}, \widehat{\varphi}_{n}^{(-i)}), \quad \widetilde{q}_{it}(\vartheta^{(+i)}) = \frac{\widetilde{V}_{it}^{2}(\varphi^{(+i)})}{\widetilde{g}_{it}(\vartheta^{(+i)})} + \log \widetilde{g}_{it}(\vartheta^{(+i)}), \\ \widetilde{g}_{it}(\vartheta^{(+i)}) &= \omega_{i,t-1} + \sum_{k=2}^{i} \alpha_{i}^{(k)} \widetilde{v}_{k,t-1}^{2}(\varphi^{(+k)}) + b_{i} \widetilde{g}_{i,t-1}(\vartheta^{(+i)}), \\ \widetilde{v}_{kt}(\varphi^{(+k)}) &= \epsilon_{kt} - \sum_{j=1}^{k-1} \widetilde{\beta}_{kj,t}(\varphi^{(+k)}) \epsilon_{jt}, \\ \widetilde{\beta}_{ij,t}(\varphi^{(+i)}) &= \omega_{ij,t-1} + \sum_{k=2}^{i} \tau_{ij}^{(k)} \widetilde{v}_{k,t-1}(\varphi^{(+k)}) + c_{ij} \widetilde{\beta}_{ij,t-1}(\varphi^{(+i)}), \end{split}$$

## QML vs. EbE

- 1) If m = 2, the one-step full QMLE and the two-step EbEE are exactly the same.
- 2) For  $m \ge 3$ , the two estimators are generally different.
- The QML and EbE estimators are CAN under similar assumptions
- The EbEE is simpler, but is not always less efficient than the full QMLE.

We illustrate the last point on a simplistic example.

## Example

Consider a static model with  $g_{it} = 1$  for  $i \in \{1, 2, 3\}$ .

$$\epsilon_{1t} = \mathbf{v}_{1t}$$
  

$$\epsilon_{2t} = \mathbf{l}_{21}\mathbf{v}_{1t} + \mathbf{v}_{2t}$$
  

$$\epsilon_{3t} = \underbrace{\mathbf{l}_{31}}_{0}\mathbf{v}_{1t} + \mathbf{l}_{32}\mathbf{v}_{2t} + \mathbf{v}_{3t} = \mathbf{l}_{32}\mathbf{v}_{2t} + \mathbf{v}_{3t}$$

In terms of  $\beta$ 's:

$$\epsilon_{2t} = \beta_{21}\epsilon_{1t} + \mathbf{v}_{2t}$$
  

$$\epsilon_{3t} = \underbrace{-\beta_{21}\beta_{32}}_{\beta_{31}}\epsilon_{1t} + \beta_{32}\epsilon_{2t} + \mathbf{v}_{3t}$$

 $\rightarrow \boldsymbol{\vartheta} = (\beta_{21}, \beta_{32})$ 

## Example

Assume for instance that the variable  $v_{2t}$  is independent of the vector  $(v_{1t}, v_{3t})'$  and that this vector is distributed as the product  $\eta \boldsymbol{u}$ , where the random variable  $\eta$  and the vector  $\boldsymbol{u}$  are independent, e.g.,  $\boldsymbol{u} \sim \mathcal{N}(\mathbf{0}, \boldsymbol{I}_2)$  and  $\eta \sim \sqrt{(\nu - 2)/\nu} St_{\nu}$ ,  $\nu > 4$ .

QMLE: 
$$\sqrt{n} \left( \widehat{\vartheta}_n - \vartheta_0 \right) \xrightarrow{\mathcal{L}} \mathcal{N} \left\{ 0, \begin{pmatrix} \frac{1 + \beta_{32}^2 E \eta^4}{(1 + \beta_{32}^2)^2} & 0 \\ 0 & E \eta^4 \end{pmatrix} \right\}.$$

$$\mathsf{EbEE:} \sqrt{n} \left( \widehat{\beta}_{21} - \beta_{0,21} \right) = \frac{n^{-1/2} \sum_{t=1}^{n} \eta_{2t} \epsilon_{1t}}{n^{-1} \sum_{t=1}^{n} \epsilon_{1t}^2} \xrightarrow{\mathcal{L}} \mathcal{N} \left( \mathbf{0}, \mathbf{1} \right).$$

#### Illustration



Figure: Ratio between the asymptotic variance of the QML estimator of  $\beta_{21}$  and its EbE counterpart as a function of the degree of freedom  $\nu$  and  $\beta_{32}$ .

Application

### Illustration



Application

## Data Generating process

$$\begin{aligned} \epsilon_t &= \Sigma_t^{1/2}(\vartheta_0)\eta_t, \\ \Sigma_t &= L_t G_t L'_t, \\ g_{i,t} &= 0.1 + 0.1 v_{i,t-1}^2 + 0.8 g_{i,t-1}, \\ \beta_{ij,t} &= 0.1 + 0.2 v_{i,t-1} + 0.8 \beta_{ij,t-1}, \end{aligned}$$

where  $(\eta_t)$  is iid  $\mathcal{N}(0, I_m)$ ,  $t = 1, \ldots, n$ .

## Results for m = 5, $\eta \sim \mathcal{N}(0, I_m)$ , 1000 replications

	FULL QML				EbE			
	BIAS	RMSE-STD	5% CP	95% CP	BIAS	RMSE-STD	5% CP	95% CP
n=1000								
ω	0.0202	0.0158	4.444	91.695	0.0190	0.0100	4.070	92.251
$\alpha$	0.0037	0.0024	4.018	91.111	0.0036	-0.0004	3.659	91.696
$\beta$	-0.0245	0.0178	7.834	94.007	-0.0230	0.0092	7.379	94.347
ω	0.0008	0.0011	5.769	91.538	0.0007	0.0001	4.604	92.559
au	0.0012	0.0011	7.306	93.939	0.0011	-0.0001	6.208	94.779
С	-0.0017	0.0022	8.115	93.805	-0.0016	0.0003	7.009	94.913
ALL	0.0000	0.0050	6.520	92.820	0.0000	0.0021	5.639	93.644
n=2000								
ω	0.0098	0.0014	3.824	92.745	0.0087	0.0000	3.305	93.138
$\alpha$	0.0019	0.0014	4.412	92.966	0.0017	-0.0004	3.766	93.410
$\beta$	-0.0119	0.0034	6.642	94.804	-0.0104	-0.0006	6.130	95.460
ω	0.0002	-0.0009	6.483	91.324	0.0002	-0.0003	4.550	93.410
au	0.0003	0.0001	7.145	93.493	0.0004	-0.0002	5.690	94.812
с	-0.0005	-0.0014	8.039	94.069	-0.0004	-0.0006	6.266	95.690
ALL	0.0000	0.0002	6.468	93.143	0.0000	-0.0004	5.135	94.426

$$g_{i,t} = \omega_i + \alpha_i v_{i,t-1}^2 + \beta_i g_{i,t-1} \text{ and } \beta_{ij,t} = \varpi_{ij} + \tau_{ij} v_{i,t-1} + c_{ij} \beta_{ij,t-1}$$

## Results for m = 5, $\eta_i \sim t(0, 1, 7)$ , 1000 replications

	FULL QML				EbE			
	BIAS	RMSE-STD	5% CP	95% CP	BIAS	RMSE-STD	5% CP	95% CP
n=1000								
ω	0.0236	0.0153	4.468	89.811	0.0225	0.0050	4.227	90.284
$\alpha$	0.0056	0.0015	2.931	89.362	0.0057	-0.0066	2.860	90.074
$\beta$	-0.0309	0.0181	9.409	92.719	-0.0293	-0.0013	8.980	93.270
ω	0.0010	-0.0002	5.922	91.052	0.0010	-0.0014	4.532	92.650
au	0.0014	-0.0013	7.080	94.173	0.0012	-0.0016	5.910	95.152
С	-0.0019	0.0005	8.818	93.995	-0.0018	-0.0024	7.308	95.226
ALL	-0.0001	0.0037	6.717	92.259	-0.0001	-0.0015	5.730	93.298
n=2000								
ω	0.0062	0.0018	3.624	92.584	0.0093	0.0005	3.141	91.734
$\alpha$	0.0009	0.0007	3.490	91.678	0.0020	-0.0017	2.748	91.189
$\beta$	-0.0079	0.0025	7.282	94.899	-0.0120	-0.0006	7.546	94.984
ω	0.0002	0.0001	8.188	90.336	0.0003	-0.0004	4.308	94.079
au	0.0002	0.0002	7.953	92.953	0.0005	-0.0006	4.984	95.507
с	-0.0004	0.0001	9.463	91.695	-0.0007	-0.0008	5.965	95.725
ALL	-0.0001	0.0006	7.289	92.125	0.0000	-0.0006	4.883	94.281

$$g_{i,t} = \omega_i + \alpha_i v_{i,t-1}^2 + \beta_i g_{i,t-1} \text{ and } \beta_{ij,t} = \varpi_{ij} + \tau_{ij} v_{i,t-1} + c_{ij} \beta_{ij,t-1}$$

## Results for m = 10, n = 4000 and 1000 replications

# Summary statistics on the 165 parametersMean biais-0.000873171Mean (rmse-Mean STD)0.00155948Mean Coverage Prob 5%5.042389091Mean Coverage Prob 95%93.6329697

## Asset Pricing for Industry Portfolios

We consider the 12 industry portfolios used by Engle (2016), examined in the context of the Fama French 3 factor model.

The three factors are: *MKT* (Market factor = excess log-returns of the SP500), *SMB* (small minus big size factor) and *HML* (high minus low value factor)

Data are from Ken French's web site and cover the period 1994-2016.

We follow Patton and Verardo (2012) in building hedged portfolios to offset some unwanted exposures to predetermined factors.

## Competing models

Let  $\epsilon_t = (\mathbf{x}'_t, y_t)'$  with  $\mathbf{x}_t = (MKT_t, SMB_t, HML_t)'$  and  $y_t = r_{kt}$ . Hedging strategy:

$$E_{t-1}(r_{kt} \mid \boldsymbol{x}_t) = \beta_{k,MKT,t}MKT_t + \beta_{k,SMB,t}SMB_t + \beta_{k,HML,t}HML_t.$$

Competing models:

- 1) CCC-GARCH(1,1)
- 2) DCC-GARCH(1,1)
- 3) CHAR with constant betas
- 4) CHAR with time varying betas  $\beta_{ij,t} = \varpi_{ij} + \tau_{ij} v_{i,t-1} v_{j,t-1} + c_{ij} \beta_{ij,t-1}$

## Buseq: Business Equipment – Computers, Software, and Electronic Equipment



## Buseq: One-step ahead forecasts



# Robust (HAC) t-statistic of the regression of the tracking errors on a constant

	C-CHAR	CHAR	CCC	DCC	
BusEq	-1.025	-0.442	0.133	-0.889	
Chems	0.683	0.150	1.187	0.252	
Durbl	-0.059	-0.402	-0.123	-0.720	
Enrgy	-1.191	-1.865	-0.528	-1.665	
Hlth	1.664	1.123	1.777	1.325	
Manuf	-0.101	-0.269	0.064	-0.197	
Money	-0.699	-0.648	-0.837	-0.541	
NoDur	2.731	2.180	2.961	2.343	
Other	-0.193	-0.436	-0.394	-0.415	
Shops	1.746	1.947	2.447	1.768	
Telcm	1.392	1.604	2.247	1.858	
Utils	1.053	0.858	1.549	1.010	

Note: Robust (HAC) t-statistics for the null hypothesis that the coefficient in the regression of  $TE_{k,t+1}$  on a constant is zero. Values in bold are greater (in absolute value) than the critical value at the 5% significance level.

## Results of the MCS test – MSE loss function

	C-CHAR	CHAR	CCC	DCC	
BusEq		$\checkmark$			
Chems		$\checkmark$			
Durbl		$\checkmark$			
Enrgy		$\checkmark$		$\checkmark$	
Hlth		$\checkmark$		$\checkmark$	
Manuf		$\checkmark$			
Money		$\checkmark$		$\checkmark$	
NoDur		$\checkmark$			
Other		$\checkmark$			
Shops		$\checkmark$			
Telcm		$\checkmark$			
Utils		$\checkmark$			

Models included in the MCS in the beta hedging exercise. Models highlighted with the symbol  $\checkmark$  are contained in the model confidence set using a MSE loss function. The significance level for the MCS is set to 20%, and 10,000 bootstrap samples (with a block length of 5 observations).

# Transaction costs : $\frac{\Delta\beta_{CHAR}}{\Delta\beta_{DCC-DCB}}$

	MKT	SMB	HML	
BusEq	0.356	0.380	0.341	
Chems	0.310	0.263	0.376	
Durbl	0.419	0.464	0.693	
Enrgy	0.373	0.337	0.456	
Hlth	0.461	0.667	0.397	
Manuf	0.442	0.402	0.430	
Money	0.390	0.397	0.366	
NoDur	0.414	0.383	0.296	
Other	0.273	0.343	0.335	
Shops	0.344	0.297	0.395	
Telcm	0.334	0.414	0.640	
Utils	0.465	0.408	0.431	

 $\begin{array}{l} \Delta_{\beta_{k,j}} = \sum_{t=2}^{1.678} |\beta_{k,j,t+1|t} - \beta_{k,j,t|t-1}|.\\ \text{For each column, the figures correspond to the ratio between the value of } \Delta_{\beta_{k,j}} \text{ obtained for the CHAR and the DCC-DCB models.} \end{array}$ 

## Conclusion

Compare to other multivariate GARCH (in particular BEKK and DCC), the Cholesky-GARCH models introduced here have several advantages.

- 1) Precise stationarity and moment conditions exist.
- 2) The parameters are directly interpretable in terms of DCB.
- 3) There is no complicated correlation constraint.
- 4) The estimation can be done without matrix invertion.
- 5) The asymptotic theory of the QMLE is available.
- 6) EbE estimation is possible for triangular models.
- The model works nicely in practice, in particular for beta hedging.

## Conclusion

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- The model works nicely in practice, in particular for beta hedging.

#### Thanks for your attention!

## CAN of the EbE estimator

Theorem (CAN of the EbEE)  
Under B1-B5 the EbEE 
$$\widehat{\vartheta}_n = \left(\widehat{\vartheta}_n^{(1)'}, \dots, \widehat{\vartheta}_n^{(m)'}\right)'$$
 satisfies

 $\widehat{\boldsymbol{\vartheta}}_n \rightarrow \boldsymbol{\vartheta}_0, \quad \text{almost surely as } n \rightarrow \infty.$ 

Under the additional assumption **B6**, as  $n \rightarrow \infty$ ,

$$\sqrt{n}\left(\widehat{\boldsymbol{\vartheta}}_{n}^{(i)}-\boldsymbol{\vartheta}_{0}^{(i)}\right) \quad \stackrel{\mathcal{L}}{\rightarrow} \mathcal{N} \quad \left\{0,\boldsymbol{\Sigma}^{(i)}:=\left(\boldsymbol{J}^{(i)}\right)^{-1}\boldsymbol{J}^{(i)}\left(\boldsymbol{J}^{(i)}\right)^{-1}\right\}$$

for i = 1 and i = 2.

$$\boldsymbol{J}_{n}^{(i)} = \frac{\partial^{2} \widetilde{O}_{n}^{(i)}(\widehat{\vartheta}_{n}^{(+i)})}{\partial \vartheta^{(i)} \partial \vartheta^{(i)}}, \qquad \boldsymbol{I}_{n}^{(i)} = \frac{1}{n} \sum_{t=1}^{n} \frac{\partial \widetilde{q}_{it}(\widehat{\vartheta}_{n}^{(+i)})}{\partial \vartheta^{(i)}} \frac{\partial \widetilde{q}_{it}(\widehat{\vartheta}_{n}^{(+i)})}{\partial \vartheta^{(i)'}}$$

## CAN of the EbE estimator

$$\beta_{32,t} = \varpi_{032} + \ldots + \tau_{032}^{(2)} v_{2,t-1} + c_{032} \beta_{32,t-1}$$
, where  $v_{2,t-1} = \varepsilon_{2,t-1} - \beta_{21,t-1} \varepsilon_{1,t-1}$ .

Theorem (CAN of the EbEE) Denoting by  $\Sigma_{\varphi^{-}}^{(+i)}$  (or by  $\Sigma_{\varphi^{+}}^{(+(i-1))}$ ) the bottom-right sub-matrix of  $\Sigma^{(+i)}$  (or of  $\Sigma^{(+(i-1))}$ ) corresponding to the asymptotic variance of  $\widehat{\varphi}_{n}^{(-i)}$  (which is equal to  $\widehat{\varphi}_{n}^{(+(i-1))}$ ), and using the convention  $\Sigma^{(+2)} = \Sigma^{(2)}$ , for i = 3, ..., m we also have

$$\sqrt{n}\left(\widehat{\boldsymbol{\vartheta}}_{n}^{(+i)}-\boldsymbol{\vartheta}_{0}^{(+i)}
ight) \quad \stackrel{\mathcal{L}}{\rightarrow} \mathcal{N} \quad \left(\mathbf{0}, \boldsymbol{\Sigma}^{(+i)}
ight)$$

with

$$\boldsymbol{\Sigma}^{(+i)} = \begin{pmatrix} \boldsymbol{\Sigma}_{\boldsymbol{\vartheta}}^{(i)} & -\left(\boldsymbol{J}^{(i)}\right)^{-1} \boldsymbol{K}^{(i)} \boldsymbol{\Sigma}_{\boldsymbol{\varphi}^+}^{(+(i-1))} \\ -\left(\boldsymbol{J}^{(i)'}\right)^{-1} \boldsymbol{K}^{(i)'} \boldsymbol{\Sigma}_{\boldsymbol{\varphi}^+}^{(+(i-1))} & \boldsymbol{\Sigma}_{\boldsymbol{\varphi}^+}^{(+(i-1))} \end{pmatrix}$$

where  $\mathbf{\Sigma}_{\boldsymbol{\vartheta}}^{(i)} = \left(\mathbf{J}^{(i)}\right)^{-1} \left\{ \mathbf{I}^{(i)} + \mathbf{K}^{(i)} \mathbf{\Sigma}_{\boldsymbol{\varphi}^+}^{(+(i-1))} \mathbf{K}^{(i)'} \right\} \left(\mathbf{J}^{(i)}\right)^{-1} \text{ and } \mathbf{K}_n^{(i)} = \frac{\partial^2 \tilde{\mathcal{O}}_n^{(i)} (\hat{\boldsymbol{\vartheta}}_n^{(+i)})}{\partial \boldsymbol{\vartheta}^{(i)} \partial \boldsymbol{\varphi}^{(-i)'}}$ 

